



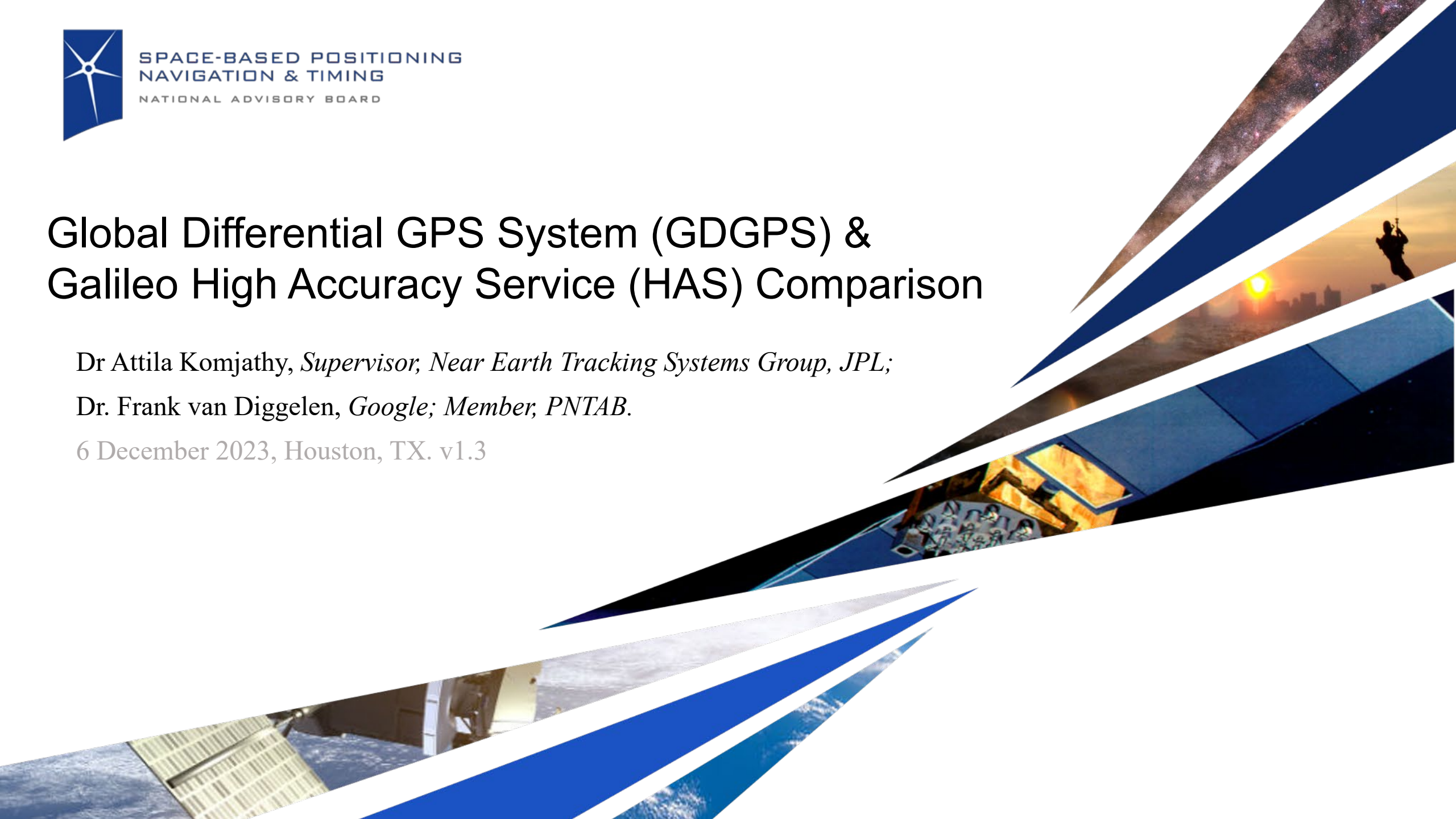
SPACE-BASED POSITIONING
NAVIGATION & TIMING
NATIONAL ADVISORY BOARD

Global Differential GPS System (GDGPS) & Galileo High Accuracy Service (HAS) Comparison

