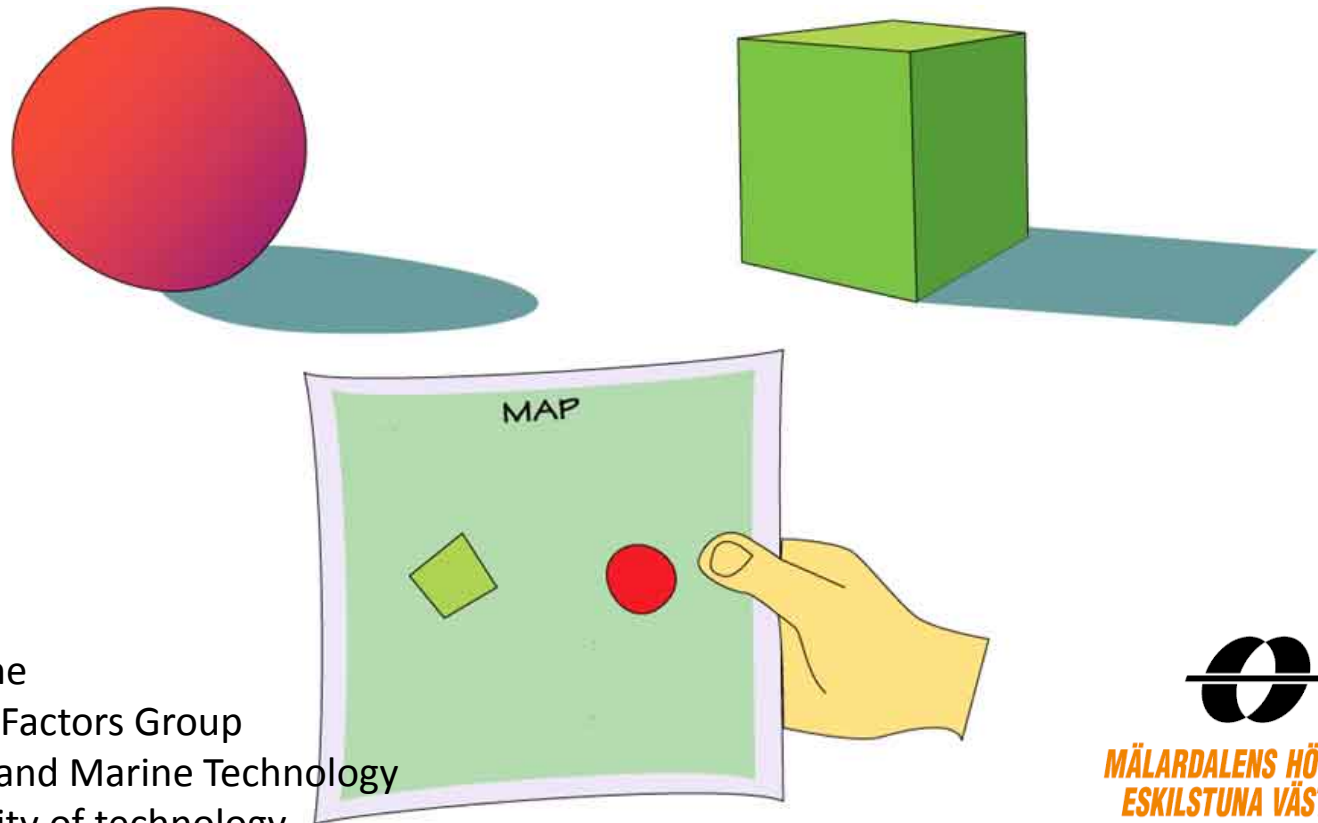


3D Nautical Charts : Cognitive Off-Loading Using an Egocentric Presentation Mode



Dr Thomas Porathe
Maritime Human Factors Group
Dep. Of Shipping and Marine Technology
Chalmers University of technology
Göteborg, Sweden



**MÄLARDALENS HÖGSKOLA
ESKILSTUNA VÄSTERÅS**



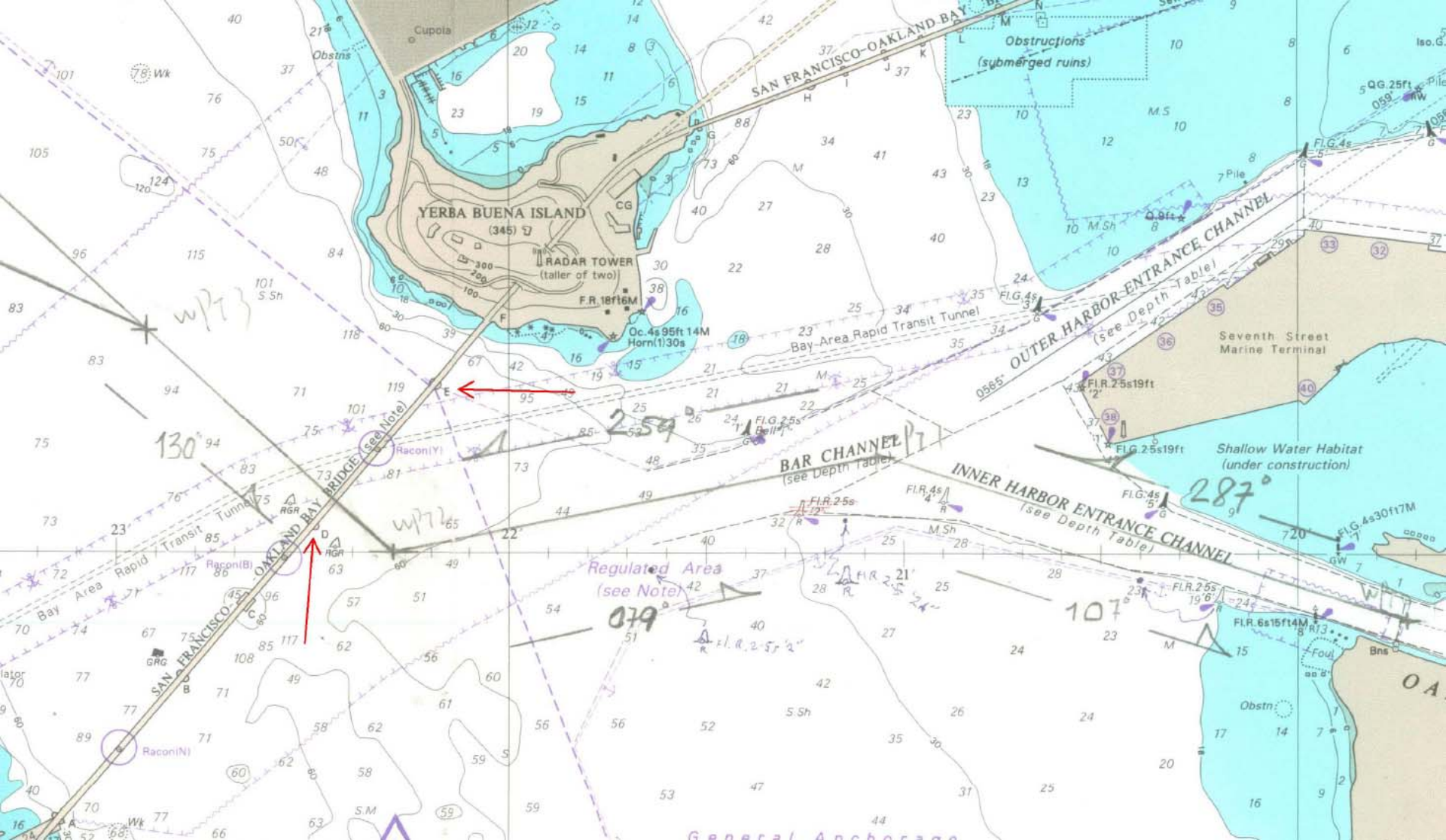
CHALMERS

There is a certain type of accidents characterized by a sudden loss of situation awareness



Cosco Busan , collision with the San Fransisco-Oakland Bay Bridge, 2007







Cosco Busan Bridge - Photo 3

RANGE 15 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

PH

HL

EVENT

ENH OFF

OSIN

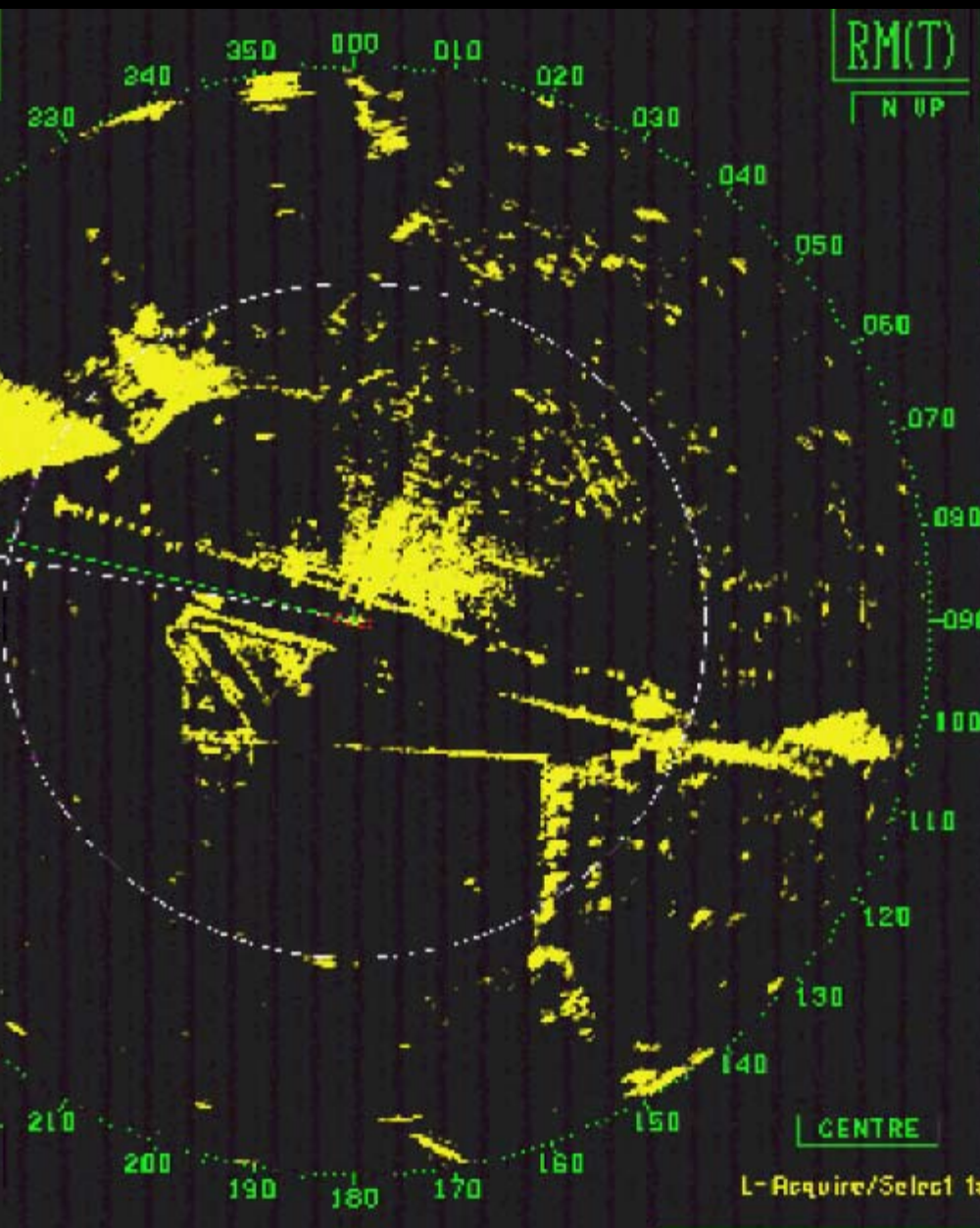
RAIN

SER

MODE

AUTO

AFC



RM(T) HDG 283.2° COG ---°

N UP SOG 0.1 KT NAV

T VECTORS 03.0 MIN TRAILS OFF

EBL 1	260.7 ° T
VRM 1	0.96 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --		
RANGE	---	NM
T BRG	----	°
CPA	---	NM
TCPA	---	MIN
COG	----	°
SOG	---	KT
BCR	---	NM
BCT	--	MIN

OWN POSITION INAVI

LAT 37°47.805 N

LOX 122°19.361 W

UTC 16:08:14 W94

CURSOR POSITION

RANGE 0.87 NM

T BRG 256.0°

LAT 37°47.52 N

LOX 122°20.40 W

L-Require/Select target R-Cancel

RANGE 1.5 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

PH

HL

EVENT

ENH OFF

RAIN

SER

MODE

+
-

NM

STBY

SP

PH

HL

EVENT

ENH OFF

RAIN

SER

MODE

AUTO

AFC

RM(T)

N UP

HDG 284.3°

COG ---°

SOG 0.6 KT

NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1 285.9 ° T

VRM 1 0.96 NM

EBL 2 OFF

VRM 2 OFF

NO ALARMS

TARGET --		
RANGE	--	NM
T BRG	---	°
CPA	--	NM
TCPA	--	MIN
COG	---	°
SOG	--	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION IN NAVI

LAT 37°47.806 N

LOX 122°19.371 W

UTC 16:08:59 W84

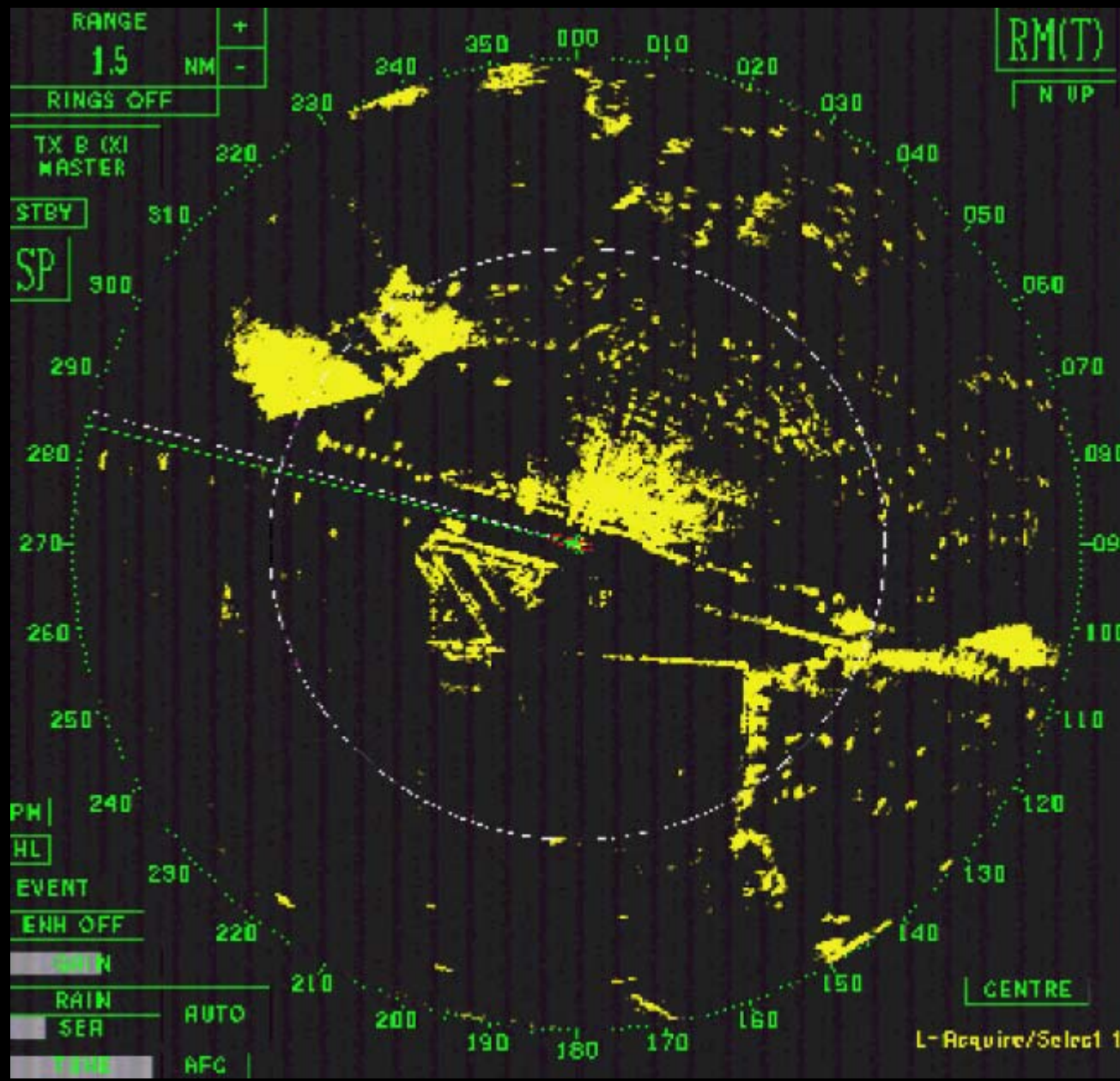
CURSOR POSITION

RANGE 0.87 NM

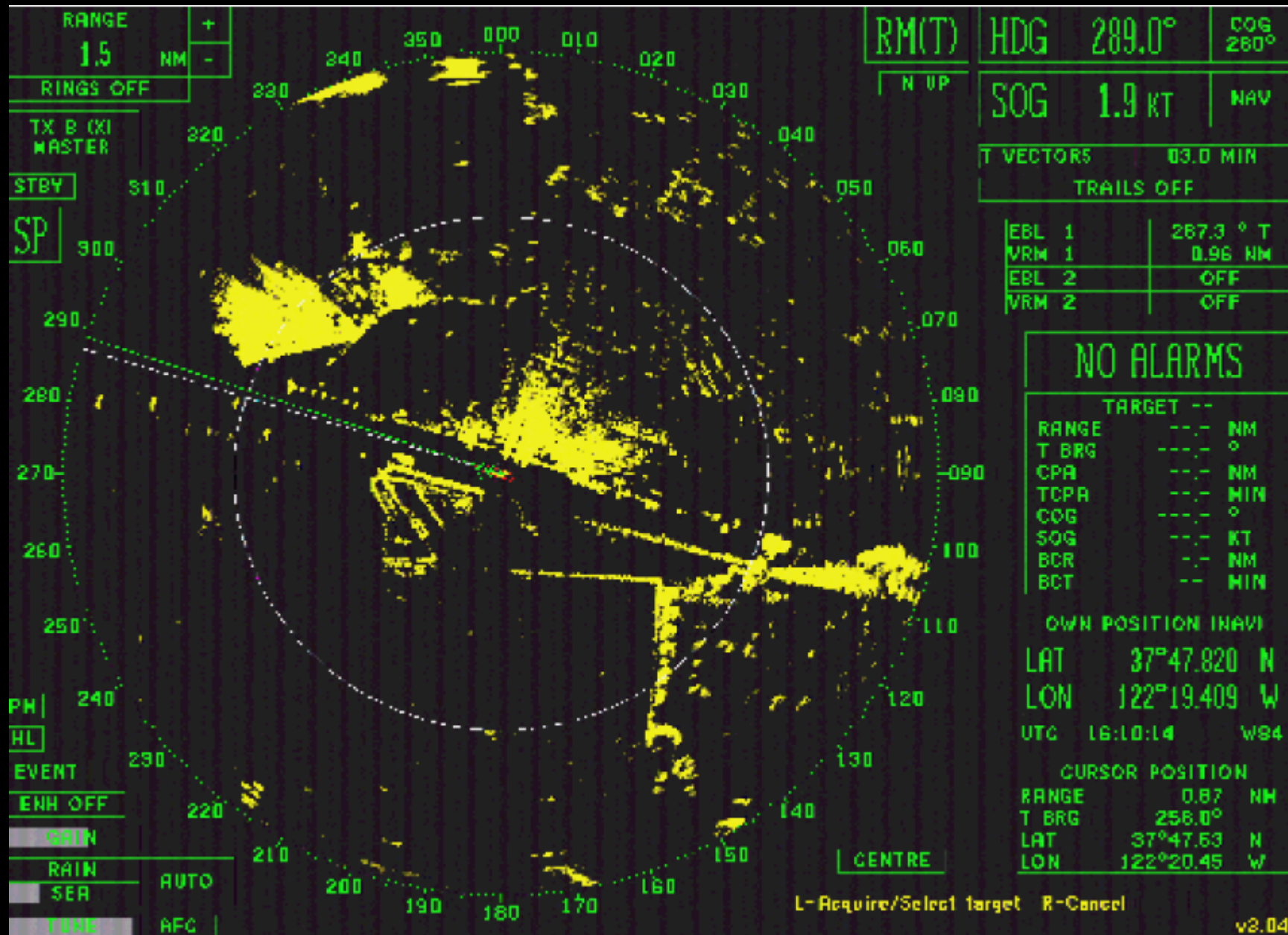
T BRG 258.0°

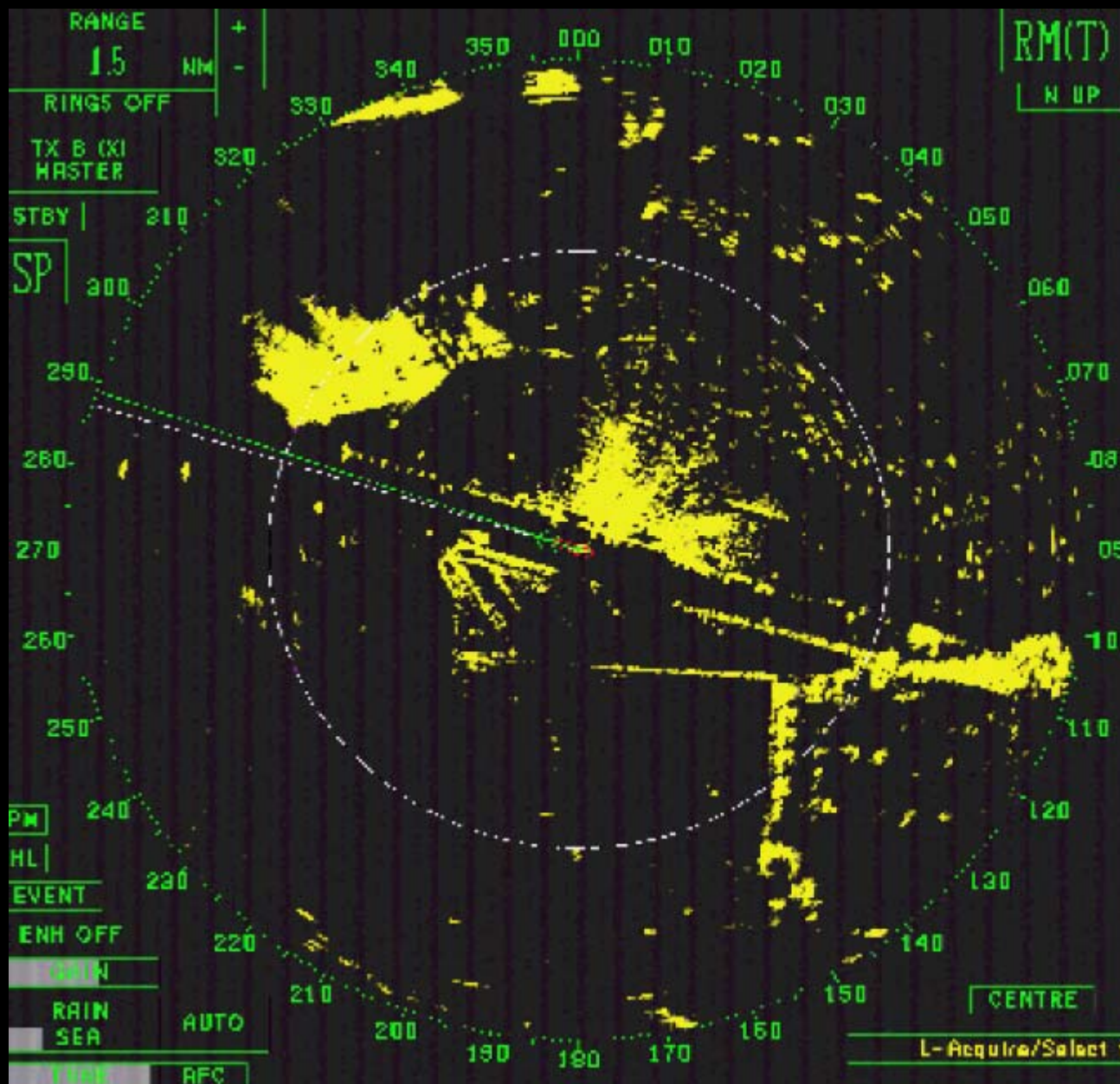
LAT 37°47.52 N

LOX 122°20.41 W



L- Acquire/Select target R- Cancel





RANGE 15 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

PH

HL

EVENT

ENH OFF

GAIN

RAIN

SER

TUNE

+

-

NM

STBY

SP

PH

HL

EVENT

ENH OFF

GAIN

RAIN

SER

TUNE

AUTO

AFC

PH

HL

EVENT

ENH OFF

GAIN

RAIN

SER

TUNE

AUTO

AFC

RM(T)

N UP

HDG 288.7° COG 287°

SOG 4.2 KT NAV

T VECTORS 03.0 MIN TRAILS OFF

EBL 1 287.3 ° T VRM 1 0.96 NM

EBL 2 OFF VRM 2 OFF

NO ALARMS

TARGET --		
RANGE	--	NM
T BRG	---	°
CPA	--	NM
TCPA	---	MIN
COG	---	°
SOG	---	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION (NAV)

