Commenter Identification Fields					Comment Description Fields							ICC Disposition Fields			Commenter Concurrence Fields		ICC Concurrence Fields			
(1) COMMENT NO.	T (2) ENTITY	(4) COMMENTER NAME	(5) PHONE #	(6) EMAIL	(7) DOC LINE# (if applicable)	(8) PARA #	(9) COMMENT TYPE (C/S/A)	(10) COMMENT	(11) ORIGINAL TEXT (FROM)	(12) SUGGESTED CHANGE ( TO )	(13) RATIONALE FOR CHANGE	(20) DISPOSITION - Accept, Accept with Comment, Reject, or Defer	(21) DISPOSITION RATIONAL	(22) FINAL CHANGED TEXT (if not identical to suggested text or no suggestion offered)	(23) COMMENTER CONCURRENCE (Concur or Non Concur)	(24) NON CONCURRENCE RATIONAL (if applicable)	(25) CONCURRENCE METHOD (email, phone, mtg)	(26) DATE CONCURRENCE RECEIVED (mm/dd/yy)	(27) FINAL COMMENT STATUS (Open/Closed)	(28) NOTES
1	Collins Aerospace	Roger Kirpes 3	19-295-4663	roger.kirpes@collins.com	IS-GPS-200K	20.3.3.3.1.7	S - Substantive	The interpretation of a T <sub>6D</sub> value of '1000000000000, for CNAV/CNAV-2 data, and '10000000' for LNAV data, is inconsistent. With respect to CNAV/CNAV-2 data, this value is defined as indicating that the group delay value is not available. However, with respect to LNAV data, no such clarification is provided.	[IS-GPS-200 30.3.3.3.1.1] The bit string of "100000000000" shall indicate that the group delay value is not available	Add clarification to IS-GPS-200 that a $T_{\rm GO}$ value of '10000000' in LNAV Subframe 1 indicates that the group delay value is not available.			Discuss at PICWG							
2	Thales	D. Bouvet		denis.bouvet@fr.thal esgroup.com	RFC_395	20.3.3.4.3.2	S - Substantive	Replacement in Table 20-IV of Kepler's equation for eccentric anomaly by a 3-step iterative algorithm schuld be re-considered, as it can imply that the control segment computes and broadcasts URA. and provides performance ommitments based on the assumption that all the GPS equipment apply this algorithm. This is not backward compatible with all the equipment produced so far. The algorithm solving Kepler's equation can be designed and adapted for specific applications by each manufacturer. Consider maintaining Table 20-IV as it was. Possilly add a note below the table describing a possible (but not unique) implementation to solve Kepler's equation.				Accept with Comments	The equations in the document state that they are optional to the users. Section 20.3.4.3 User Algorithm for Ephemeris Determination states that the equations are optional. Control Segment does not use these equations The purpose of the change is to allow for easier implementation for new users. Old users do not have to revert to these equations. In fact, kil users can still use their old equations with no additional effect.							
3					RFC_395	20.3.3.4.3.2	S - Substantive	Introduction of the satellite velocity and acceleration equation tables should be re-considered. GPS control segment may assume that it is only when the GPS equipment applies this new set of equations that the performance (for velocity and acceleration) defined in the SPS PS is met. Consider providing these equations as a possible algorithm, and clarifying that alternatives are acceptable.				Accept with Comments	A statement was added along with the equations stating that these equations are optional. They are there for easier implementation for new users. They are not required to be used by the CS or UE.							
4		Frank Czopeck				15200, 15705, 15800	A - Administrative	[Deferred from RFC-400 Leap Second and Earth Orientation Parameters] Please note the separation between "DIRECTION OF FLOW FROM SV" and "MSB FIRST." To me it book like we are calling out two separate fields but in reality we are informing the reader the direction of data being sent and what bit is sent first. So I would like to see "DIRECTION OF FLOW FROM SV (MSB FIRST)" replace the header on the line.				Reject	There are 58 figures which would have to be updated – some figures are pictures and would need to be re- drawn. Users have not otherwise had problems interpreting/understanding interpreting/understanding the figures. The main ideas are to convey the direction of data flow, and that the MSB comes first – which may easily be interpreted from the current figures. See below.							
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