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Outline

- PPP and Real Time DGNSS
- DGNSS review: SSR and OSR
- How we test with phones
- Global Coverage
- Correction components
- Test results
- Proposed data standards

PPP and Real-time DGNSS

Precise Point Positioning (PPP)

Static (usually)

Survey-grade antennas (usually)

Minutes of convergence

Decimeters



Benchmark by Galileo HAS and GDGPS

Real-time Differential GNSS (DGNSS)

Kinematic

Embedded antennas in phones

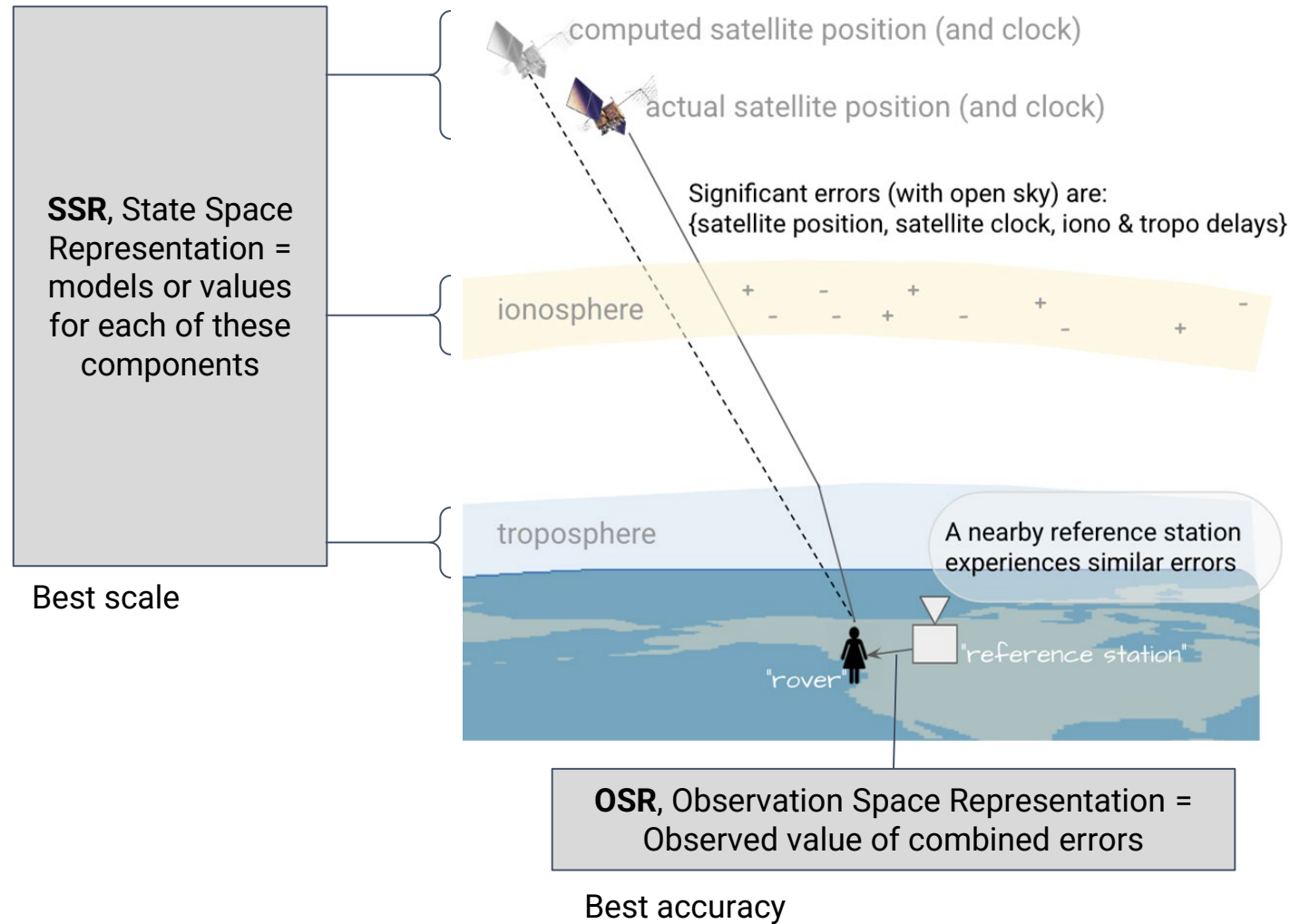
1Hz updates

Meters