LAT 37°47.860 N

LON 122°19.579 W

UTC 16:12:29 W84

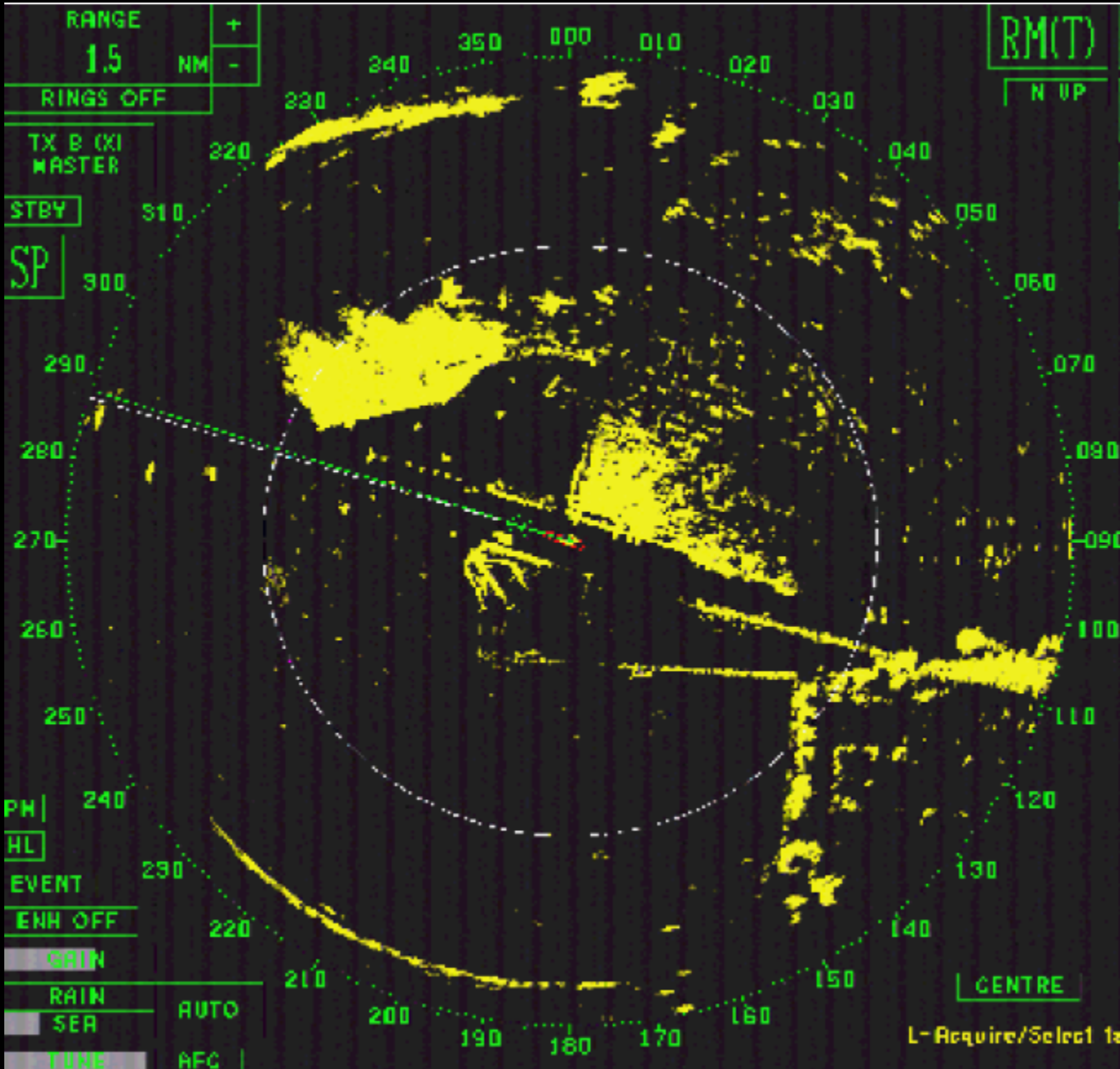
CURSOR POSITION

RANGE 0.87 NM

T BRG 256.0°

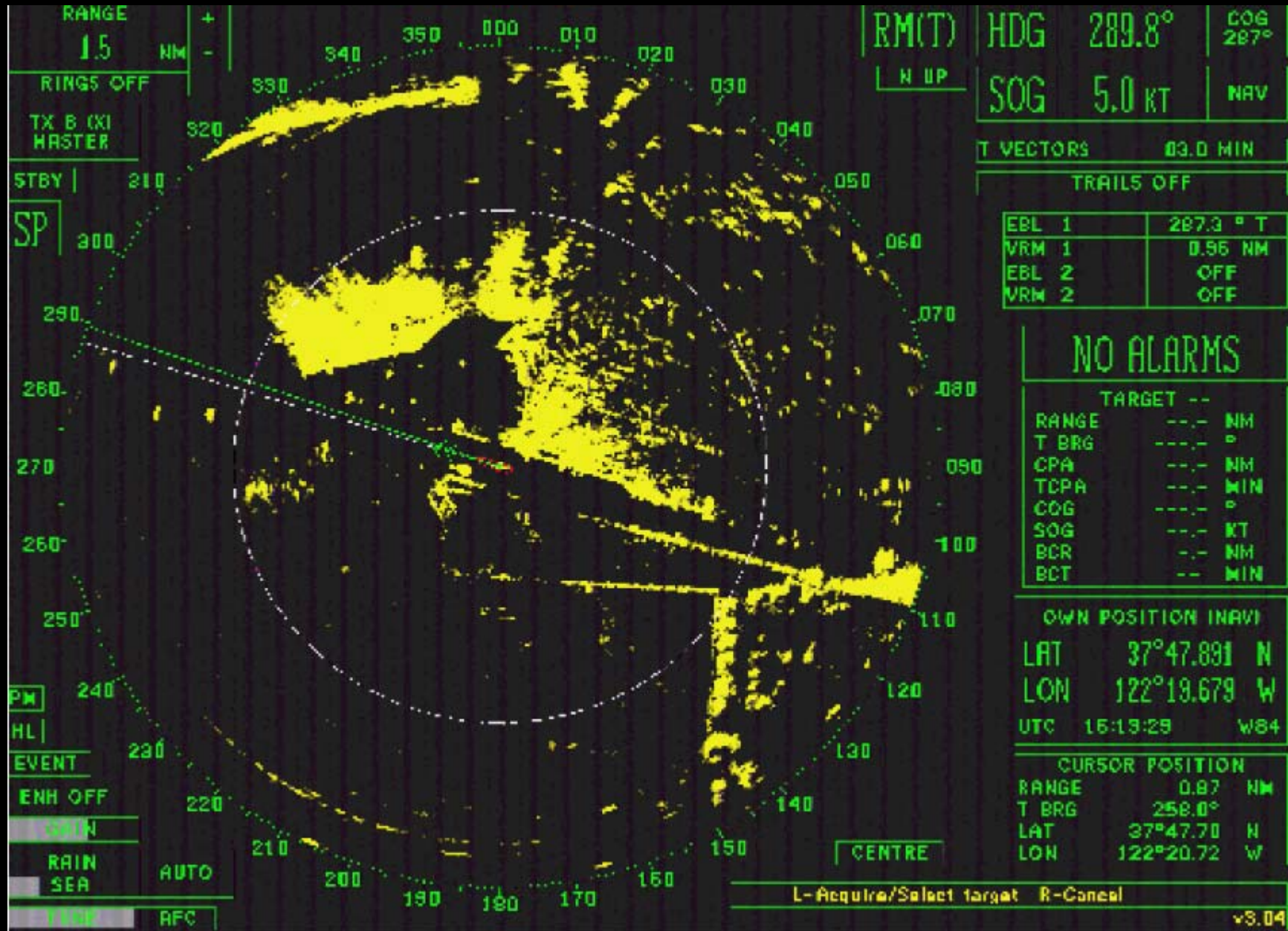
LAT 37°47.57 N

LON 122°20.52 W



L-Acquire/Select target R-Cancel

v2.04



RANGE 15 NM

RINGS OFF

TX B (X) MASTER

STBY

SP 900

290

280

270

260

250

PH 240

HL

EVENT

ENH OFF

RAIN

SER

230

220

210

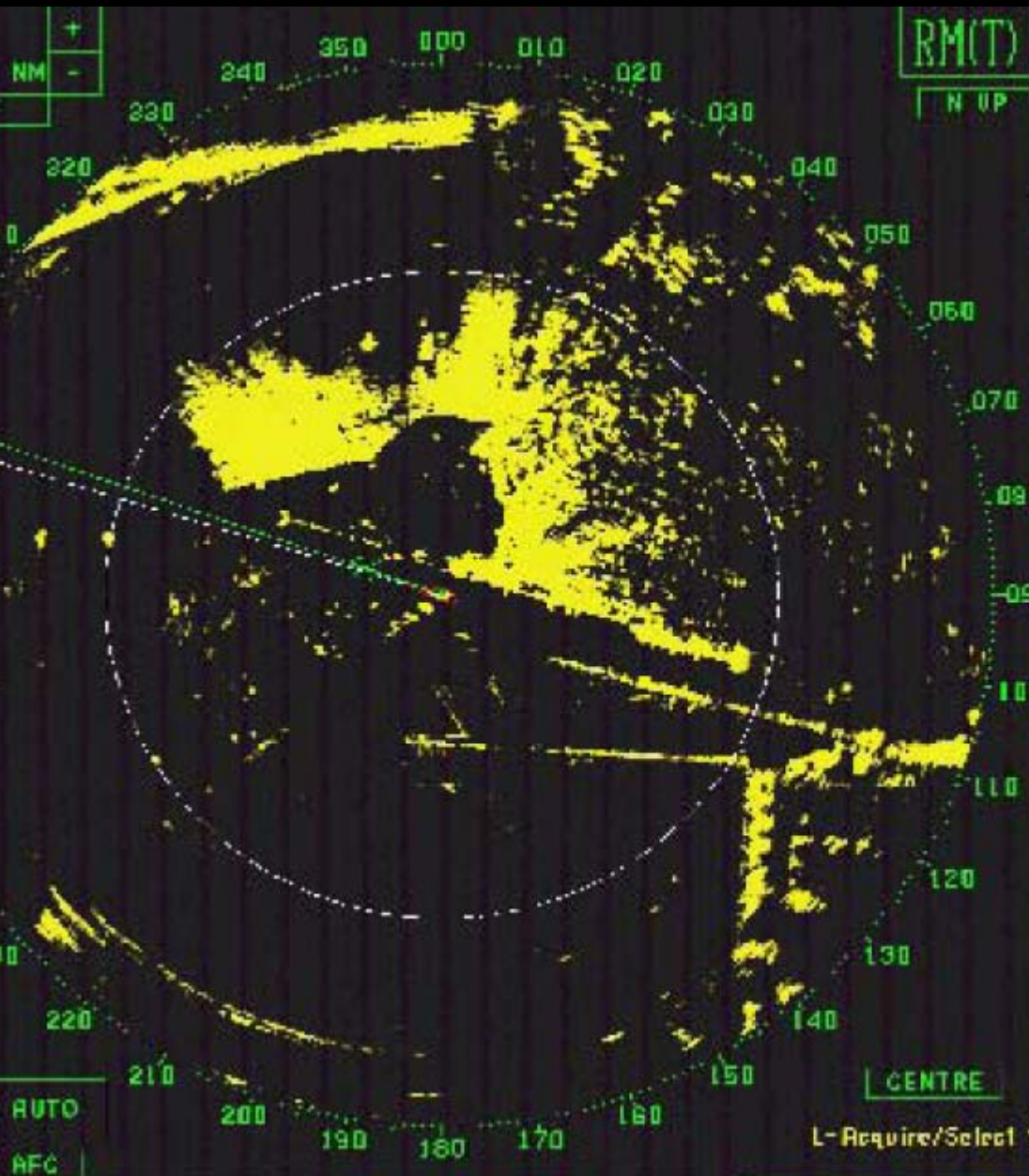
200

190

180

170

160



RM(T)

HDG 290.0°

COG 290°

N UP

SOG 5.6 KT

NAV

T VECTORS 03.0 MIN
TRAILS OFF

EBL 1	267.3 ° T
VRM 1	0.96 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --		
RANGE	---	NM
T BRG	---	°
CPA	---	NM
TCPA	---	MIN
COG	---	°
SOG	---	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION IN NAVI
 LAT 37°47.921 N
 LON 122°19.789 W
 UTC 16:14:29 W94

CURSOR POSITION
 RANGE 0.87 NM
 T BRG 256.0°
 LAT 37°47.73 N
 LON 122°20.83 W

L- Acquire/Select target R-Cancel

v2.04



RM(T)	HDG 287.8°	COG 291°
H UP	SOG 6.0 KT	NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	287.3 ° T
VRM 1	0.96 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	-- NM
T BRG	-- °
CPA	-- NM
TCPA	-- MIN
COG	-- °
SOG	-- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION INAVI	
LAT	37°47.943 N
LON	122°19.910 W
UTC	16:15:29 W84

CURSOR POSITION	
RANGE	0.87 NM
T BRG	258.0°
LAT	37°47.76 N
LON	122°20.95 W

L- Acquire/Select target R- Cancel



RANGE

15

NM

RINGS OFF

TX B (X)
MASTER

STBY

SP

PM

HL

EVENT

ENH OFF

RAIN

SEA

WIND

AUTO

RFC

RM(T)

N UP

HDG 288.2°

SOG 6.4 KT

COG 288°

NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	287.3 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	-- NM
T BRG	-- °
CPA	-- NM
TCPA	-- MIN
COG	-- °
SOG	-- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION (NAVI)

LAT 37°47.979 N

LOX 122°20.039 W

UTC 15:15:28 W84

CURSOR POSITION

RANGE 0.87 NM

T BRG 258.0°

LAT 37°47.79 N

LOX 122°21.09 W

L-Acquire/Select target R-Cancel

v3.04

RANGE 1.5 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

PH

HL

EVENT

ENH OFF

RAIN

SEA

AUTO

AFC

RM(T)

N UP

HDG 286.5°

COG 289°

SOG 6.8 KT

NAV

T VECTORS 03.0 MIN
TRAILS OFF

EBL 1	287.3 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --		
RANGE	--	NM
T BRG	---	°
CPA	--	NM
TCPA	--	MIN
COG	---	°
SOG	--	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION IN NAVI

LAT 37°48.018 N

LOX 122°20.170 W

UTC 16:17:29 W84

CURSOR POSITION

RANGE 0.87 NM

T BRG 258.0°

LAT 37°47.83 N

LOX 122°21.21 W

CENTRE

L- Acquire/Select target R- Cancel



RANGE 15 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

290

280

270

260

250

PH 240

HL

EVENT

ENH OFF

RAIN

SEA

WIND

320

300

310

290

280

270

260

250

240

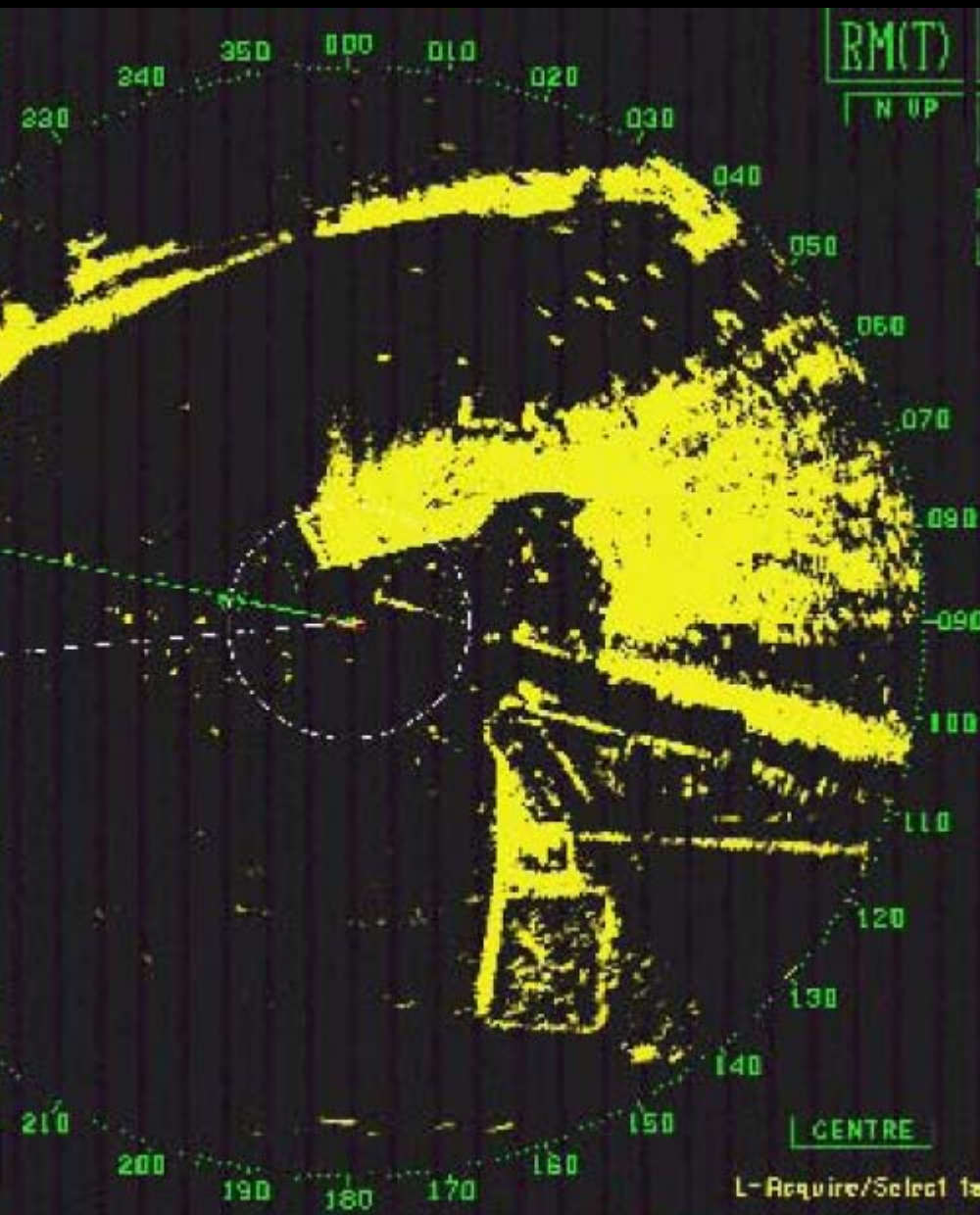
230

220

210

AUTO

AFC



RM(T)

N UP

HDG 282.5°

COG 261°

SOG 7.4 KT

NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	264.6 ° T
VRM 1	0.23 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --		
RANGE	--	NM
T BRG	----	°
CPA	--	NM
TCPA	--	MIN
COG	----	°
SOG	--	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION (NAVI)

LAT 37°48.075 N

LOX 122°20.472 W

UTC 16:19:29 W84

CURSOR POSITION

RANGE 0.67 NM

T BRG 256.0°

LAT 37°47.85 N

LOX 122°21.51 W

L-Acquire/Select target R-Cancel

v2.04



RANGE 15 NM

RINGS OFF

TX B (X) MASTER

STBY

SP

PH

HL

EVENT

ENH OFF

RAIN

SEA

WIND

AUTO

SE

AF

RM(T)

N UP

HDG 283.2°

COG 278°

SOG 7.7 KT

NAV

T VECTORS 03.0 MIN
TRAILS OFF

EBL 1	264.6 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET	--	--
RANGE	---	NM
T BRG	----	°
CPA	---	NM
TCPA	---	MIN
COG	----	°
SOG	---	KT
BCR	--	NM
BCT	--	MIN

OWN POSITION (NAVI)
LAT 37°48.095 N
LON 122°20.631 W
UTC 16:20:29 W94

CURSOR POSITION
RANGE 0.87 NM
T BRG 256.0°
LAT 37°47.51 N
LON 122°21.57 W

L- Acquire/Select target R- Cancel

v2.04







RANGE
15 NM

RINGS OFF

TX B (X)
MASTER

STBY

SP
900

290

280

270

260

250

PH | 240

HL

EVENT

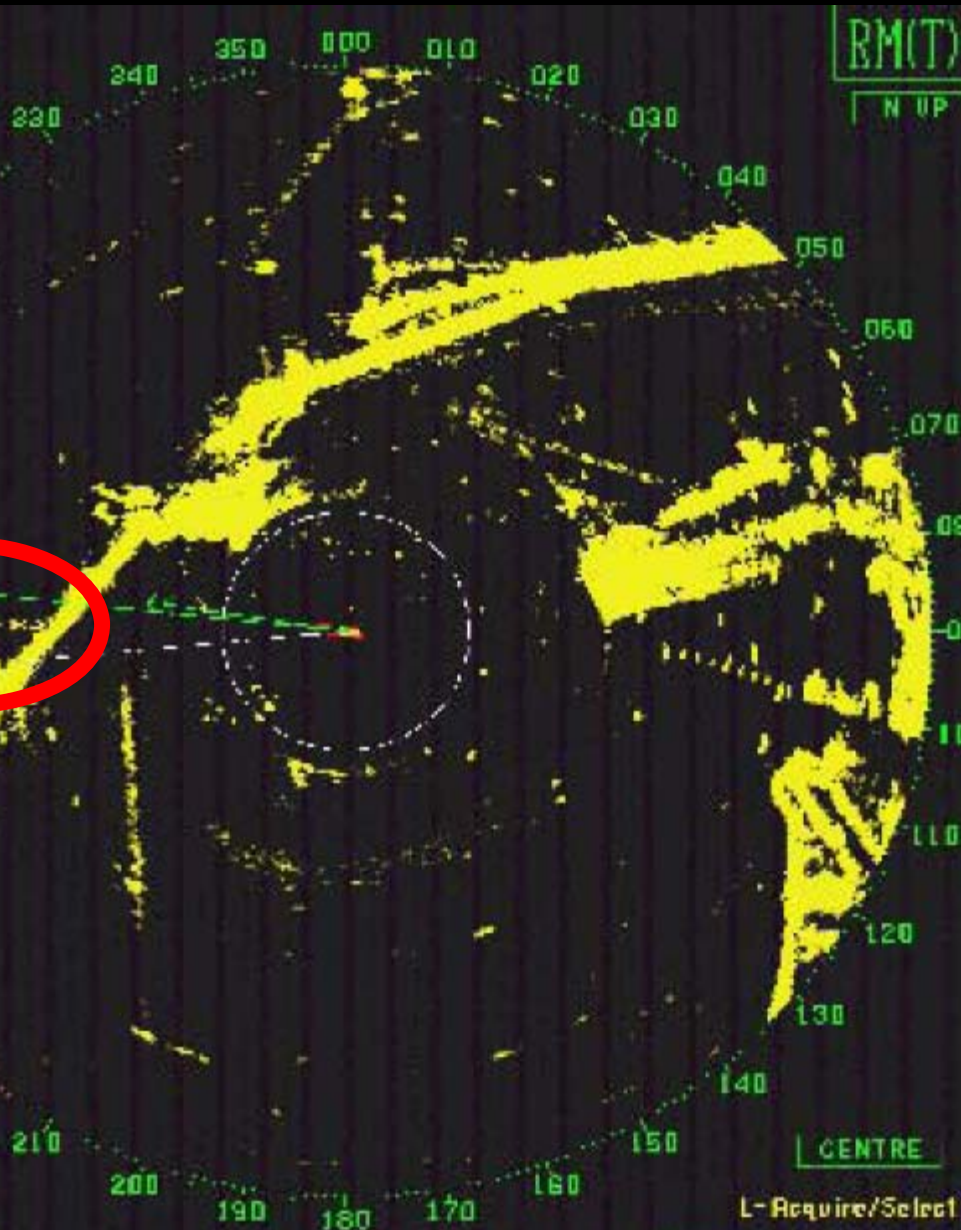
ENH OFF

RAIN

SER

AUTO

AFC



RM(T)

HDG 275.5°

COG 279°

N UP

SOG 10.8 KT

NAV

T VECTORS 03.0 MIN
TRAILS OFF

EBL 1	254.6 ° T
VRM 1	0.23 NM
EBL 2	OFF
VRM 2	OFF

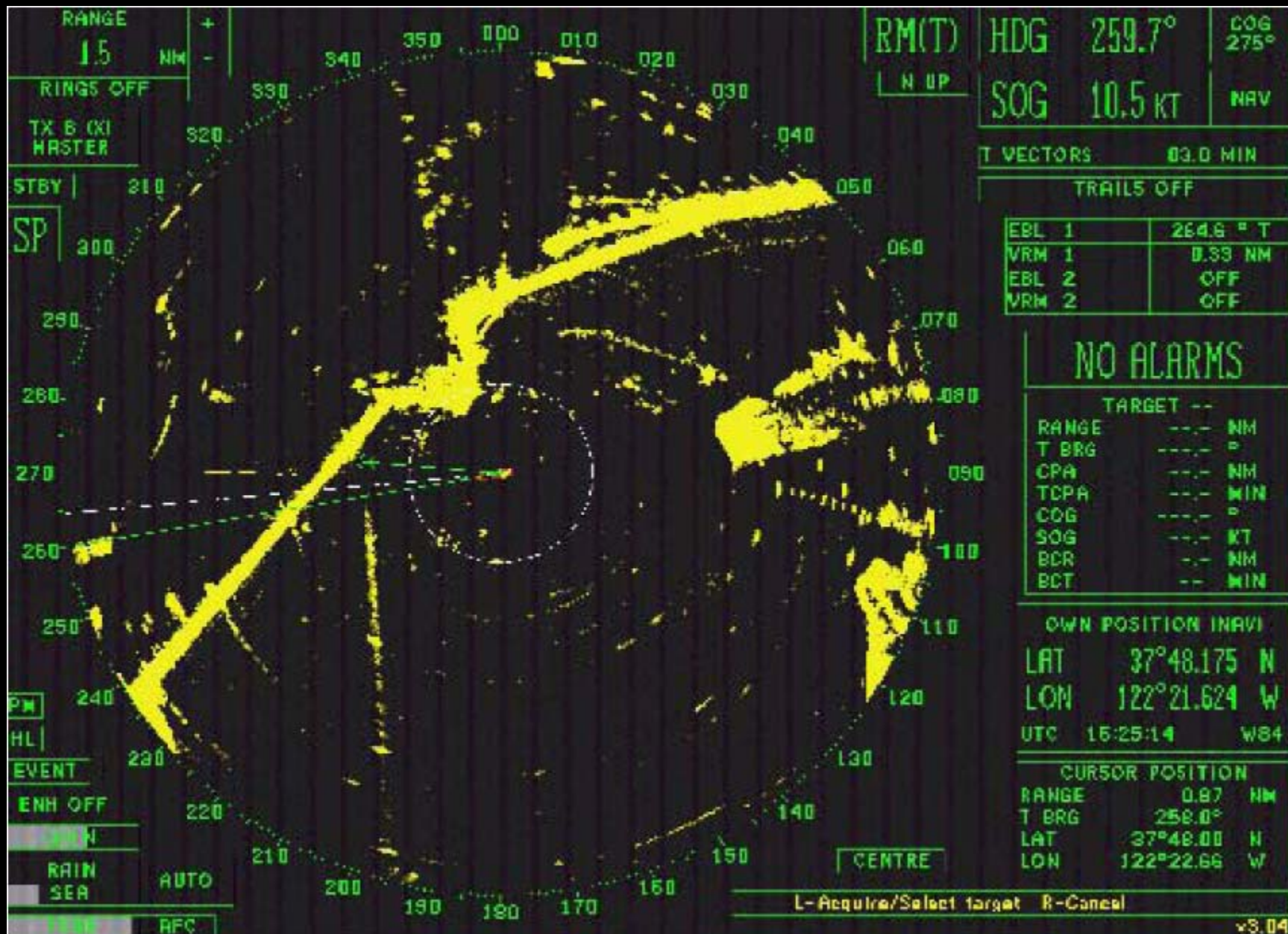
NO ALARMS

TARGET --	
RANGE	-- NM
T BRG	-- °
CPA	-- NM
TCPA	-- MIN
COG	-- °
SOG	-- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION INAVI
 LAT 37°48.189 N
 LON 122°21.453 W
 UTC 16:24:29 W84

CURSOR POSITION
 RANGE 0.87 NM
 T BRG 258.0°
 LAT 37°48.01 N
 LON 122°22.49 W

L-Acquire/Select target R-Cancel



RANGE
15 NM

RINGS OFF

TX B (X)
MASTER

STBY | 210

SP | 300

290

280

270

260

250

240

PM | 230

HL |

EVENT

ENH OFF

220

RAIN SEA AUTO

210 200 190 180 170 160

RM(T)
N UP

HDG 259.7°

COG 275°

SOG 10.5 KT

NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	284.6 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	--- NM
T BRG	--- °
CPA	--- NM
TCPA	--- MIN
COG	--- °
SOG	--- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION INAVI	
LAT	37°48.175 N
LON	122°21.624 W
UTC	15:25:14 W84

CURSOR POSITION	
RANGE	0.87 NM
T BRG	258.0°
LAT	37°48.00 N
LON	122°22.66 W

CENTRE
L-Acquire/Select target R-Cancel



RM(T)

HDG 241.2°

COG 248°

N UP

SOG 10.5 KT

NAV

T VECTORS 83.0 MIN

TRAILS OFF

EBL 1	218.2 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	--- NM
T BRG	--- °
CPA	--- NM
TCPA	--- MIN
COG	--- °
SOG	--- KT
BCR	--- NM
BCT	--- MIN

OWN POSITION IN NAVI
 LAT 37°48.069 N
 LON 122°21.878 W
 UTC 16:26:29 W84

CURSOR POSITION
 RANGE 0.97 NM
 T BRG 258.0°
 LAT 37°47.90 N
 LON 122°22.92 W

L-Acquire/Select target R-Cancel

RANGE 15 NM

RINGS OFF

TX B (K) MASTER

STBY

SP 900

290

280

270

260

250

PH 240

HL

EVENT

ENH OFF

RAIN

SEA

1000

220

210

200

190

180

170

160

150

140

130

120

110



RM(T)

N UP

HDG 253.8°

COG 234°

SOG 10.6 KT

NAV

T VECTORS 03.0 MIN
TRAILS OFF

EBL 1	310.2 ° T
VRM 1	0.29 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET	--	--
RANGE	--	NM
T BRG	--	°
CPA	--	NM
TCPA	--	MIN
COG	--	°
SOG	--	KT
BCR	--	NM
BCT	--	MIN

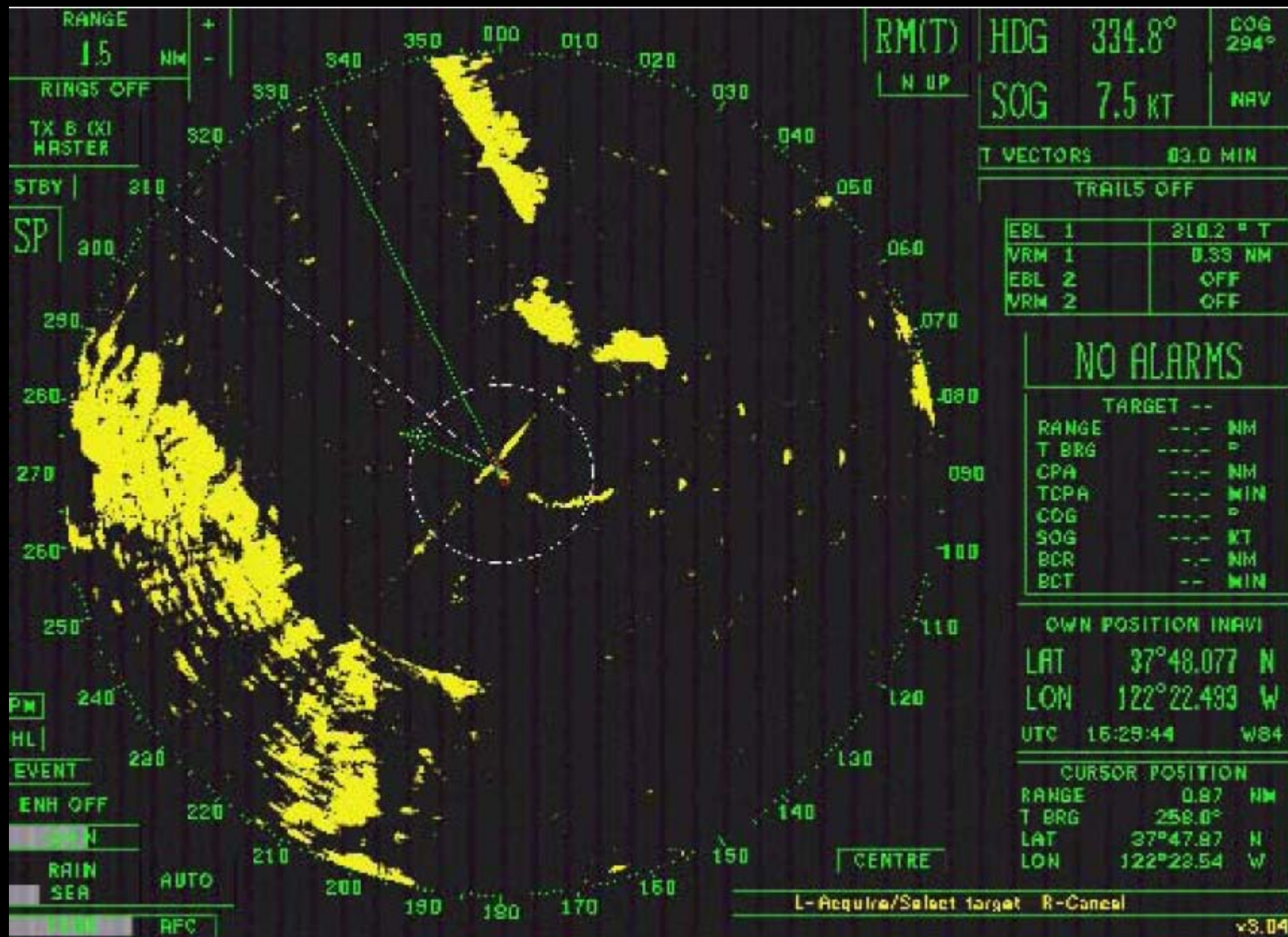
OWN POSITION IN NAVI
 LAT 37°47.980 N
 LON 122°22.083 W
 UTC 16:27:29 W84

CURSOR POSITION
 RANGE 0.87 NM
 T BRG 258.0°
 LAT 37°47.81 N
 LON 122°23.12 W

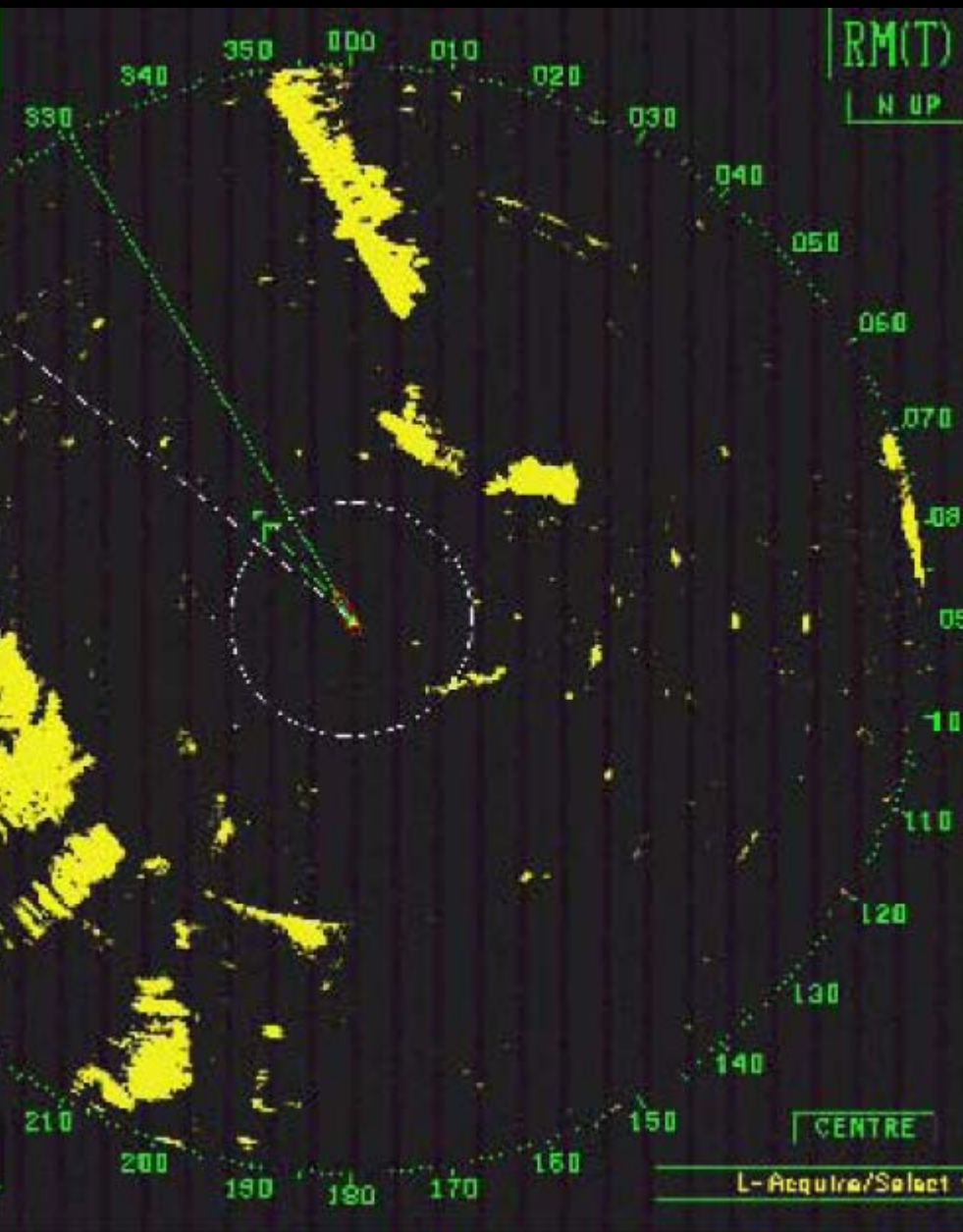
CENTRE

L-Acquire/Select target R-Cancel





RANGE 15 NM
 RINGS OFF
 TX B (X) MASTER
 STBY | 210
 SP 300
 250
 260
 270
 260
 250
 240
 HL
 EVENT
 ENH OFF
 RAIN SEA AUTO
 RFC



RM(T) HDG 330.7° COG 319°
 N UP SOG 8.1 KT NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	310.2 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	-- NM
T BRG	-- °
CPA	-- NM
TCPA	-- MIN
COG	-- °
SOG	-- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION IN NAVI
 LAT 37°48.136 N
 LON 122°22.517 W
 UTC 16:30:14 W84

CURSOR POSITION
 RANGE 0.87 NM
 T BRG 258.8°
 LAT 37°47.93 N
 LON 122°28.57 W

L-Acquire/Select target R-Cancel
 v3.04



What went wrong?







The Human Factor



The Human Factor

A dark, high-angle photograph of an aircraft cockpit. The cockpit is filled with various instrument panels, screens, and control panels. The lighting is dim, with the primary light source being the screens and some ambient light from the windows. The overall atmosphere is serious and focused.

Is subject to attention narrowing (“tunnel vision”)

The Human Factor



Is subject to attention narrowing (“tunnel vision”)

Falls asleep

Forgets

Misunderstands

Slips

Make mistakes

Make short cuts

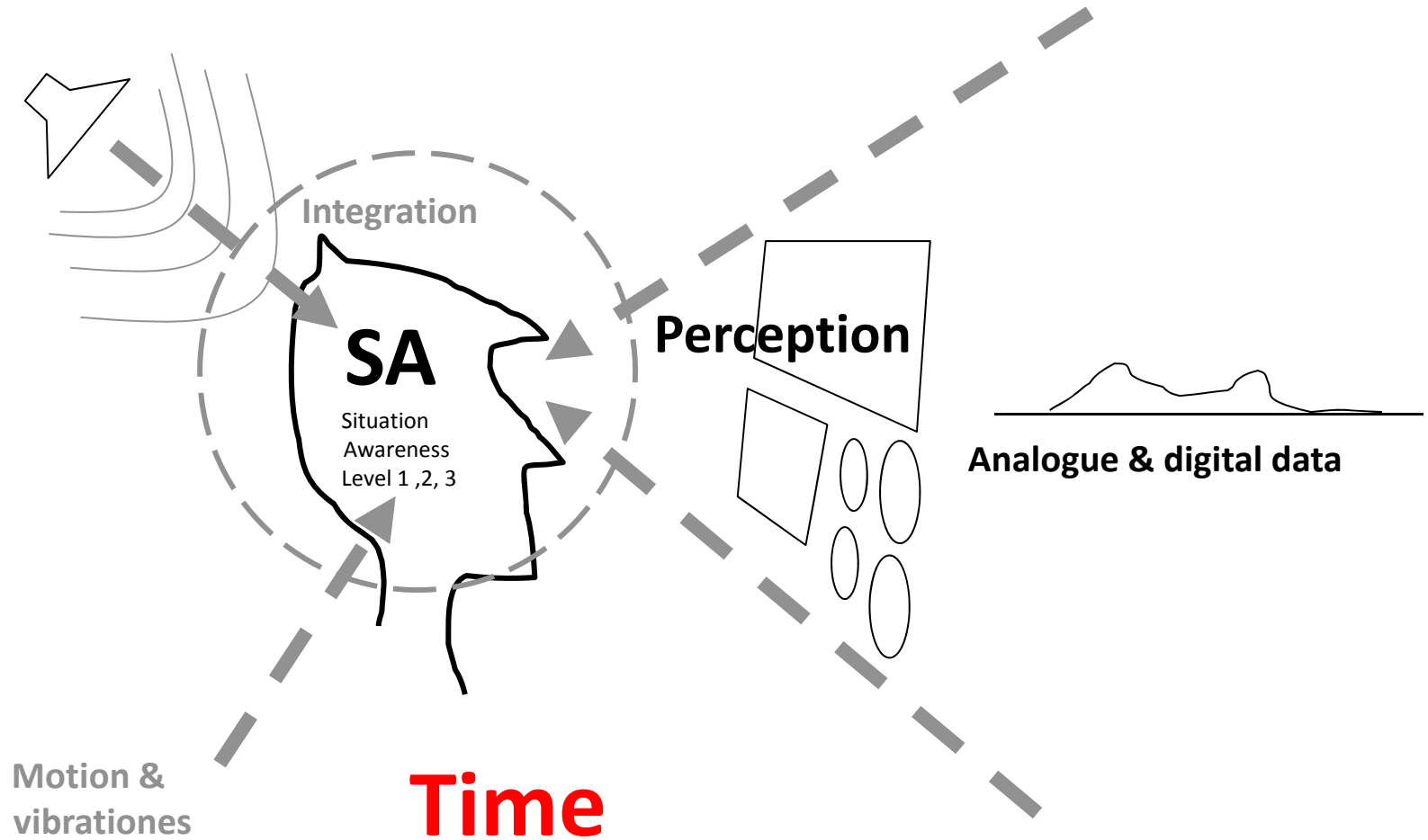
...

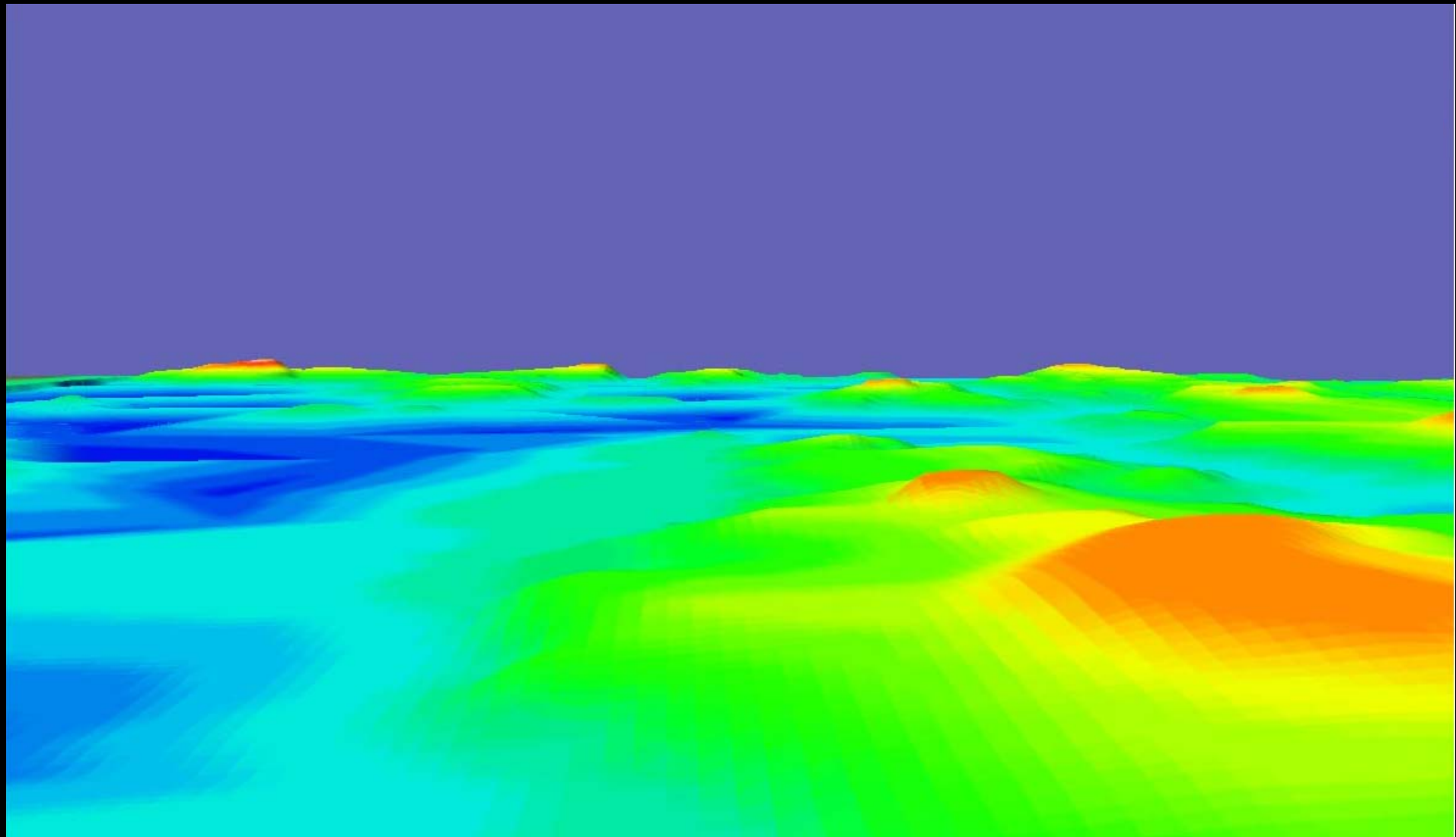
The bad news

- Human error continues to be a dominant factor in approximately 80 to 85% of maritime accidents;
- Failures of situation awareness and situation assessment overwhelmingly predominate, being a causal factor in the majority of those accidents attributed to human error;
- Human fatigue and task omission seem closely related to failures of situation awareness and the human errors and accidents that result.

(Baker & McCaffery, 2005)

Baker, C. C., & McCafferty, D. B. (2005). *Accident database review of human element concerns: What do the results mean for classification?*
Paper presented at The International Conference Human Factors in Ship Design and Operation, RINA Feb, 2005







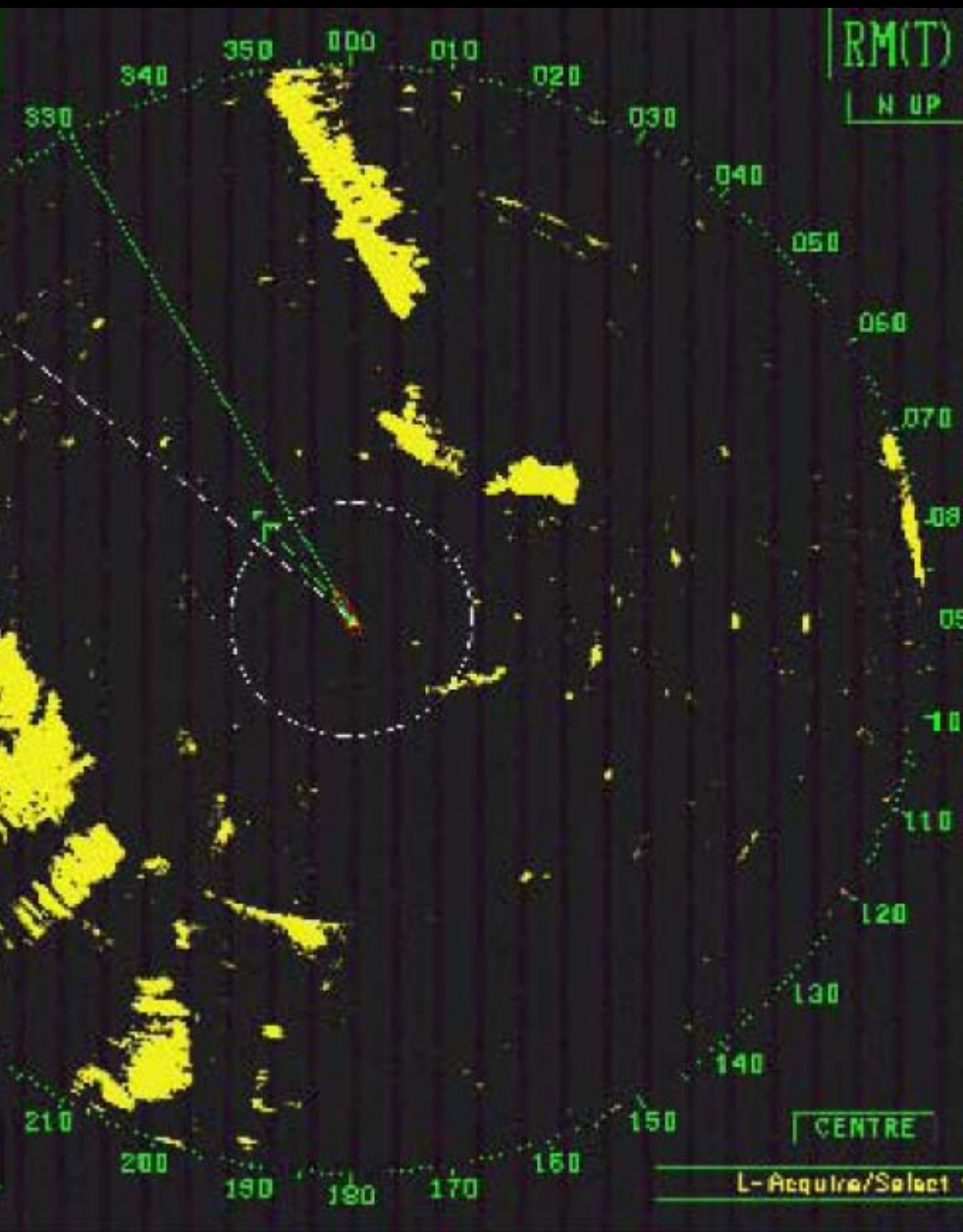
Bev Doolittle (1984). *The Forest has Eyes*

Information design – solving problems

“Solving a problem simply means representing it so as to make the solution transparent.”