Consumer experience for phones, watches, cars

DGNSS review: SSR & OSR

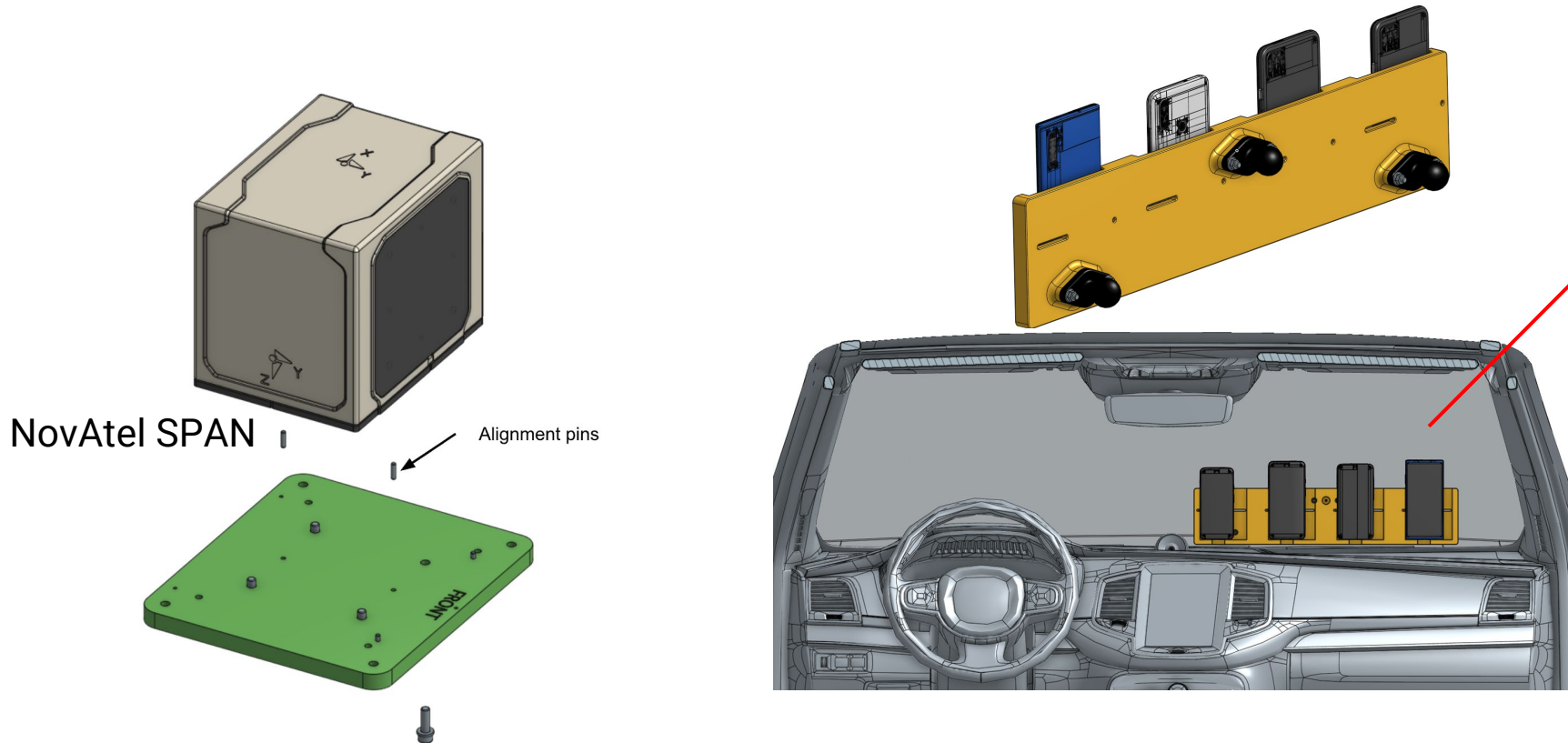


GDGPS, GPS HAS, and Galileo HAS are all SSR,
we use OSR as a reference: an unachievable lower bound on accuracy

Precisely Coordinated Test Vehicle

Customized cars with:

- stable mount for the reference receiver
- 3D printed phone mounts
- mm-level lever arm compensation using robotic arm



Drive Tests setup



25 drive traces in SF Bay area,
from 2023-09-05 to 2023-09-07.
7 different phone models.
3 different GNSS chip vendors.