(Simon, 1996)

RANGE 15 NM
 RINGS OFF
 TX B (X) MASTER
 STBY 210
 SP 300
 PW 240
 HL
 EVENT
 ENH OFF
 RAIN SEA AUTO
 RFC



RM(T) HDG 330.7° COG 319°
 N UP SOG 8.1 KT NAV

T VECTORS 03.0 MIN

TRAILS OFF

EBL 1	310.2 ° T
VRM 1	0.33 NM
EBL 2	OFF
VRM 2	OFF

NO ALARMS

TARGET --	
RANGE	-- NM
T BRG	-- °
CPA	-- NM
TCPA	-- MIN
COG	-- °
SOG	-- KT
BCR	-- NM
BCT	-- MIN

OWN POSITION INAVI
 LAT 37°48.136 N
 LON 122°22.517 W
 UTC 16:30:14 W84

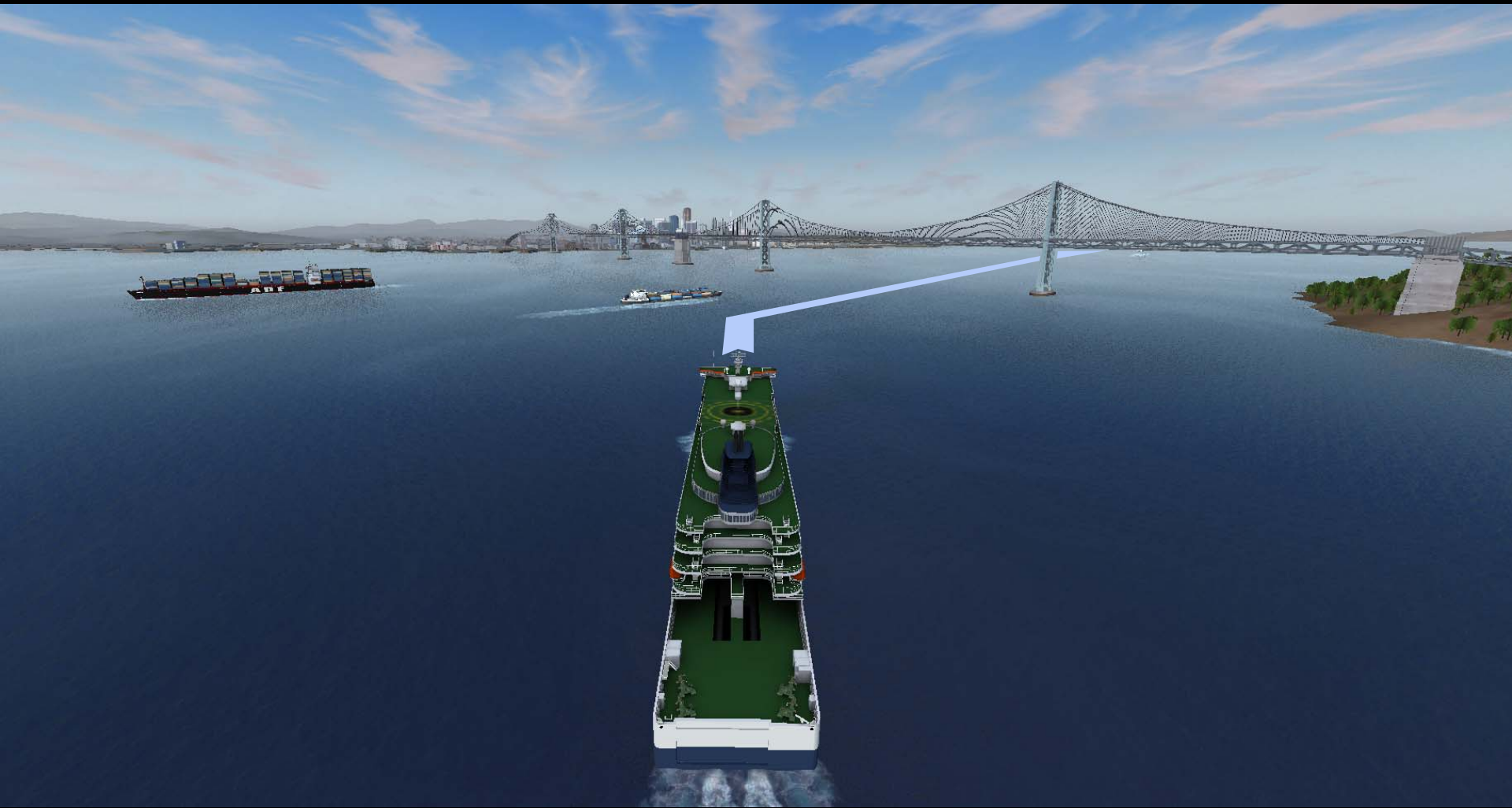
CURSOR POSITION
 RANGE 0.87 NM
 T BRG 258.8°
 LAT 37°47.93 N
 LON 122°28.57 W

L-Acquire/Select target R-Cancel

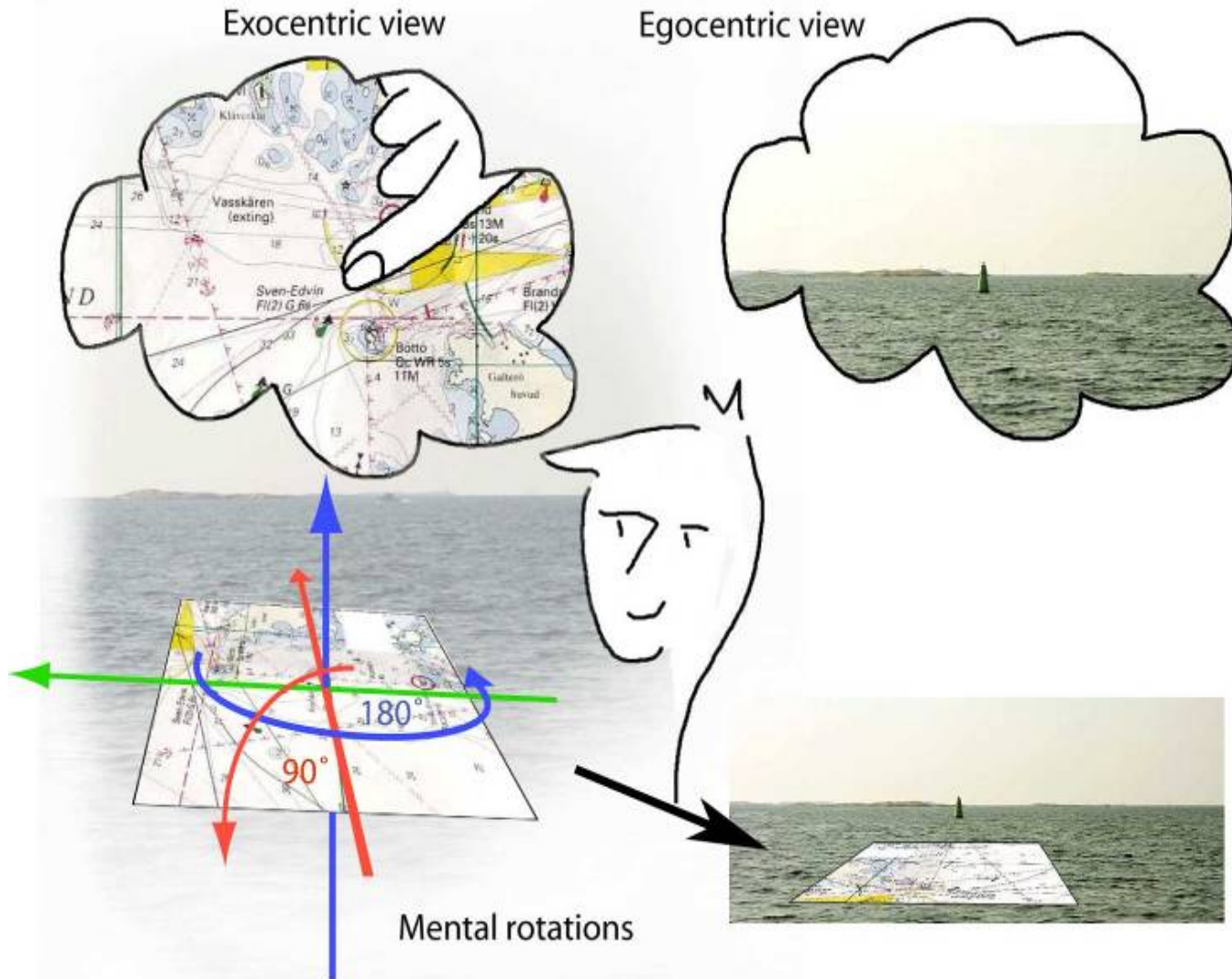


“Solving a problem simply means representing it so as to make the solution transparent.”

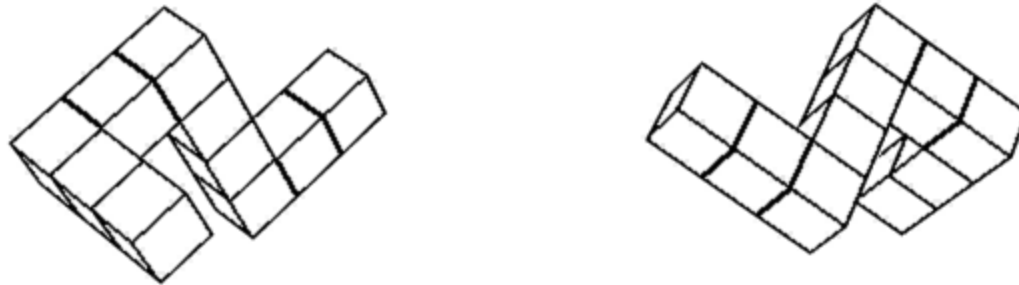
(Simon, 1996)



Ship Simulator 2008

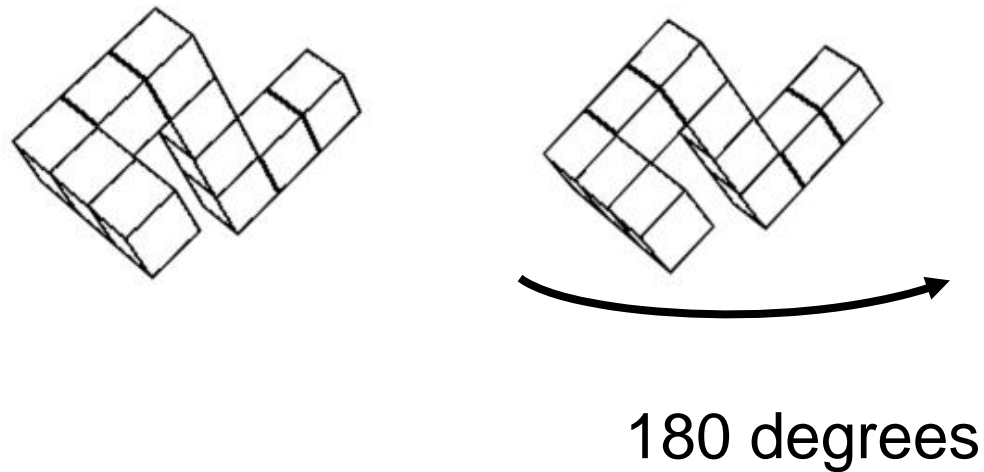


Mental Rotations



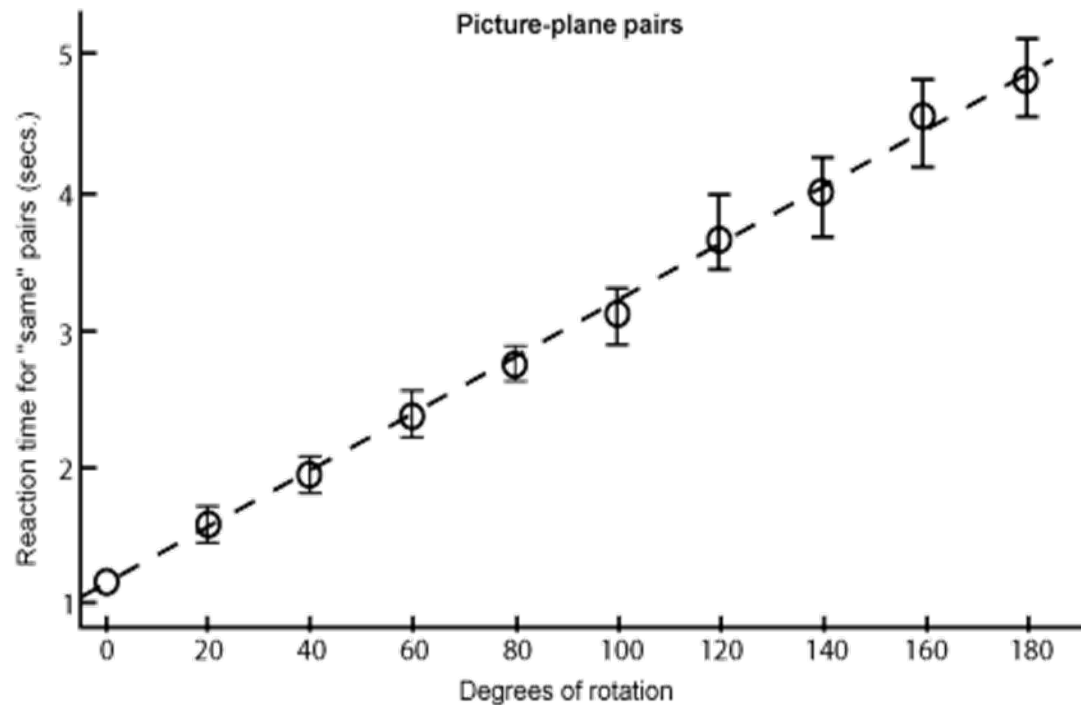
Shepard, R. N., & Metzler, J. (1971). Mental rotation of three-dimensional objects. *Science*, 171, 701-703.

Mental Rotations

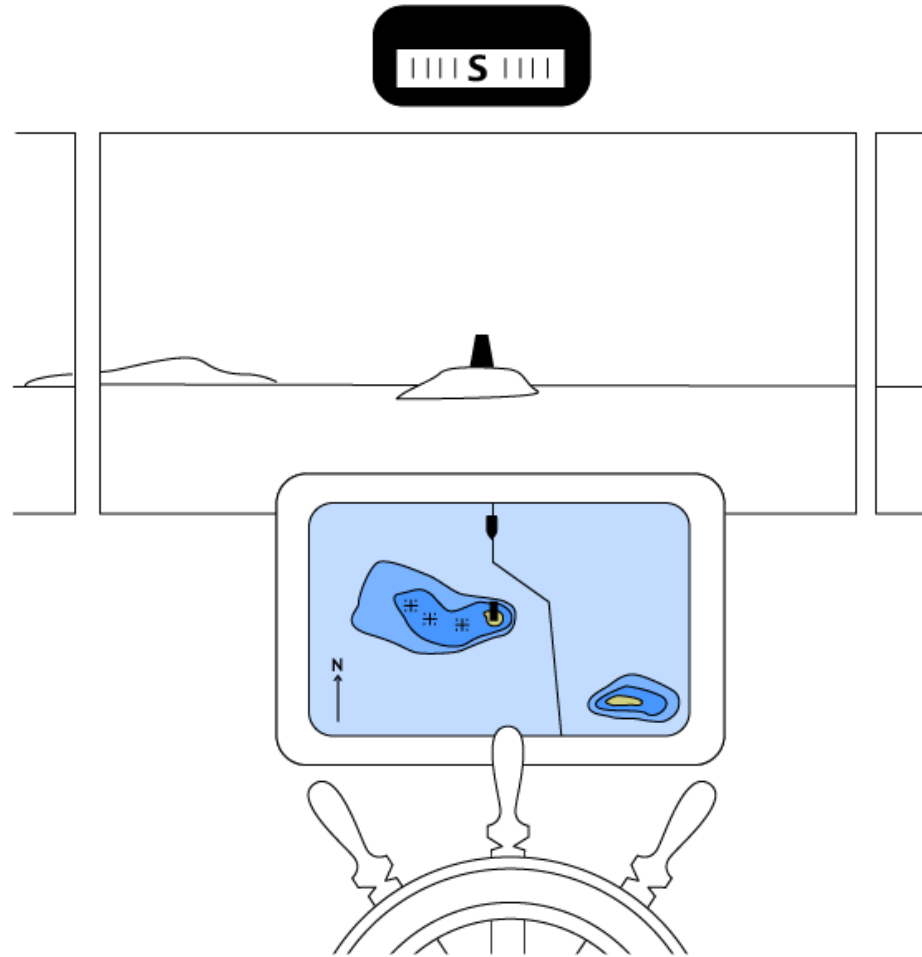


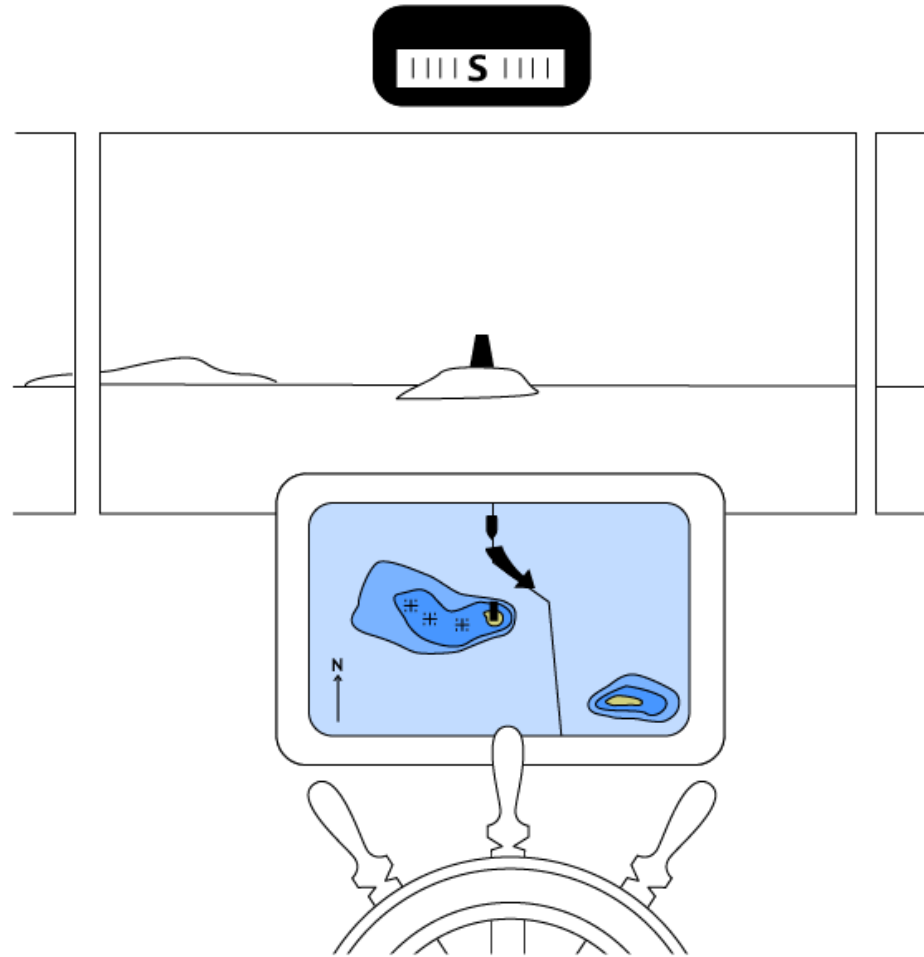
Shepard, R. N., & Metzler, J. (1971). Mental rotation of three-dimensional objects. *Science*, 171, 701-703.

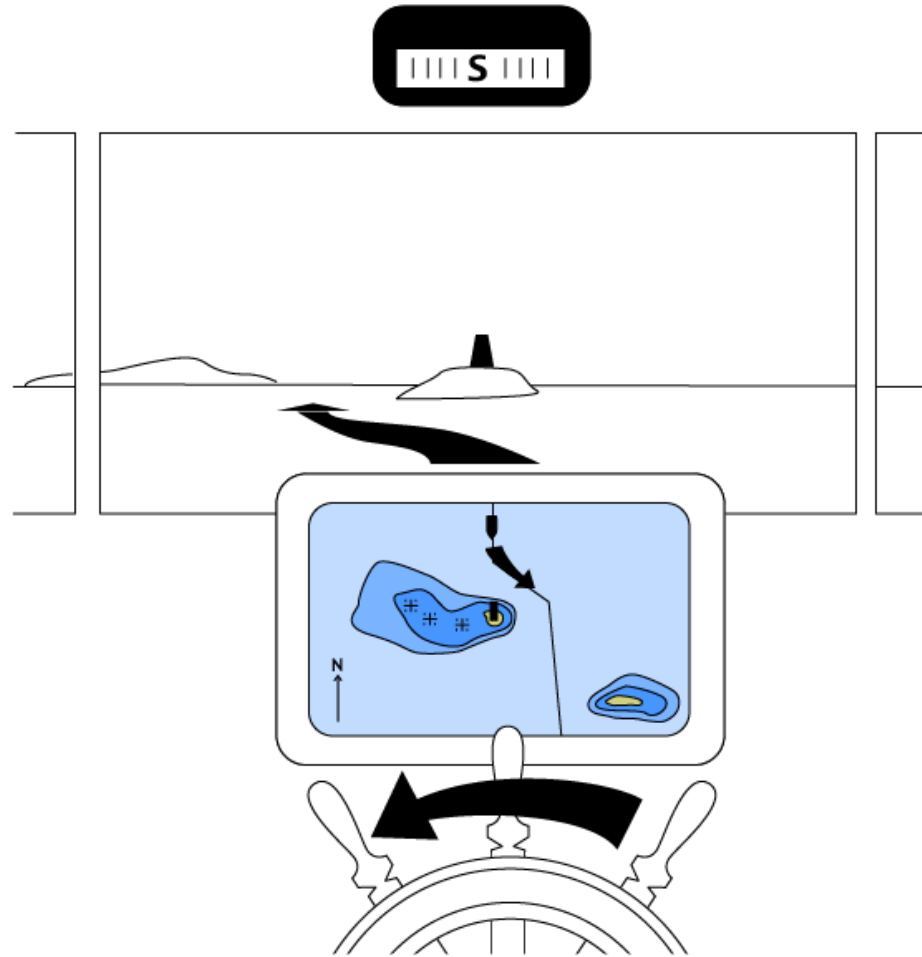
Mental Rotations

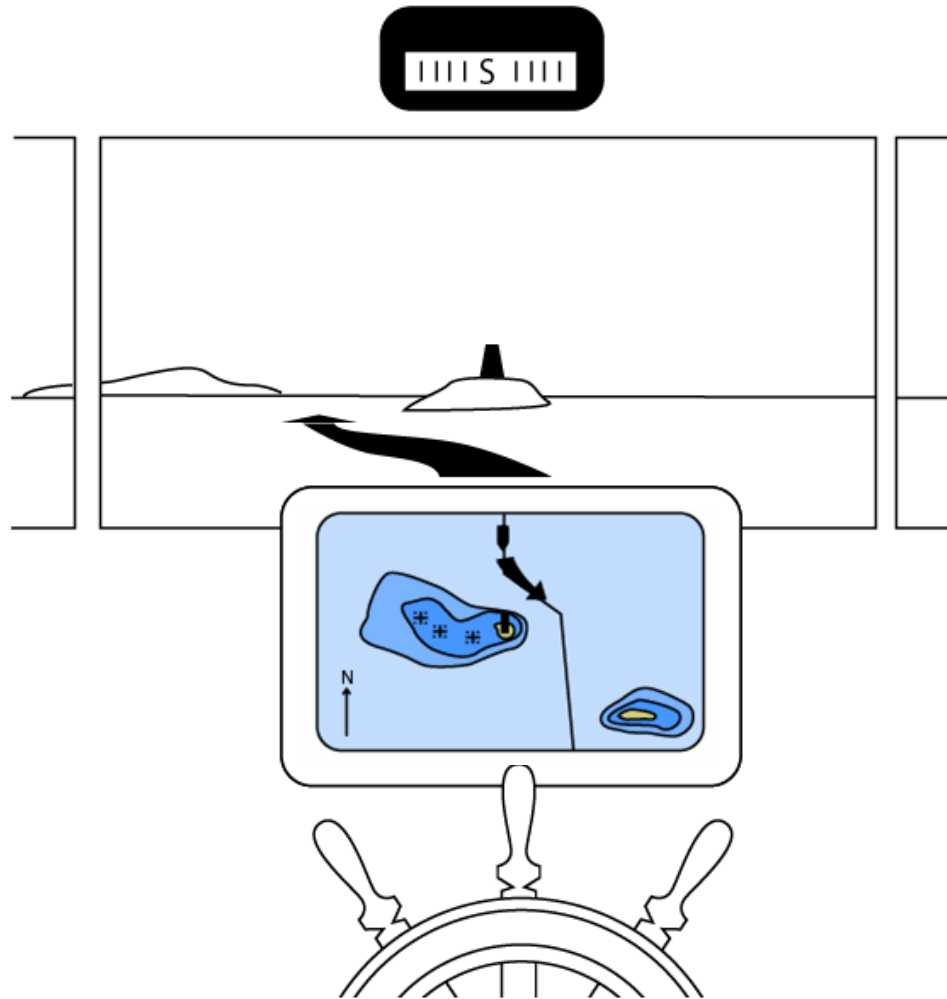


Shepard, R. N., & Metzler, J. (1971). Mental rotation of three-dimensional objects. *Science*, 171, 701-703.