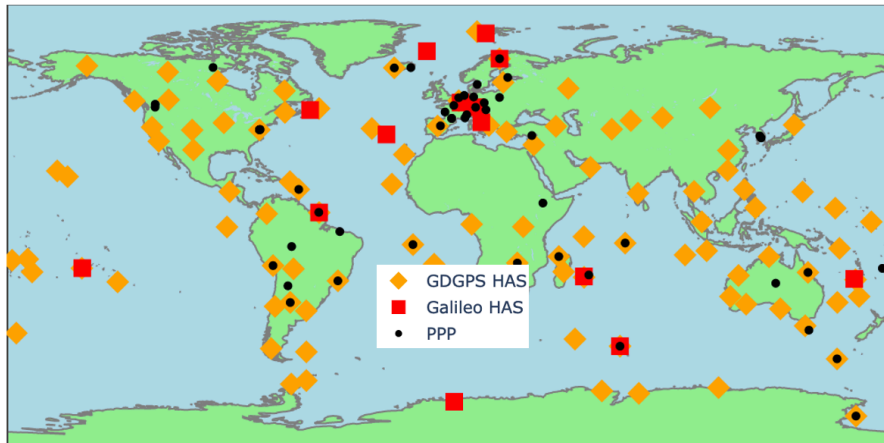
Manufacturer	Model	GNSS Vendor
Google	Pixel 7 Pro	Broadcom
Google	Pixel 6 Pro	Broadcom
Google	Pixel 4 XL	Qualcomm
Google	Pixel 5a	Qualcomm
Google	Pixel 5	Qualcomm
Samsung	Galaxy S8+	Broadcom
Samsung	Galaxy S22 Ultra	Samsung LSI

Coverage

Stations Used for Comparing PPP Performance Using GDGPS HAS and Galileo HAS



- Over 2700 independent overlapping 3-hour Galileo HAS and GDGPS HAS datasets used to compute combined GPS+GAL solutions at 50 stations
- 7-days' worth of GDGPS HAS and Galileo HAS data analyzed

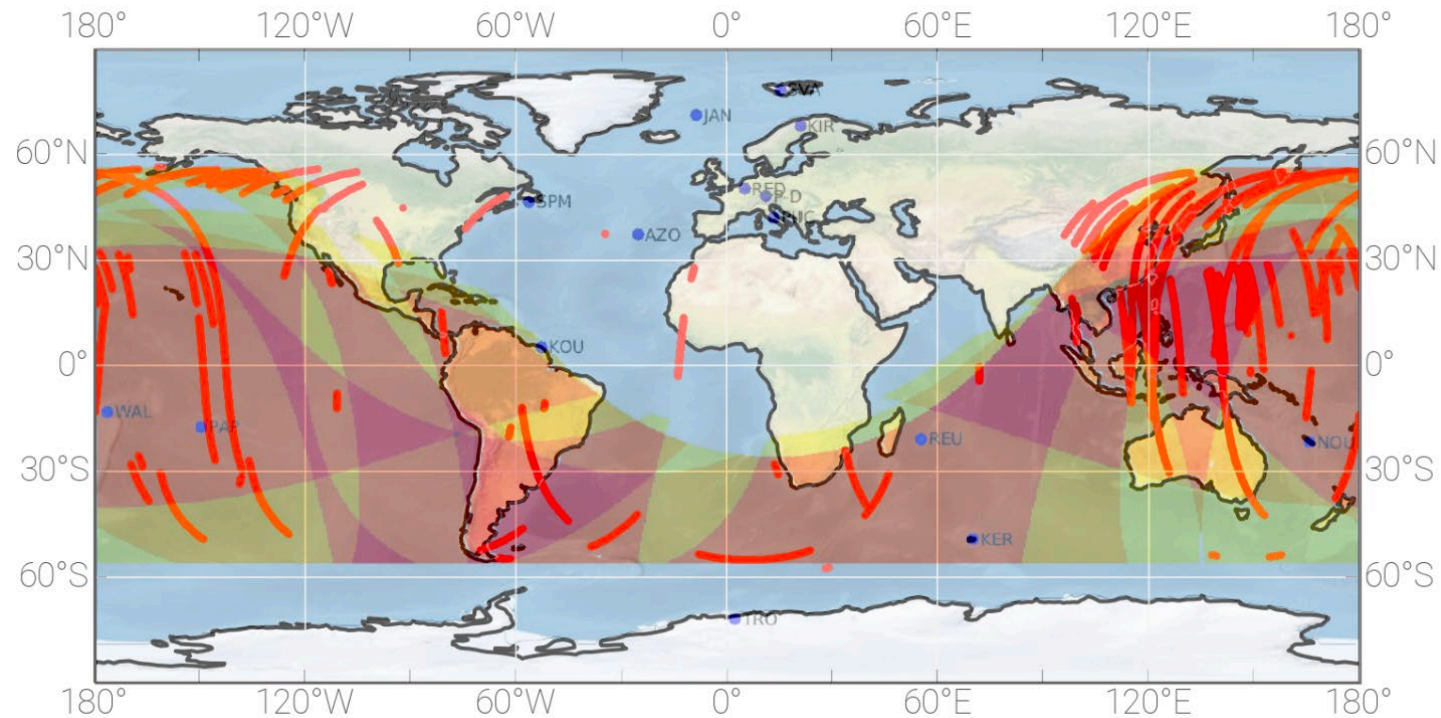


50 stations used globally to compare HAS performances

This document has been reviewed and determined not to contain export controlled technical data.