Africa in its canonical orientation

Enterprises navigating in high speed generally use maps head-up.



Fighter airplanes and helicopters



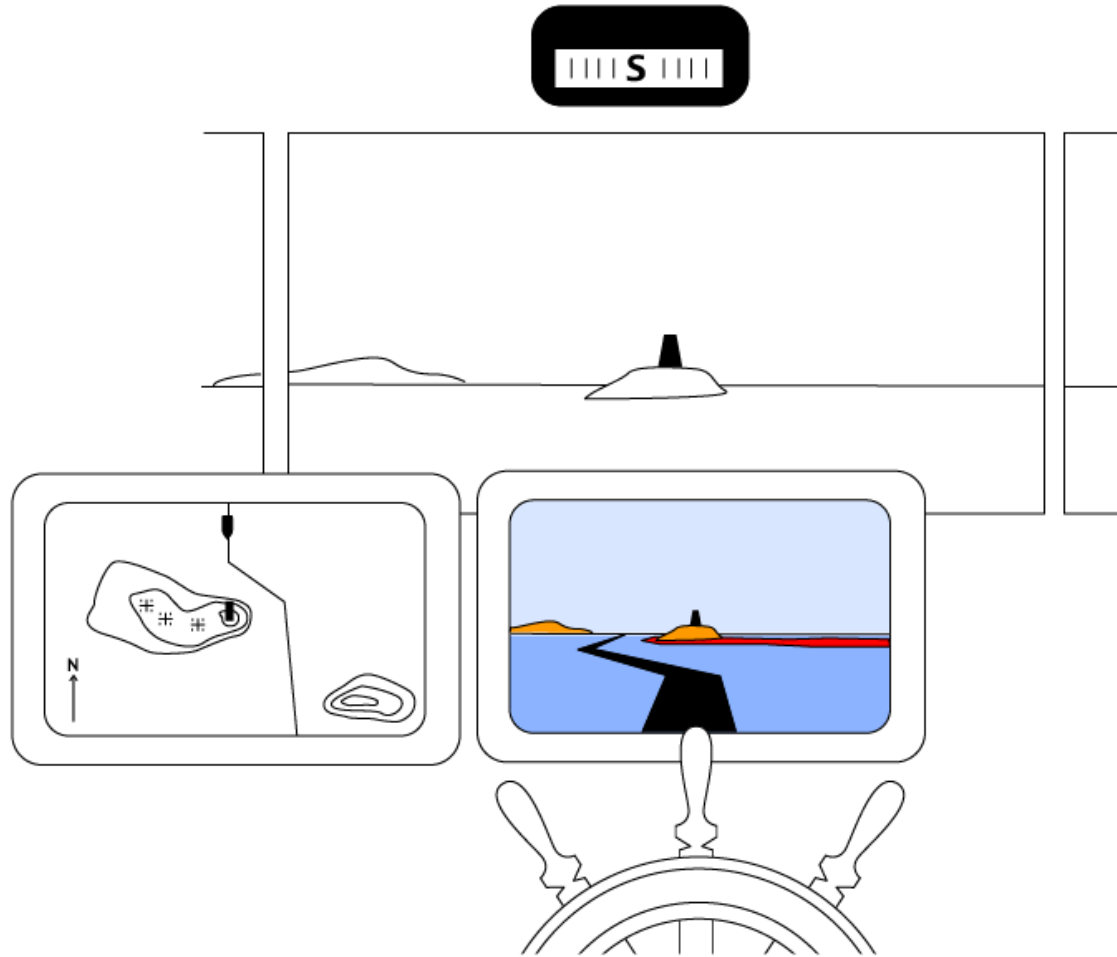
Rally and orienteering





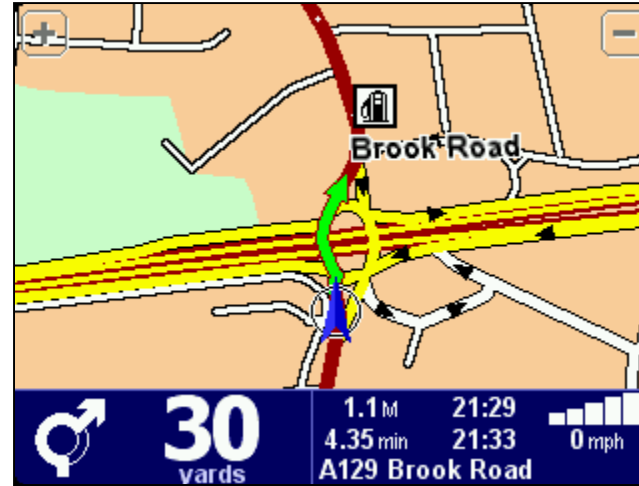


HMS Altair

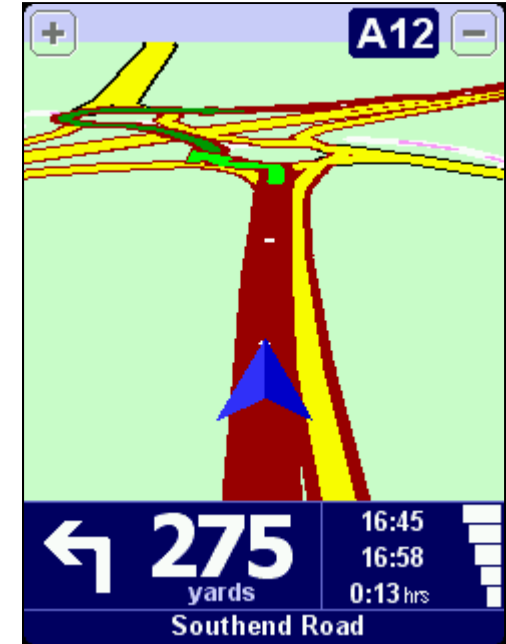




North-up mode



Head-up mode

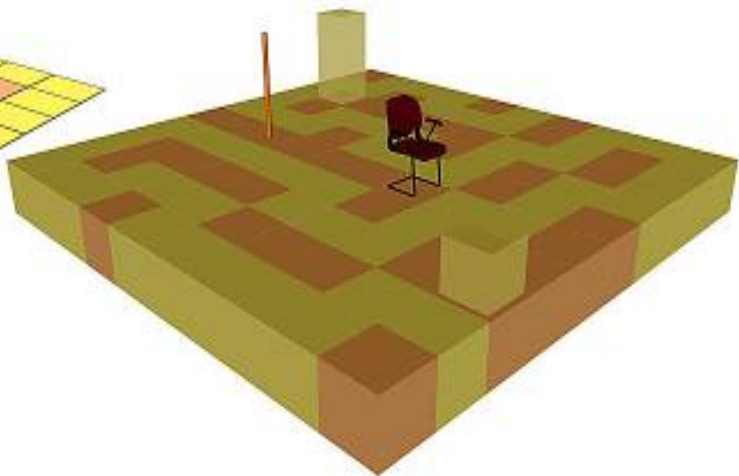
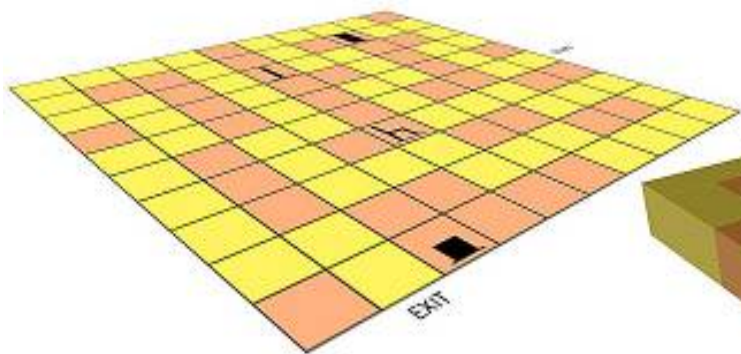
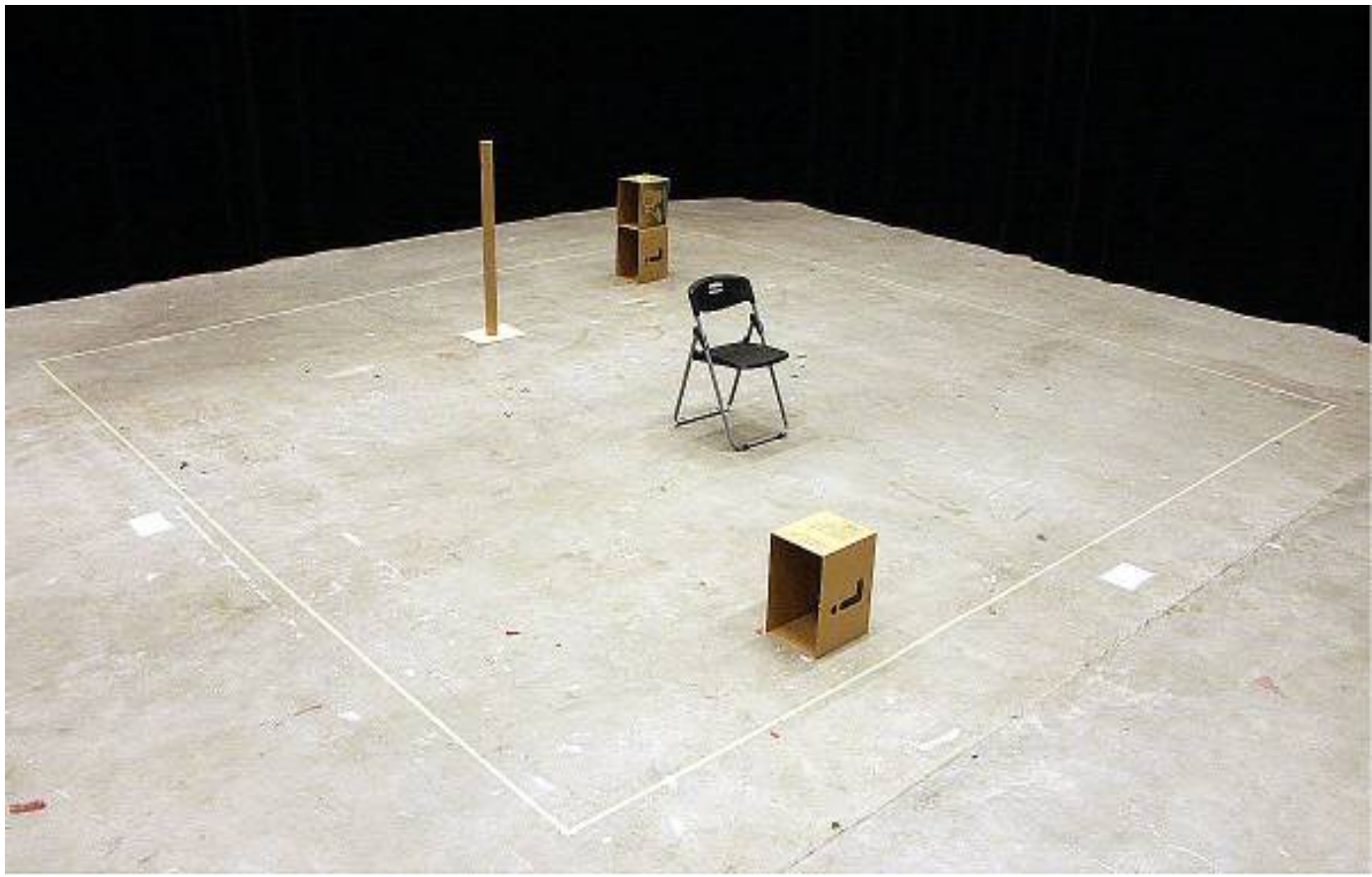


3-D egocentric mode



TomTom Navigator
HP Edition

Experimental results



Two studies

The University
group

45 participants

Age: 16 - 63

21 women

24 men

The Bridge
Officer group

30 participants

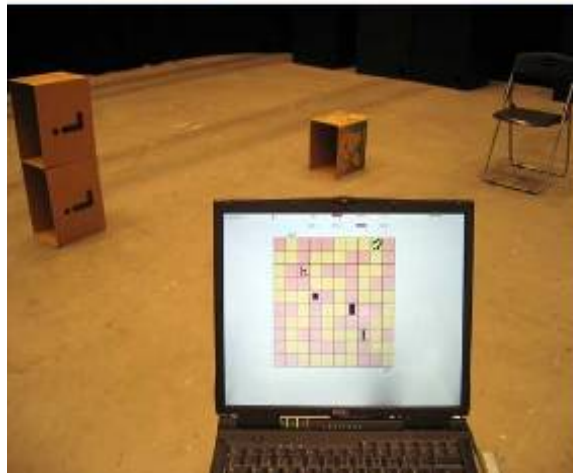
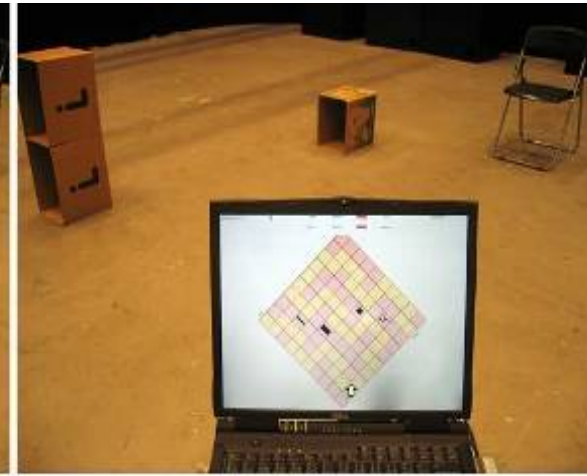
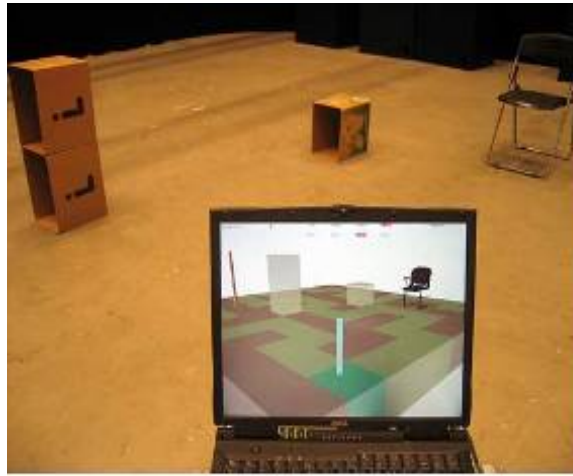
Age: 22 – 54, all men

18 combat boat drivers,

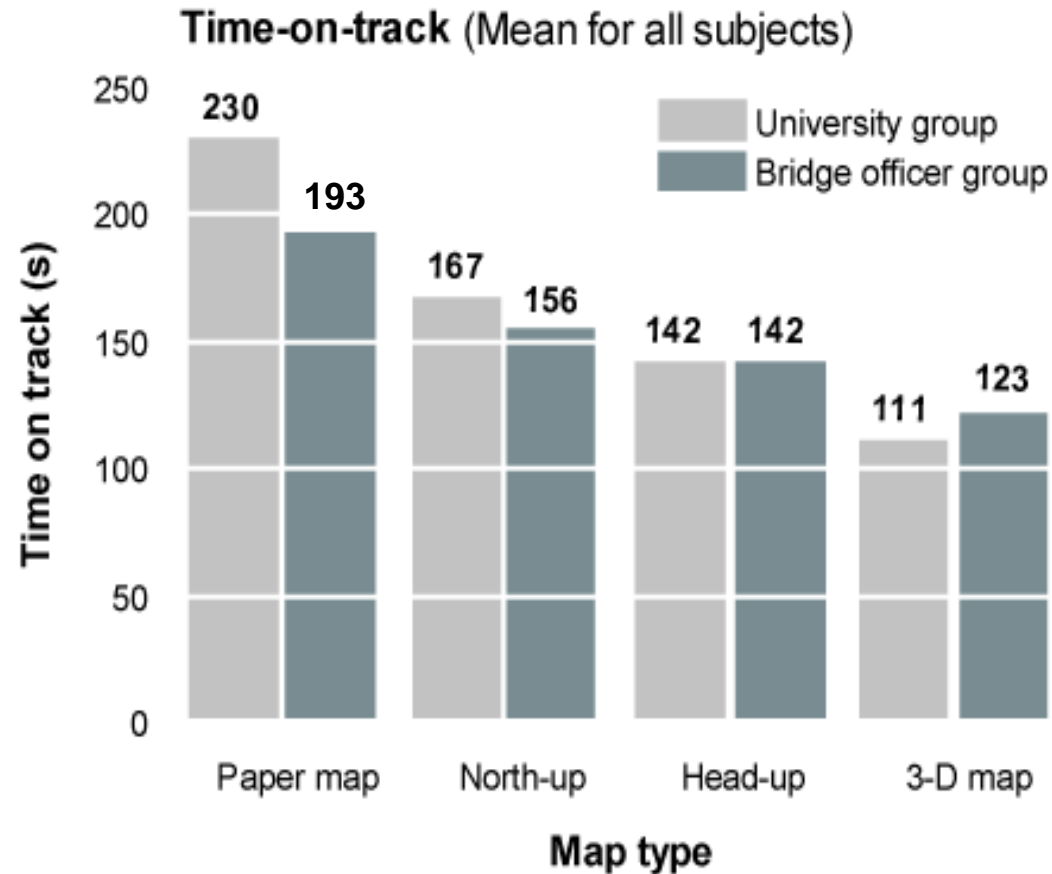
6 Experienced, active

bridge crew members

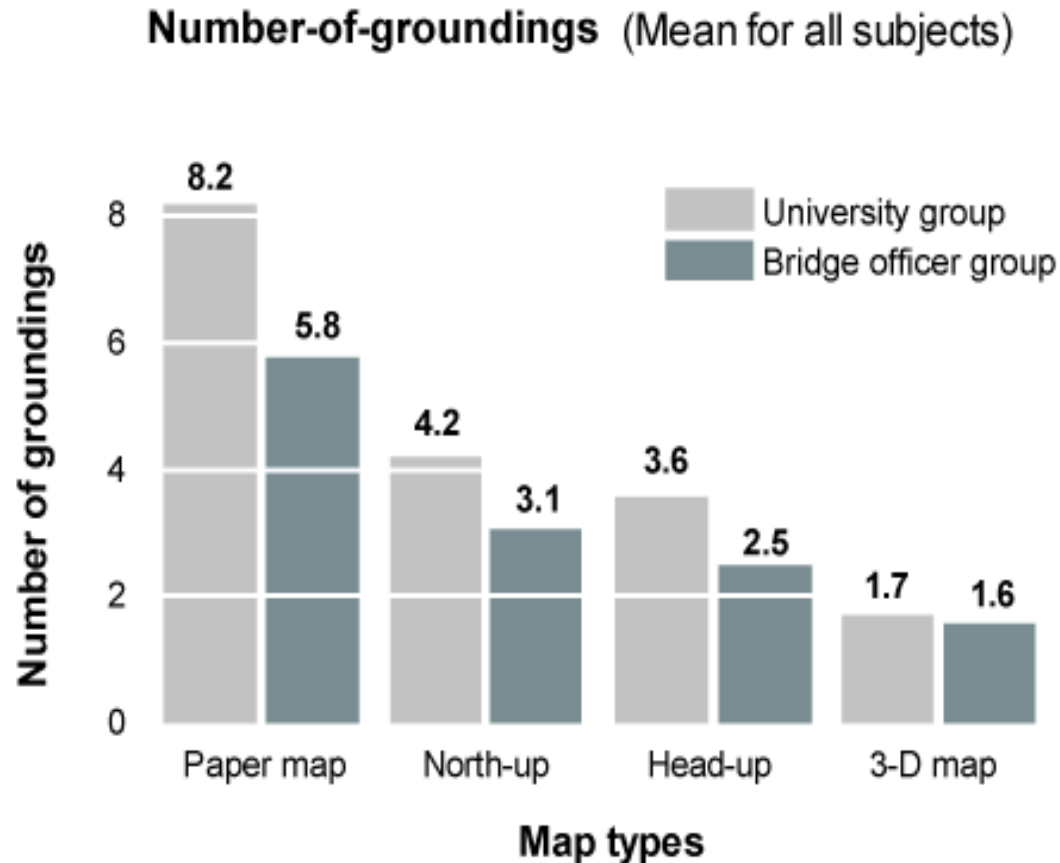
6 Cadets



Independent variables	Dependent variables
Map types (Paper, North-up, Head-up, 3-D)	Time on track
Gender	Number of groundings
Age	Subjective ranking of user-friendliness
Navigational experience	Score on figure rotation test
Self taxed sense of direction	

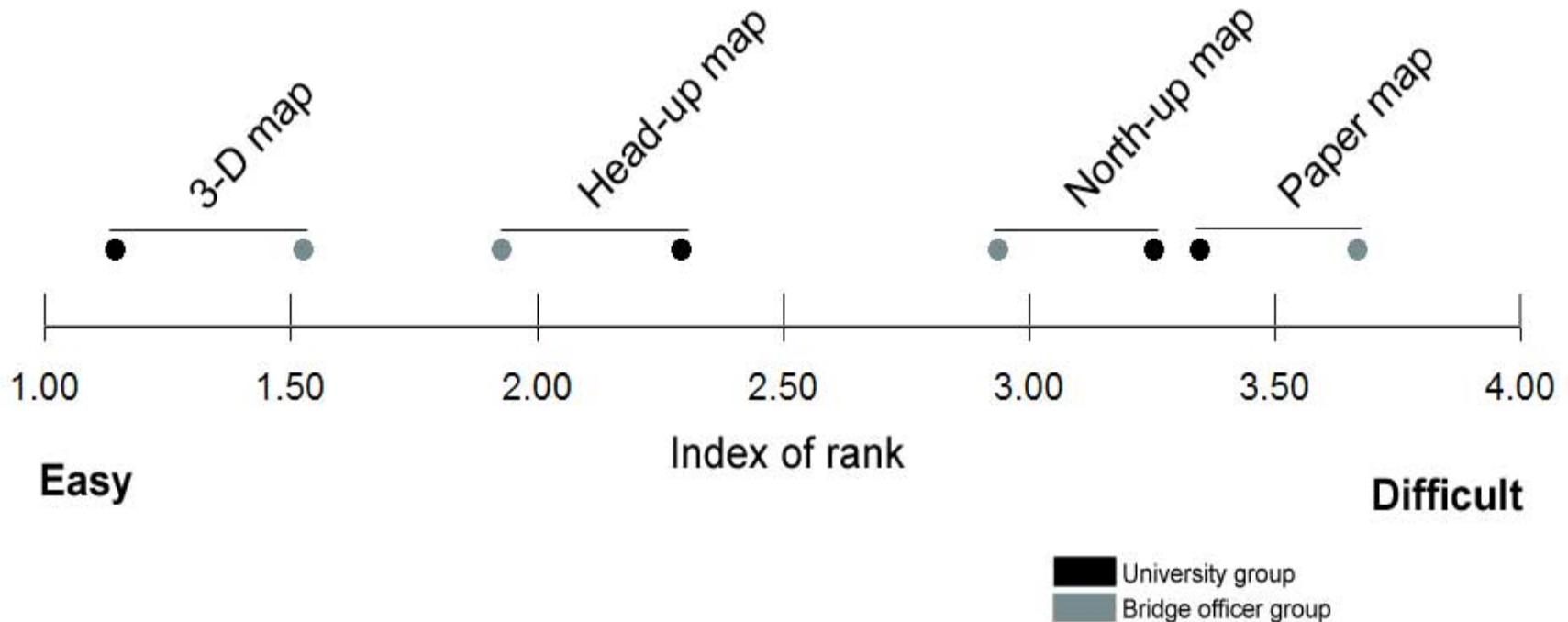


Prison, J., & Porathe, T. (2007). Navigation with 2-D and 3-D Maps: A Comparative Study with Maritime Personnel. *Proceedings of the 39th Nordic Ergonomics Society Conference*, 1-3 October 2007.



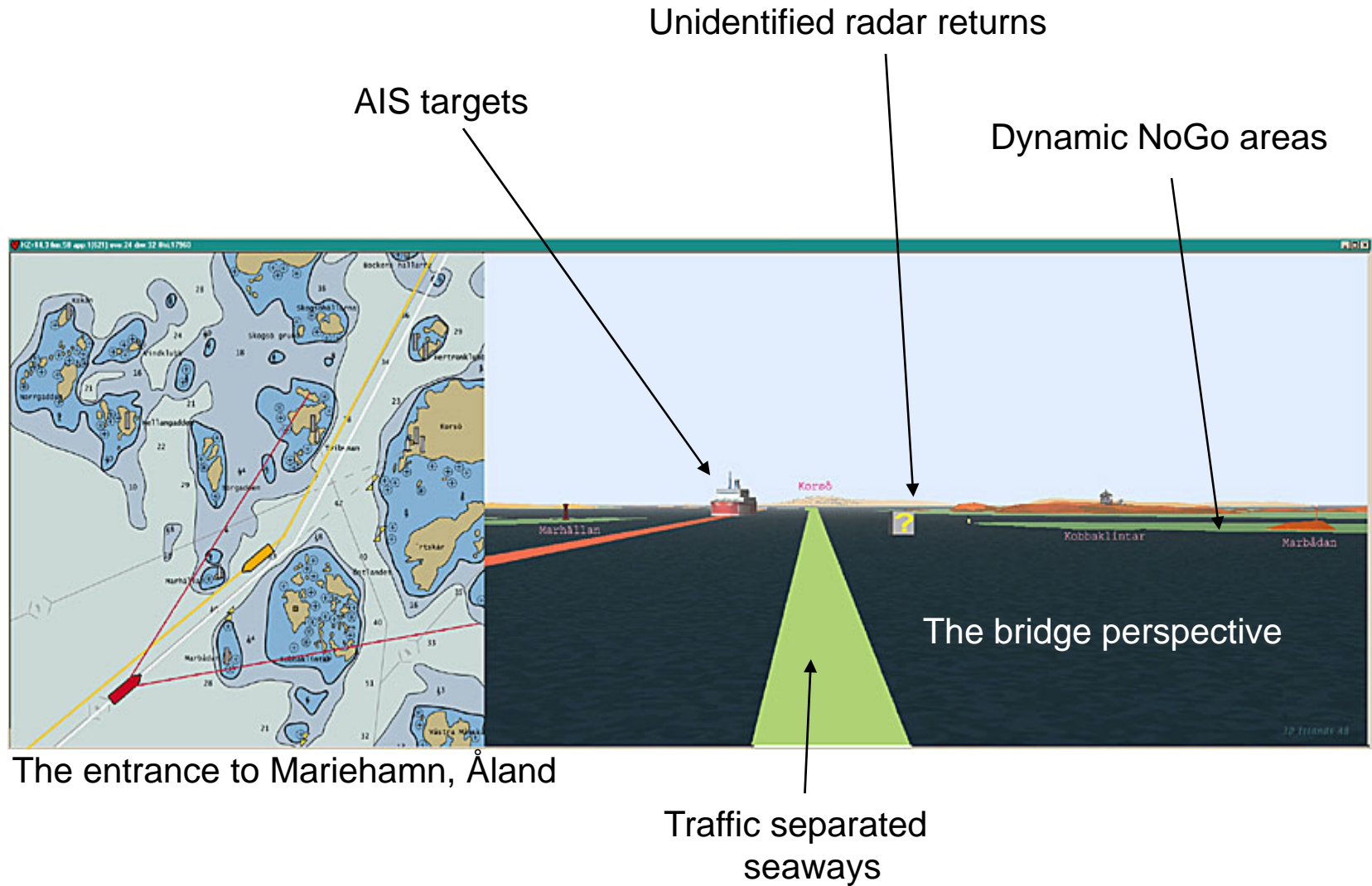
Prison, J., & Porathe, T. (2007). Navigation with 2-D and 3-D Maps: A Comparative Study with Maritime Personnel. *Proceedings of the 39th Nordic Ergonomics Society Conference*, 1-3 October 2007.

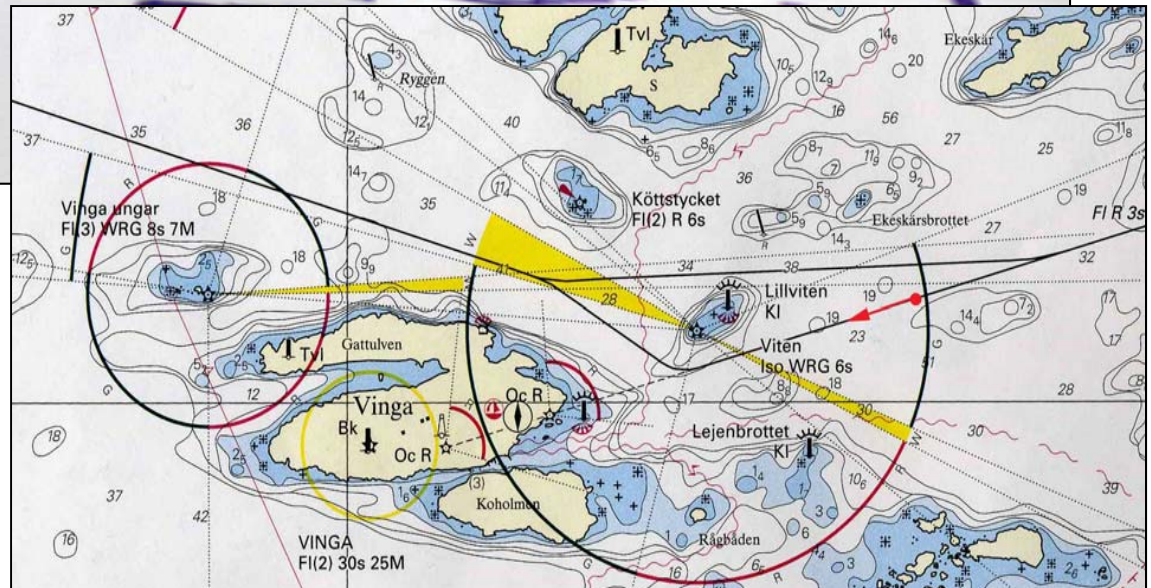
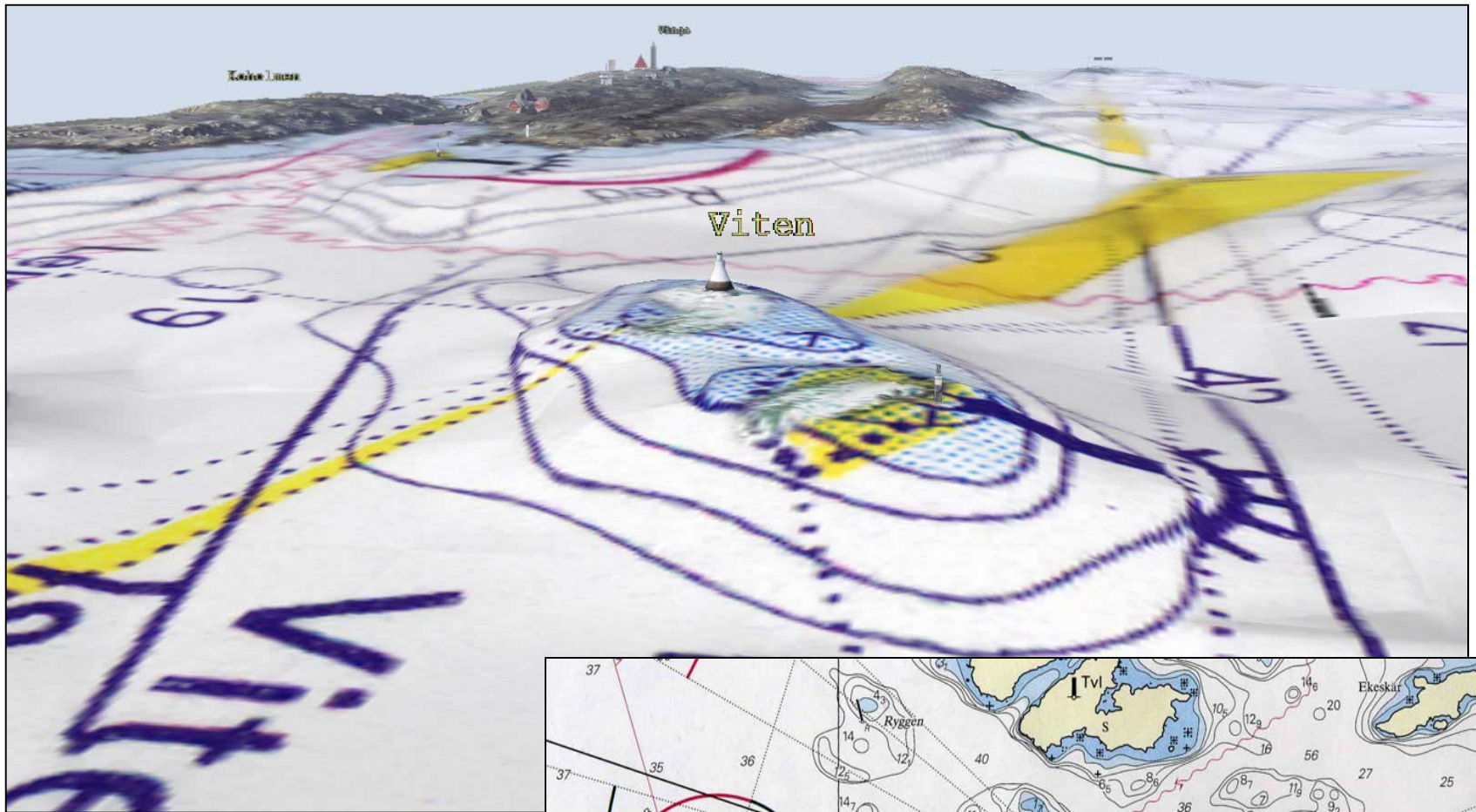
Perceived user-friendliness

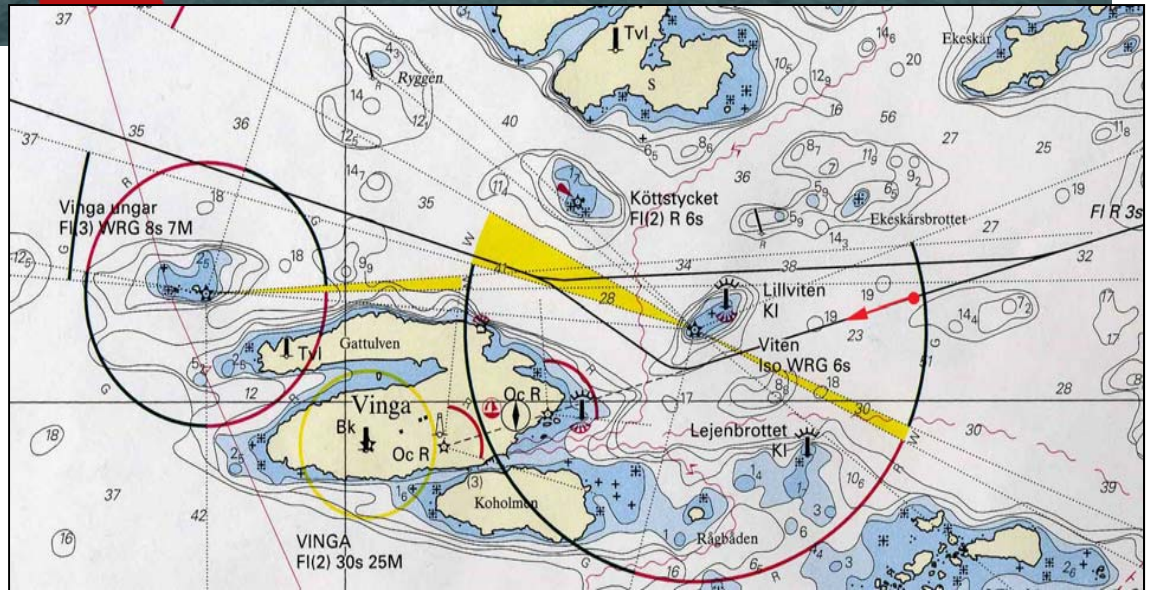
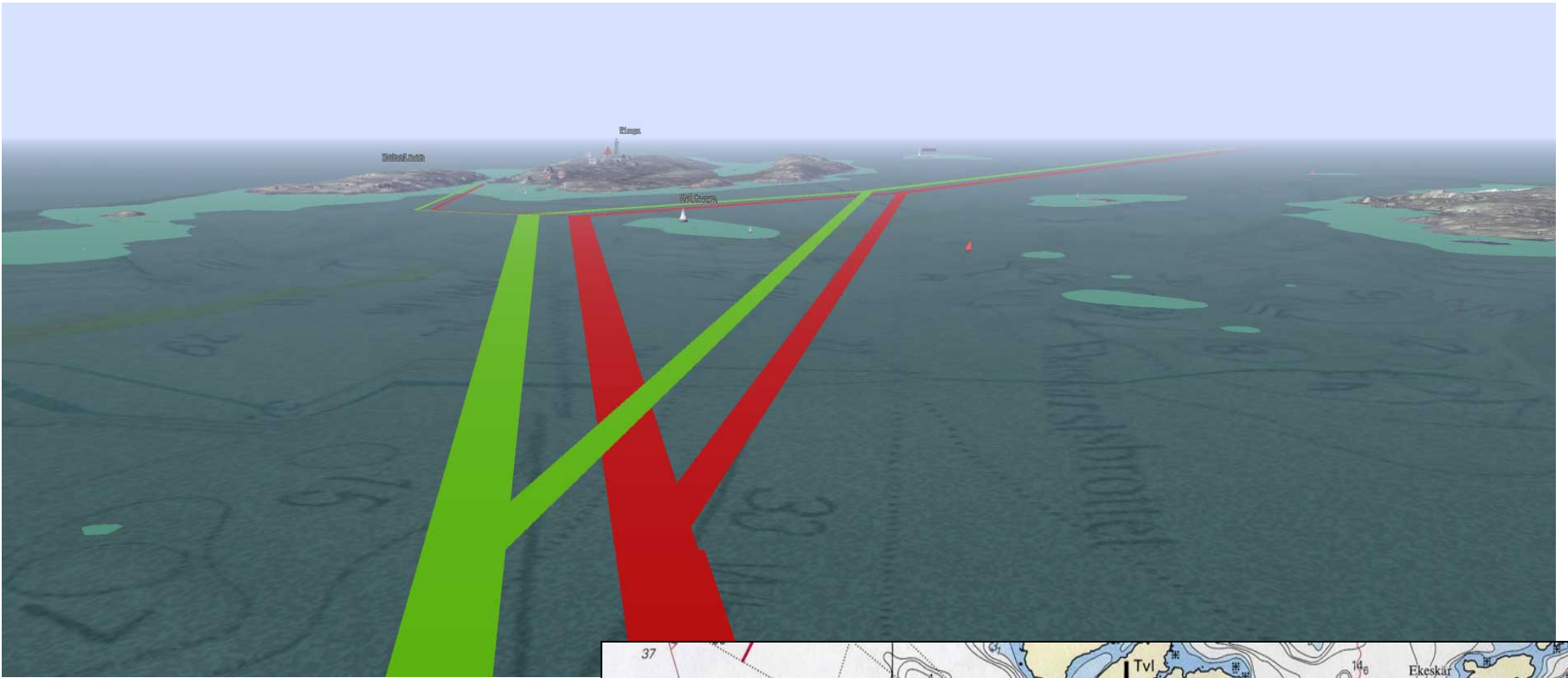


Prison, J., & Porathe, T. (2007). Navigation with 2-D and 3-D Maps: A Comparative Study with Maritime Personnel. *Proceedings of the 39th Nordic Ergonomics Society Conference*, 1-3 October 2007.

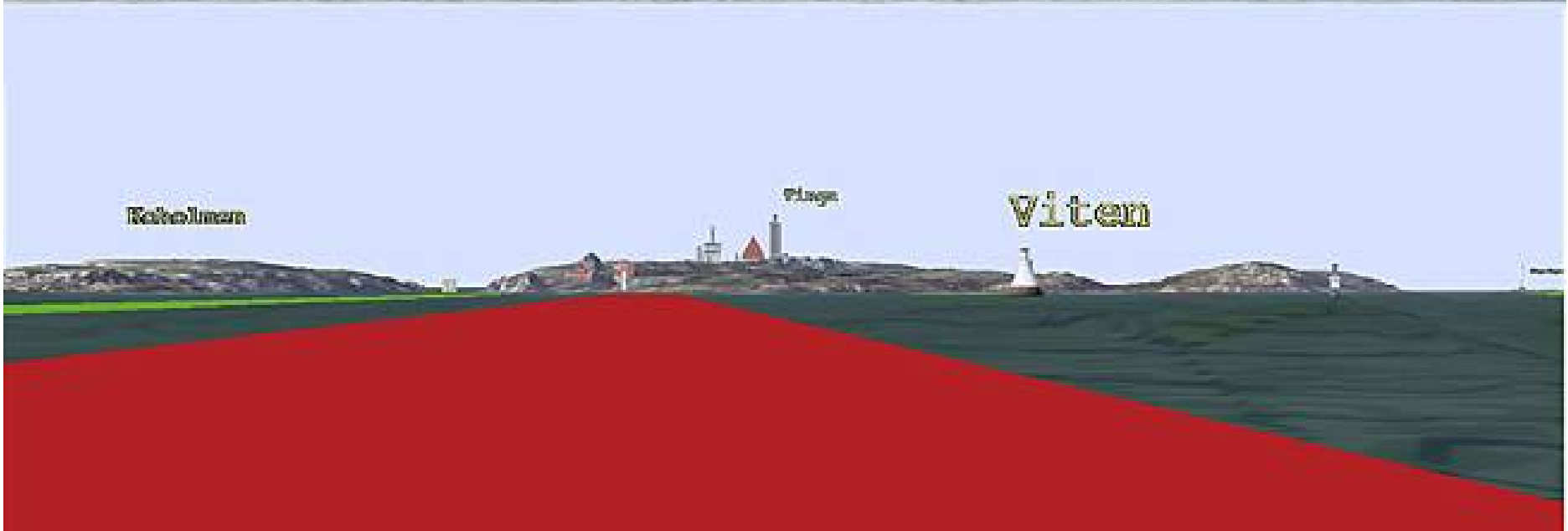
We will redo this experiment with Chinese mariners at Dalian Maritime University in November 2011.







Visual iconicity



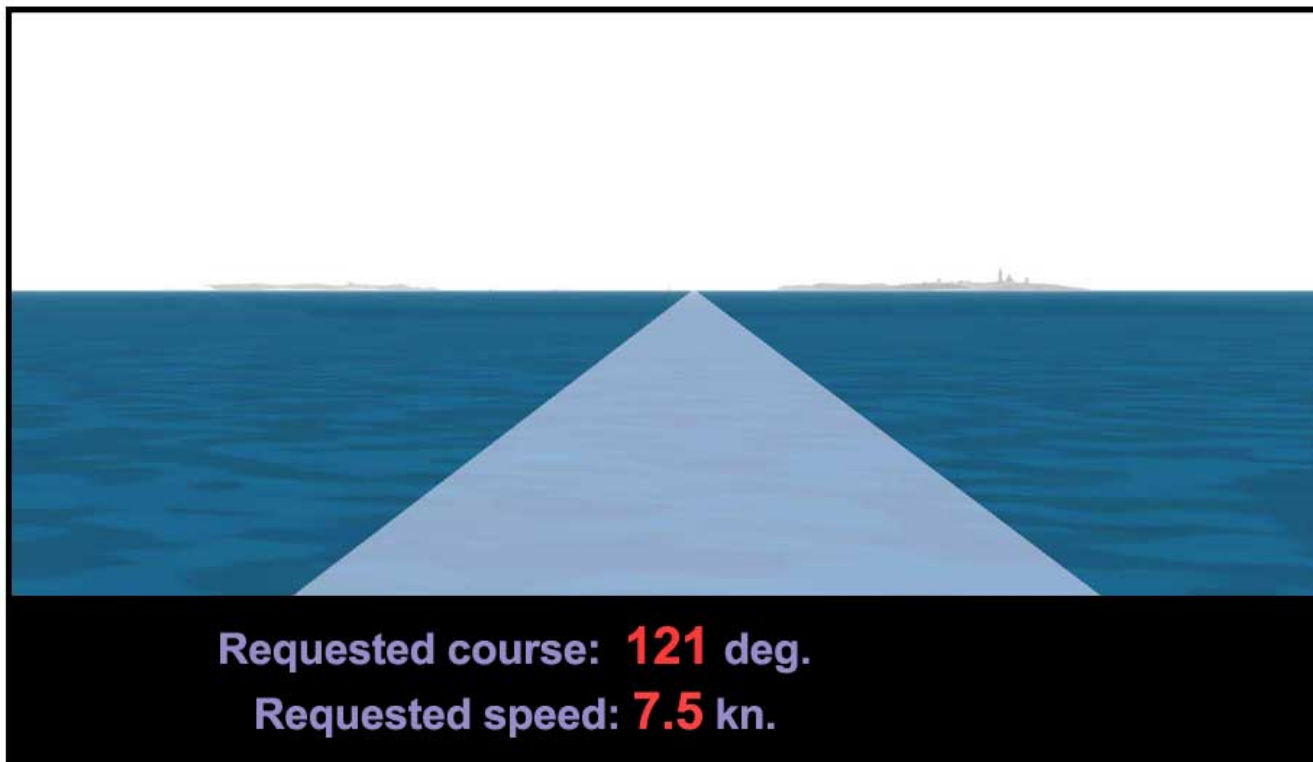


Hamnen.biz - Arrivals & Departures

Welcome to the Port of Göteborg

M/S Breeze

Please follow the white leading line to you berhing place:



Hamnen.biz - Arrivals & Departures - Windows Internet Explorer

https://www.ebusiness.portgot.se/arrdepjava/

File Edit View Favorites Tools Help

Google port got Sök 173 blockerade Stavning Skicka till port got Inställningar

Istanbul Ferryboats, Turkey Hamnen.biz - Arrivals & D...

Hamnen.biz - Arrivals & Departures

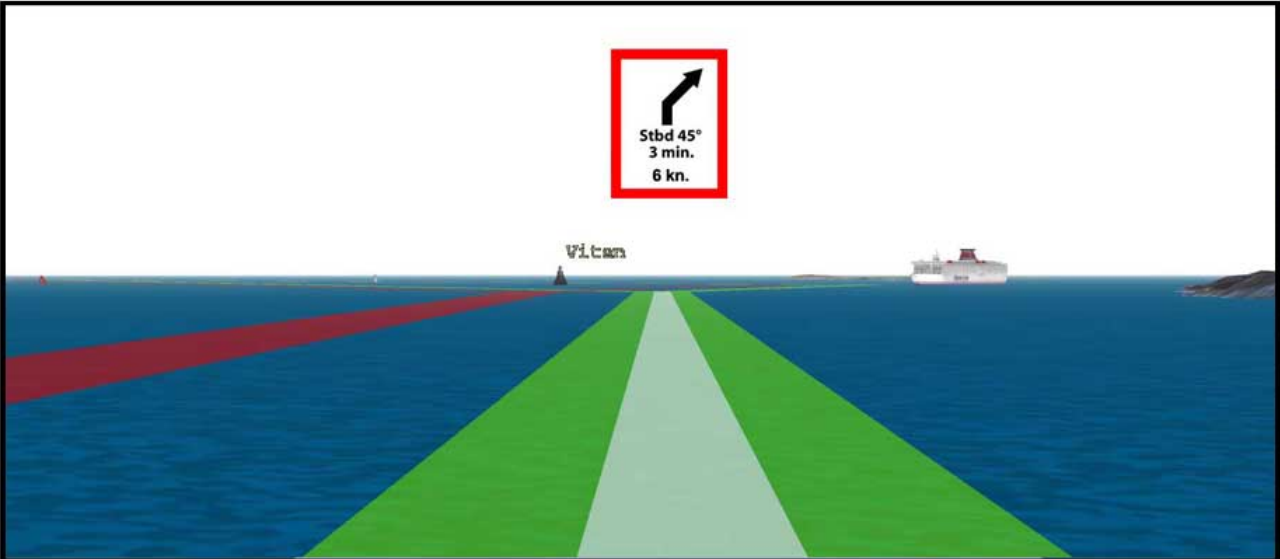
PORT OF GÖTEBORG AB

Close Window

Welcome to the Port of Göteborg

M/S Breeze

Please follow the white leading line to you berhing place:



Stbd 45°
3 min.
6 kn.