5 jpl.nasa.gov

Galileo HAS gaps

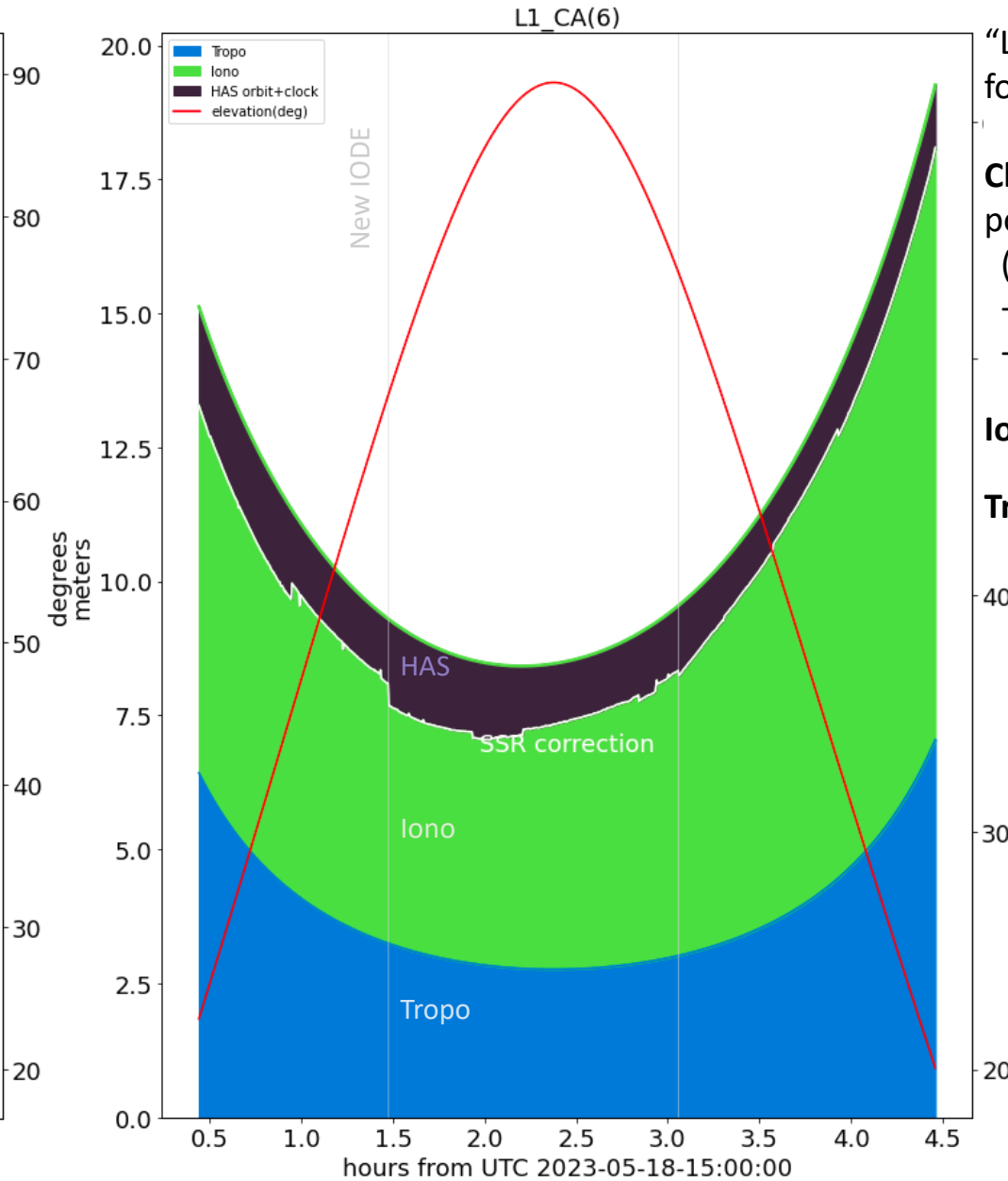
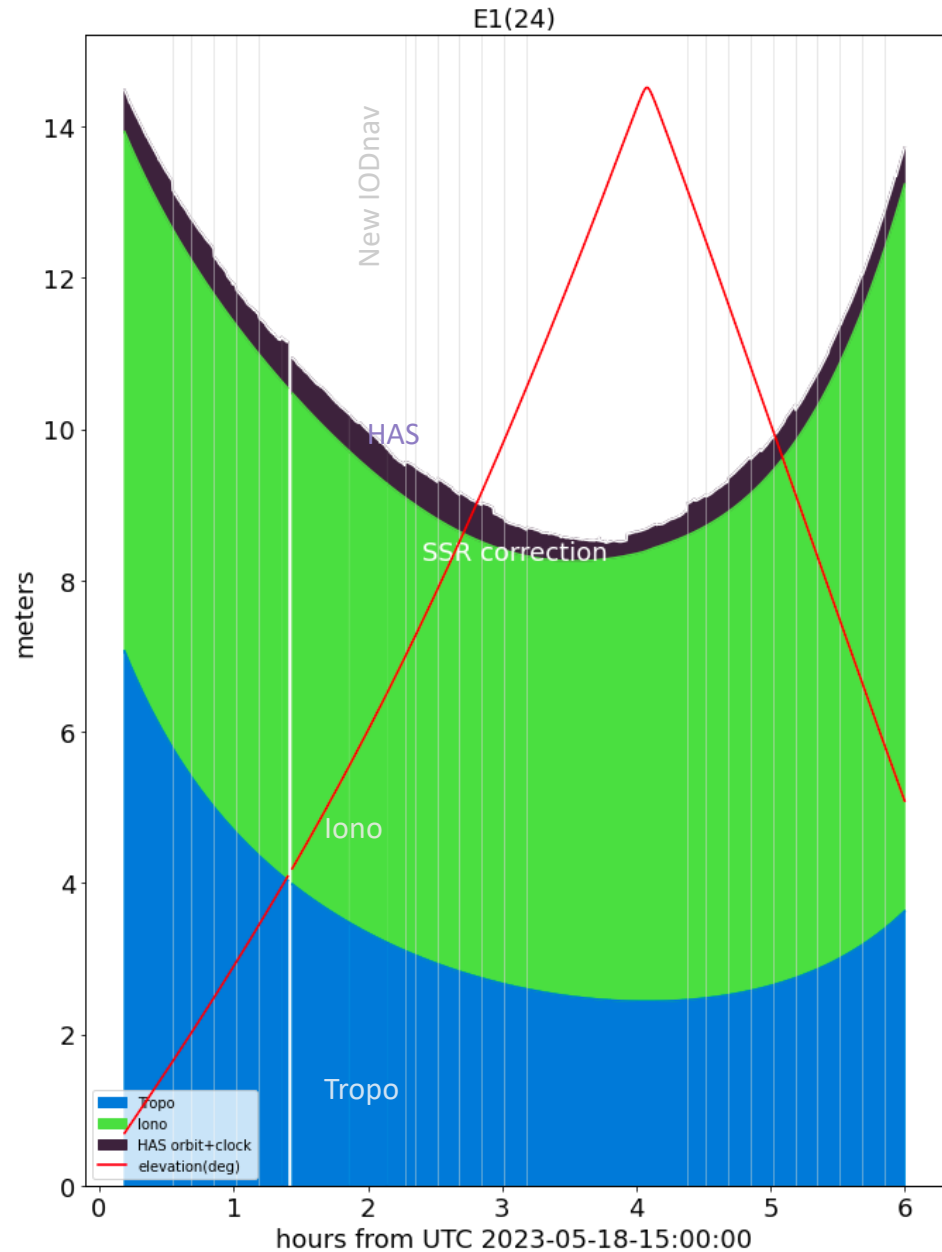


Shading => number of Galileo ground stations with satellite view

 Traces of satellites during gaps in HAS corrections

24h of ground trace on 2023-09-07 (UTC)

Components of SSR: HAS, iono, and tropo corrections



“Layer Cake”
following RTCM 10423:

Clock & orbit: corrections to ephem
position and clock:
(broadcast error af_0, af_1, af_2
+ group delay
+ relativistic offset)

Iono: entire iono delay

Tropo: entire tropo delay

Drive Test Results, all traces

	2d errors (50%, meters)	2d errors (95%, meters)	Cross-track errors (50%, meters)	Cross-track errors (95%, meters)
Chipset	1.85	3.42	1.06	2.49
Galileo HAS SSR	1.18	2.31	0.58	1.57
GDGPS SSR	1.15	2.24	0.58	1.46
DGNSS OSR	0.98	2.07	0.48	1.30

Comparative results, each using the same set of GPS & Galileo satellites (L1 + L5).
SSR corrections includes IGS GIM ionosphere model and Saastamoinen tropo model.
25 drive traces in SF Bay area collected from 2023-09-05 to 2023-09-07.
7 different phone models.

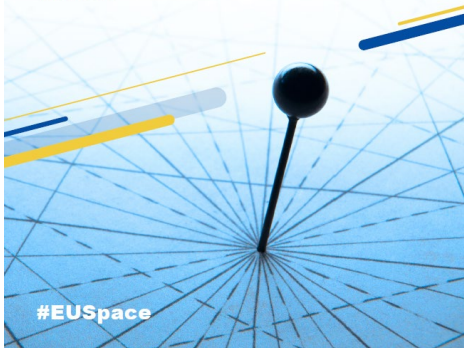
Data Standards

Galileo HAS



GALILEO HIGH ACCURACY SERVICE
INTERNET DATA DISTRIBUTION
INTERFACE CONTROL DOCUMENT
(HAS IDD ICD)

Issue 1.0
January 2023



Galileo High Accuracy Service
- Internet Data Distribution
Interface Control Document
(HAS IDD ICD)

Data format follows RTCM
10403.3 Differential GNSS *

Using NTRIP defined in RTCM
10410.1

* RTCM 10403.3 Differential GNSS defines SSR for GPS not other constellations. Galileo HAS uses an unpublished draft of 10404.3 that includes Galileo corrections:

“Proposal of new RTCM SSR Messages SSR Stage 1: Galileo, QZSS, SBAS, BDS for RTCM STANDARD 10403.3, 2018-06-07, ssr_1_gal_qzss_sbas_bds_v08”

NTRIP: Networked Transport of RTCM via Internet Protocol

GPS HARS

We propose maximum compatibility with existing standards and approaches, to make adoption easy and robust for all device manufacturers.

Summary

- Both Galileo HAS and GDGPS provide similar accuracy:
 - Takes phone accuracy most of the way to OSR
 - From multi-lane accuracy (GNSS chip native solution) to single-lane
- GDGPS provides worldwide coverage