Requested course: **121** deg.
Requested speed: **7.5** kn.
Meeting with M/S Stena Germanica, Port to port, **2.5** min

Done Internet 100%

Hamnen.biz - Arrivals & Departures - Windows Internet Explorer

https://www.ebusiness.portgot.se/arrdepjava/

File Edit View Favorites Tools Help

Google port got Sök

Bokmärken 173 blockerade Stavning Skicka till port got Inställningar

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Hamnen.biz - Arrivals & Departures

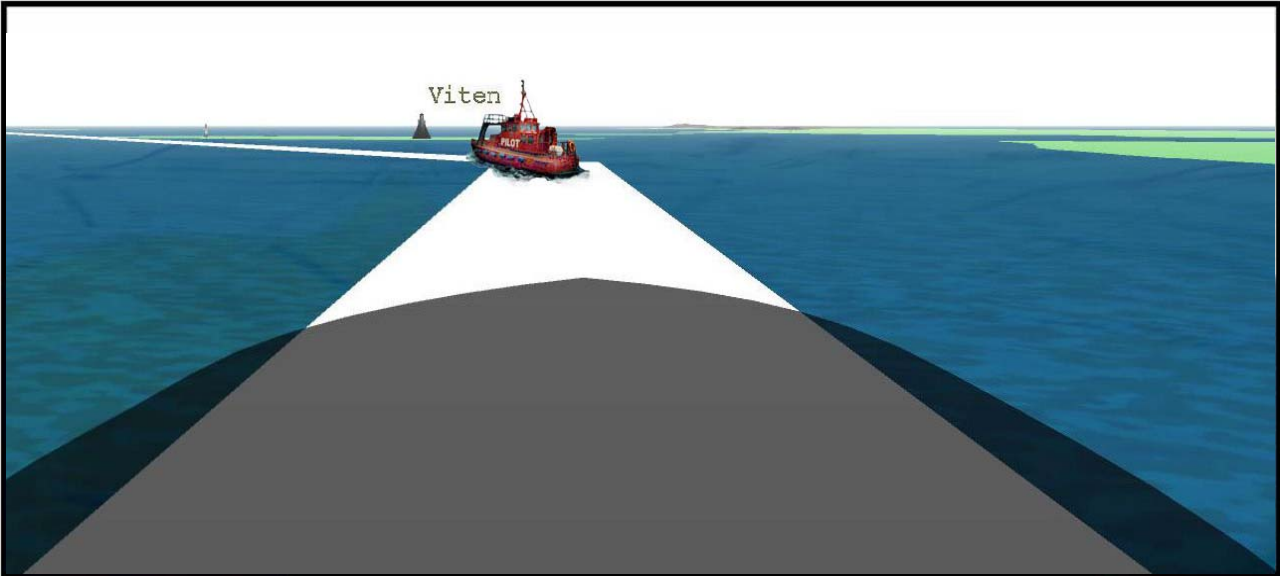
PORT OF GÖTEBORG AB

Close Window

Welcome to the Port of Göteborg

M/S Breeze

Please follow the white leading line to you berthing place:



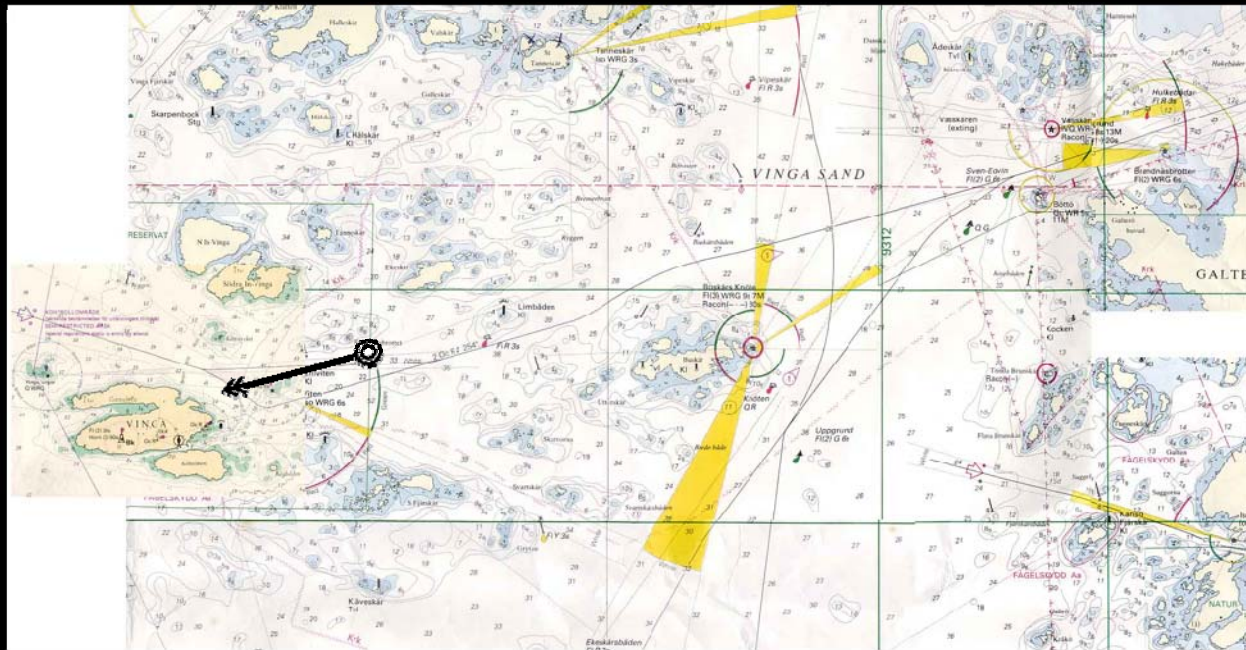
Viten

Requested course: **121** deg.
Requested speed: **7.5** kn.

Done Internet 100%

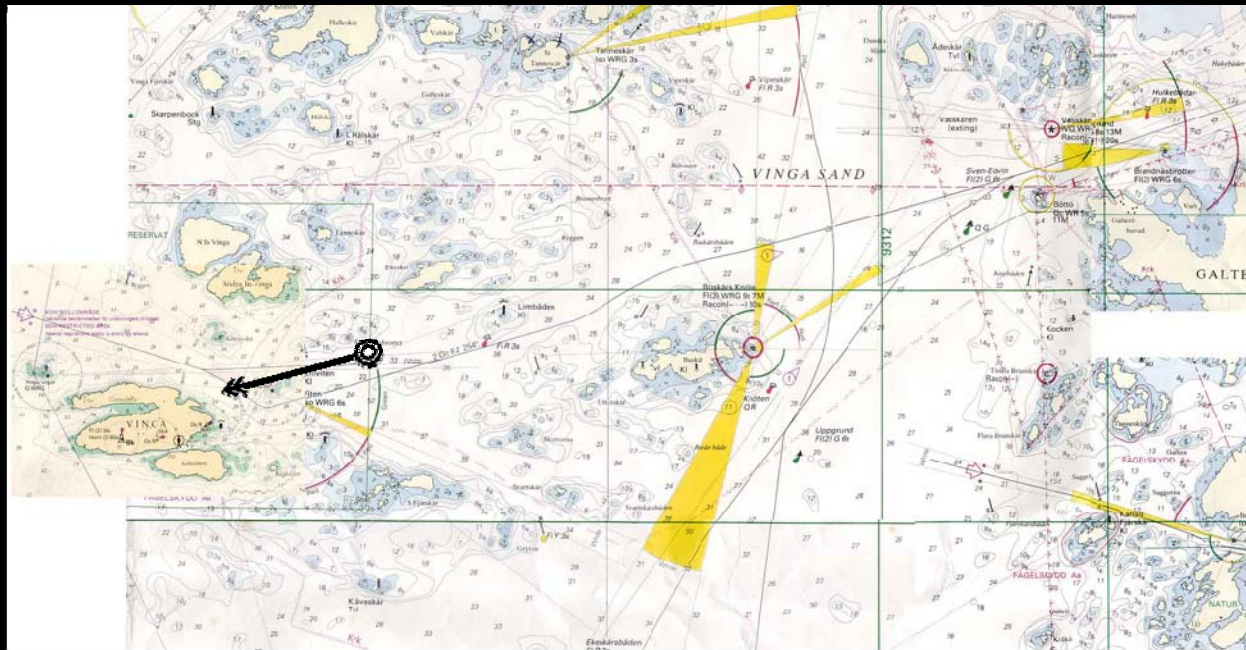


Tethered view





The 3D chart as a HUD in the windscreen







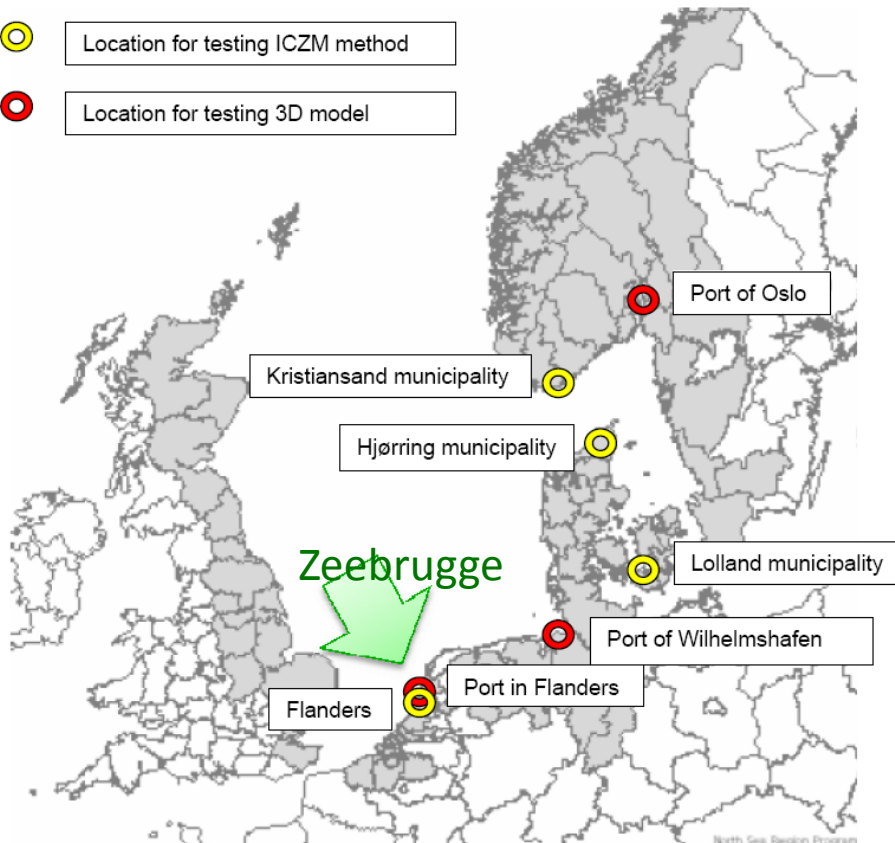
BLAST

The Interreg IVB
North Sea Region
Programme

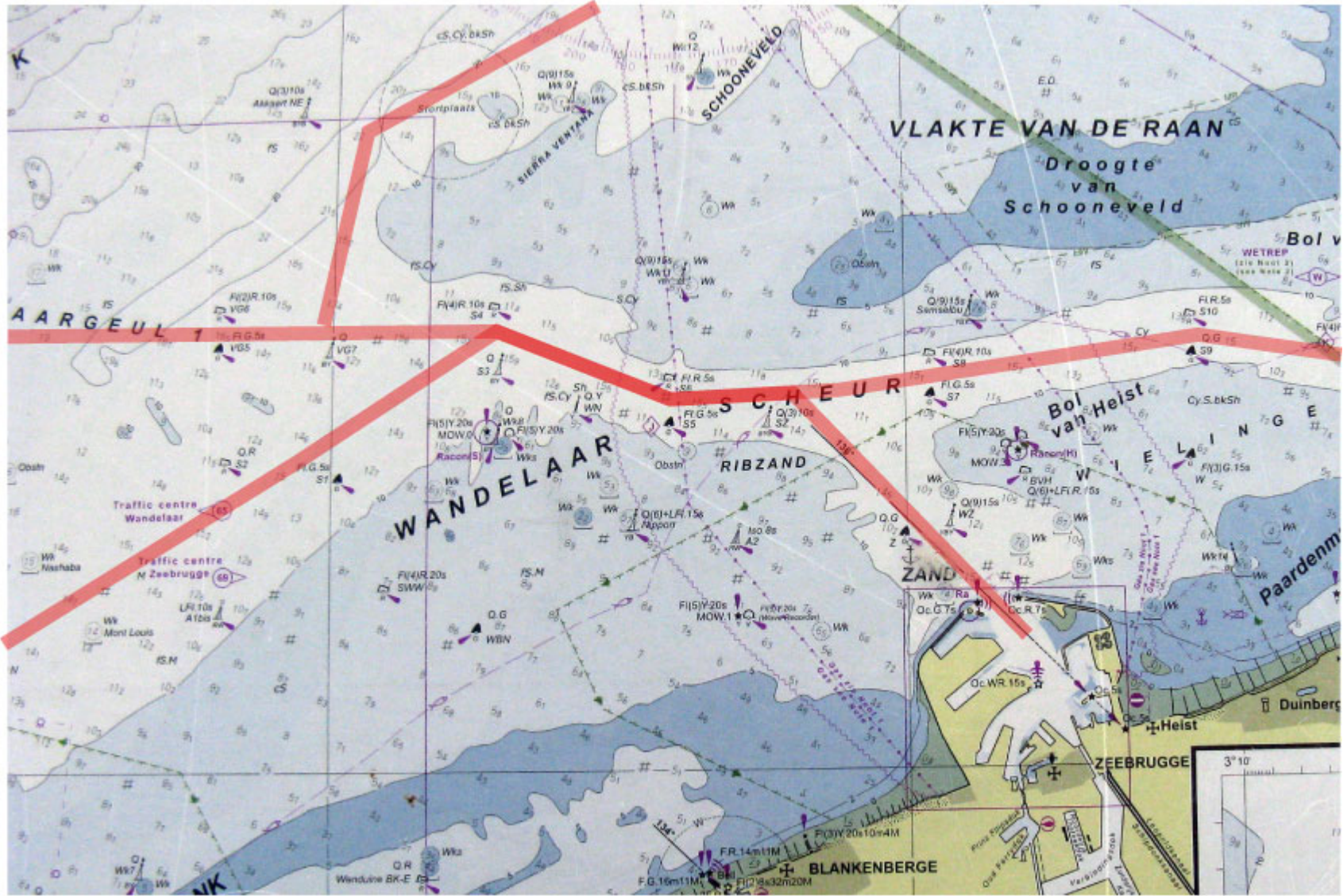



(Bringing Land And Sea Together)

-  Location for testing ICZM method
-  Location for testing 3D model



1	Lead Partner – Norwegian Hydrographic Service
2	Norwegian Coastal Administration
3	National Survey and Cadastre (KMS)
4	Danish Coastal Authority
5	Local Government Denmark
6	National Space Institute
7	Aalborg University
8	Federal Maritime & Hydrographic Agency
9	Jeppesen GmbH
10	T-Kartor AB
11	Malardalen University
12	Natural Environment Research Council
13	Seazone Solutions Ltd.
14	UK Hydrographic Office
15	Agency for Maritime and Coastal Services



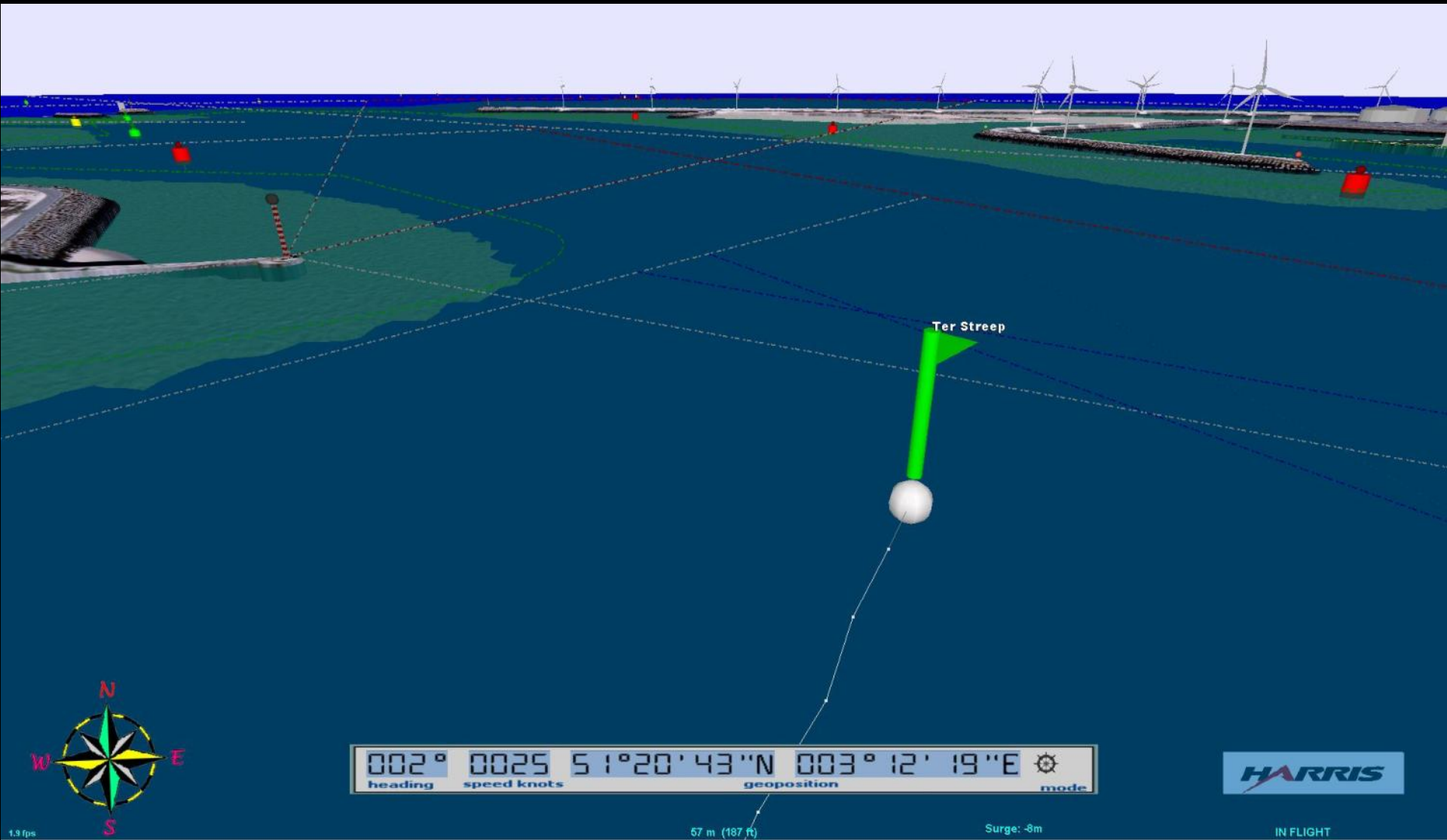


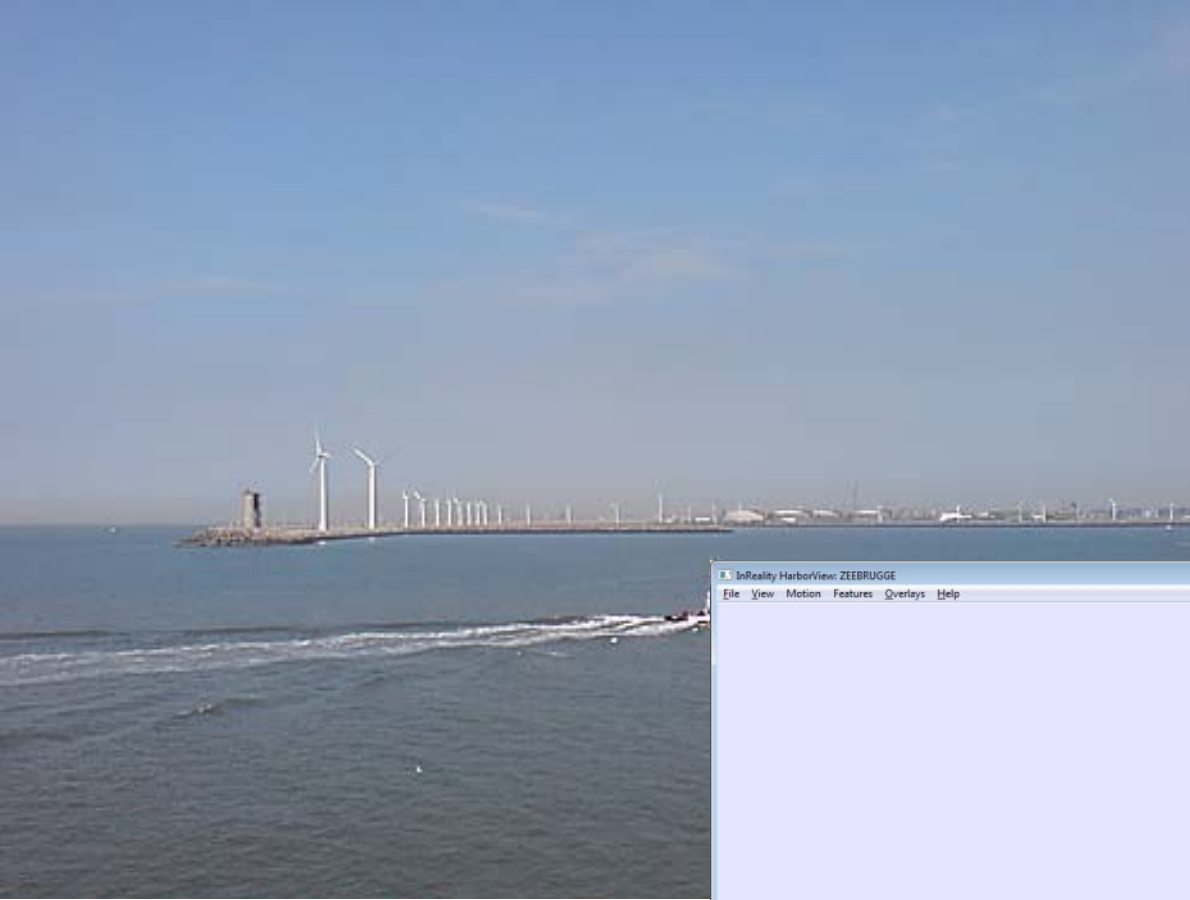
Kongsberg Polaris simulator
Antwerp maritime academy



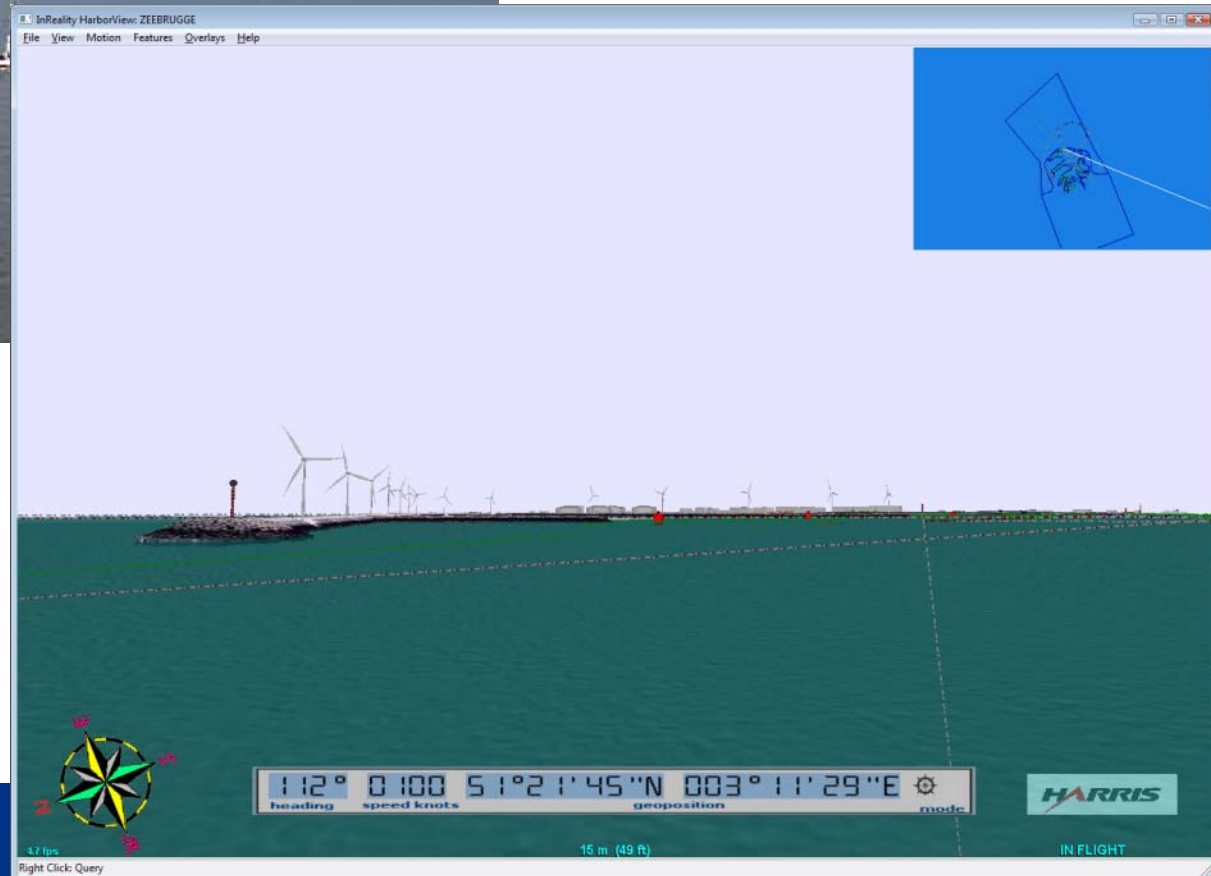
Onboard the Belgian hydrographic survey ship "Ter Streep"





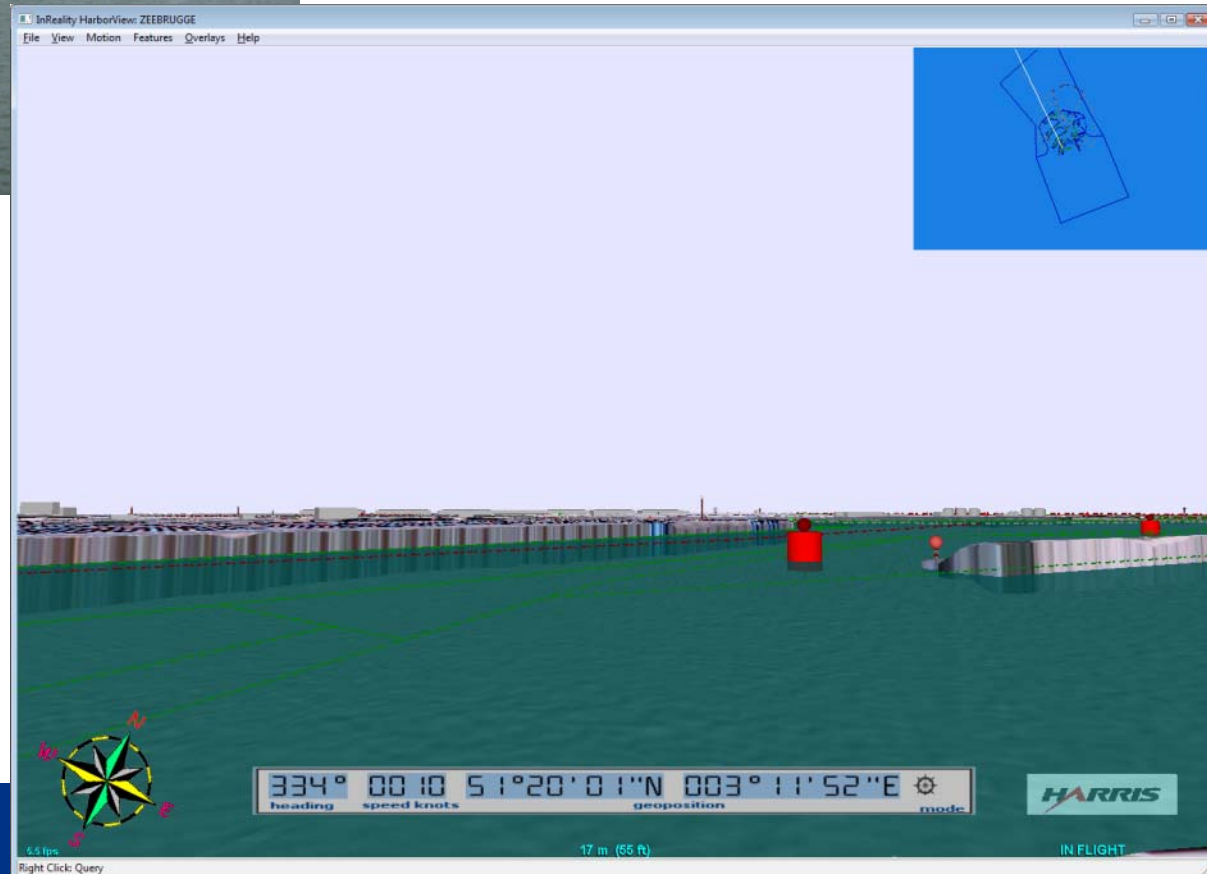


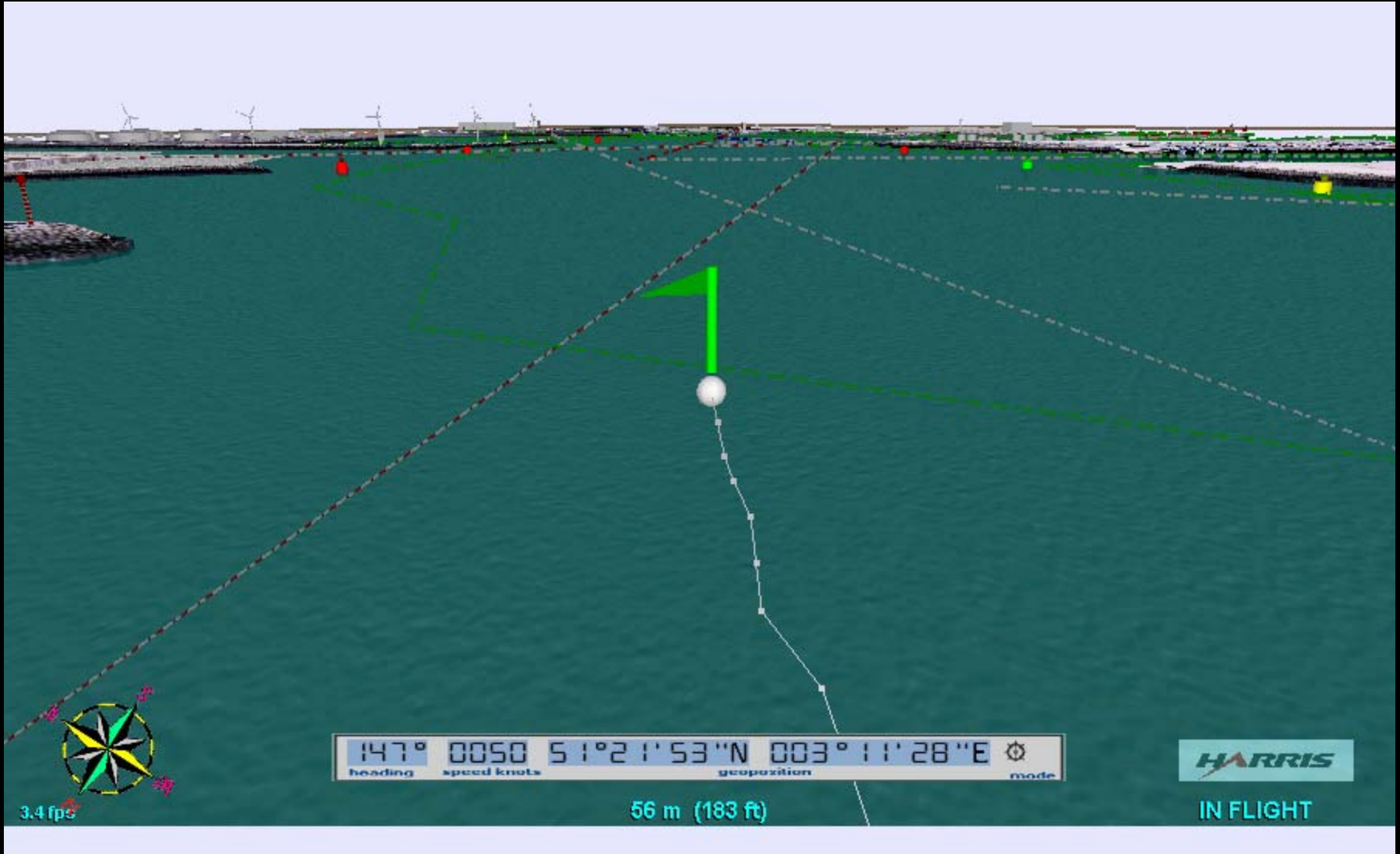
Eastern outer breakwater with wind farm

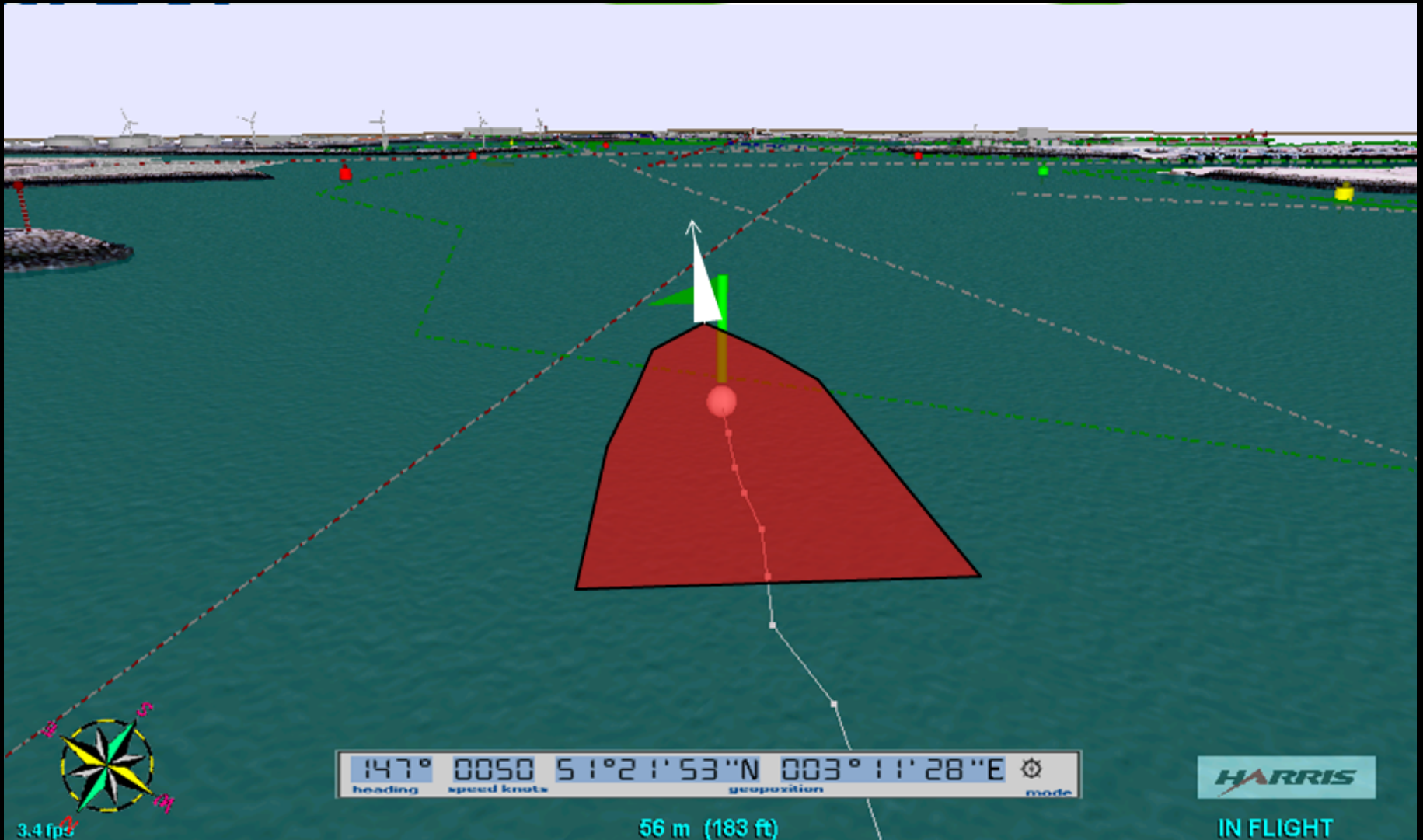




The Westhoofd quay from the corner of the military dock

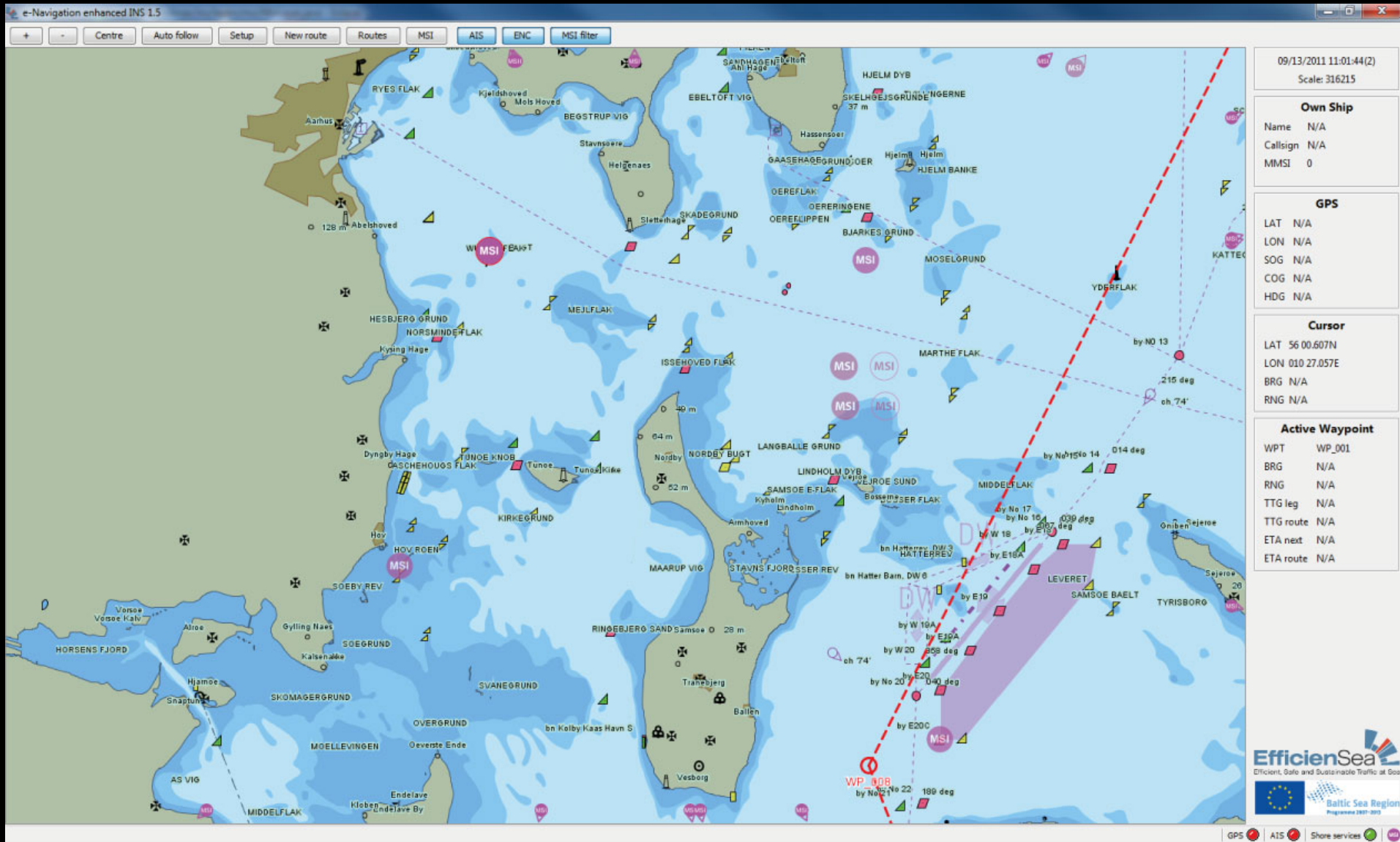






2009 - 2012

- Danish Maritime Safety Administration (project leader)
- Norwegian Coastal Administration
- Moere Romsdal County, Norway
- Swedish Maritime Administration
- Swedish Transport Agency
- SSPA, Sweden
- Chalmers University of Technology Sweden
- Maritime University Szczecin, Poland
- National Institute of Technology, Poland
- Gdynia Maritime University, Poland
- Maritime Institute in Gdansk, Poland
- Maritime Office Gdynia, Poland
- Kymenlaakso University, Finland
- Finnish Maritime Administration
- Helsinki University of Technology, Finland
- Estonian Maritime Administration



Display

Orient: North Up Browse

Range: 3 NM Rings Off

CCRP: Conning Overlays On

Heading & Speed

HDG: 127.7 ° Auto (Gyro 1)

STW: 0.2 kn Auto (Log 1)

COG: 127.7 °

SOG: 0.2 kn Auto (Log 1)

Set: 000.0 ° Drift: 0.0 kn

Position

LAT: 50°52.005' N Auto (GPS 1)

LON: 001°22.345' W

Vector & Trails

Stabil: Ground T

Vector: 6 Min

Trails: Off

Plot: Off

Predict: Off

Charts

ENC

Targets

Fusion: Off

Sleeping: All AIS

Alarms

Crossing Safety Contour

M01E001 | Normal

ENC Draught Control

Categories

Category: Standard

Basic

Symbols: Paper Chart

Areas: Plain

Text: Normal

Advanced

Light Descriptions Full Length Light Sectors

Extra Info Symbol Indicate Data Quality

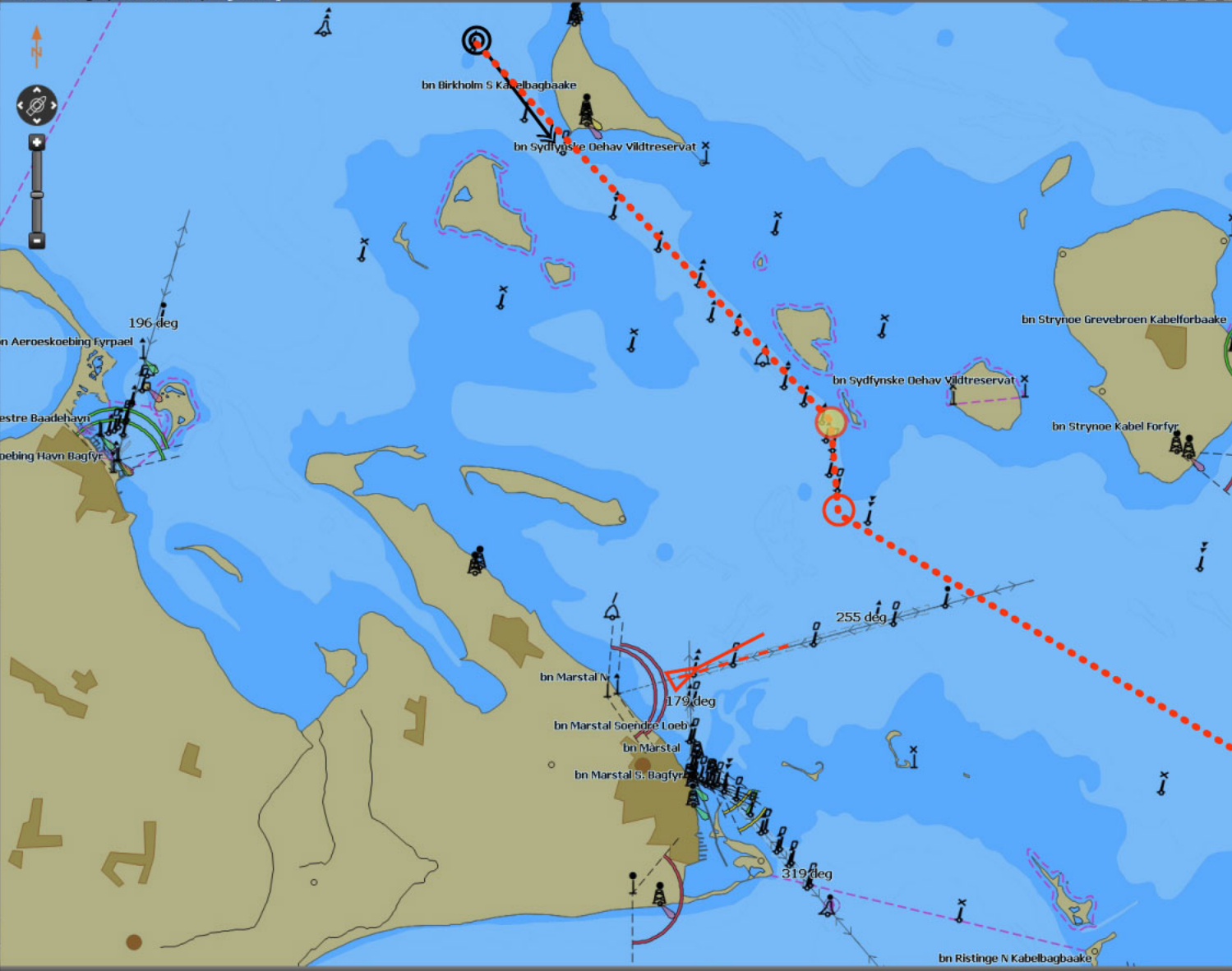
Highlight Updates: None

Conditionally Displayed Features

Date Dependent: Within Effective Dates

Scale Dependent: Within Effective Scales

Display | LOP | Nav Tools | User Symbols | Past T



Display

Orient. **North Up** ▾ Browse ▾

Range **3 NM** ▾ Rings Off

CCRP **Conning** ▾ Overlays On ▾

Heading & Speed

HDG **127.7 °** Auto (Gyro 1) ▾

STW **0.2 kn** Auto (Log 1) ▾

COG **127.7 °**

SOG **0.2 kn** Auto (Log 1) ▾

Set **000.0 °** Drift **0.0 kn**

Position

LAT **50°52.005' N** Auto (GPS 1)

LON **001°22.345' W**

Vector & Trails

Stabil. **Ground** ▾ T ▾

Vector **6 Min** ▾

Trails **Off** ▾

Plot **Off** ▾

Predict **Off** ▾

Charts

ENC ▾

Targets

Fusion **Off**

Sleeping **All AIS**

Alarms

△ Crossing Safety Contour

M01E001 | Normal

Navigation

ENC Draught Control Display Depth

Categories

Category **Standard** ▾

Basic

Symbols **Paper Chart** ▾

Areas **Plain** ▾

Text **Normal**

Advanced

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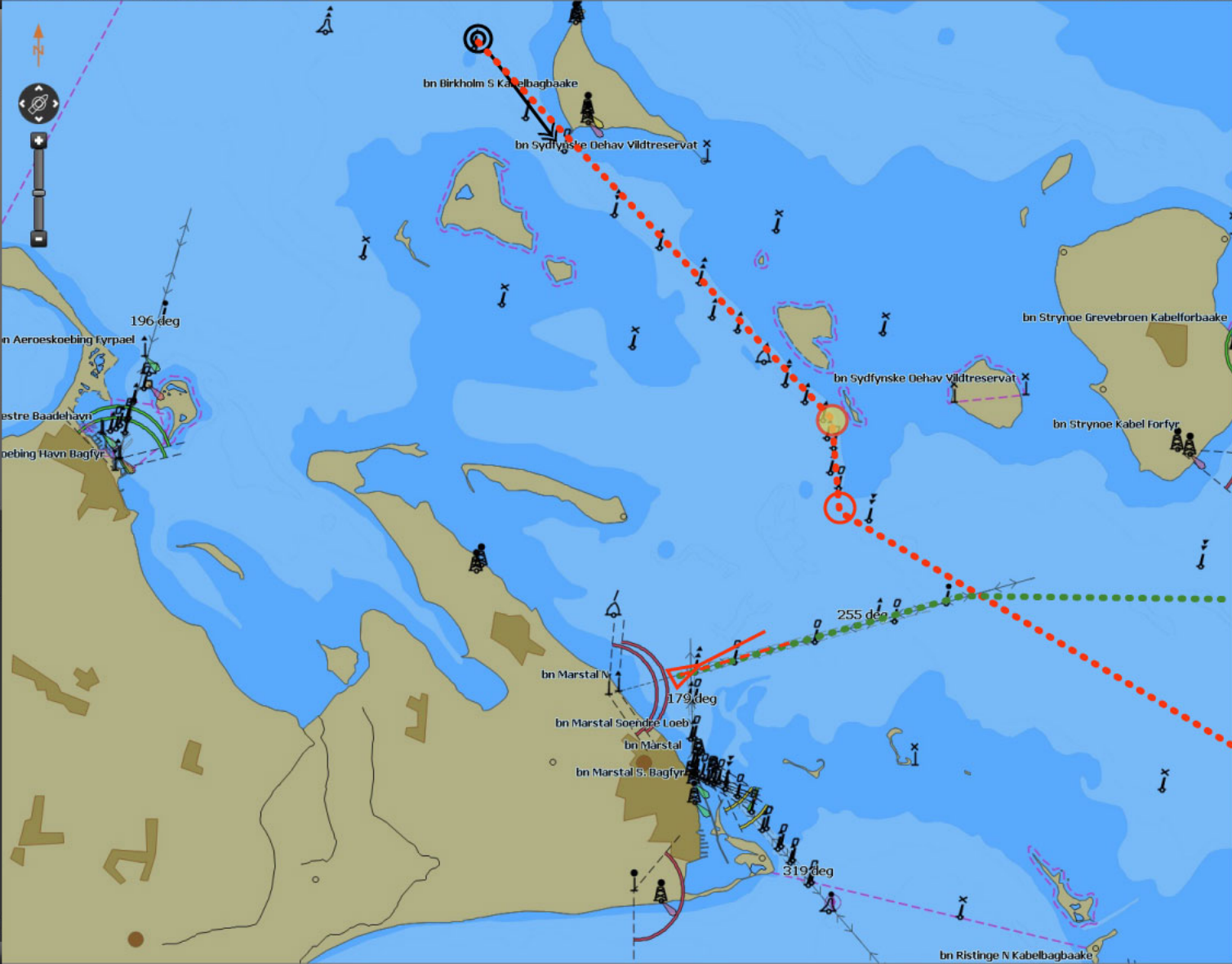
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Conditionally Displayed Features

Date Dependent **Within Effective Dates** ▾

Scale Dependent **Within Effective Scales** ▾

Display | LOP | Nav Tools | User Symbols | Past T

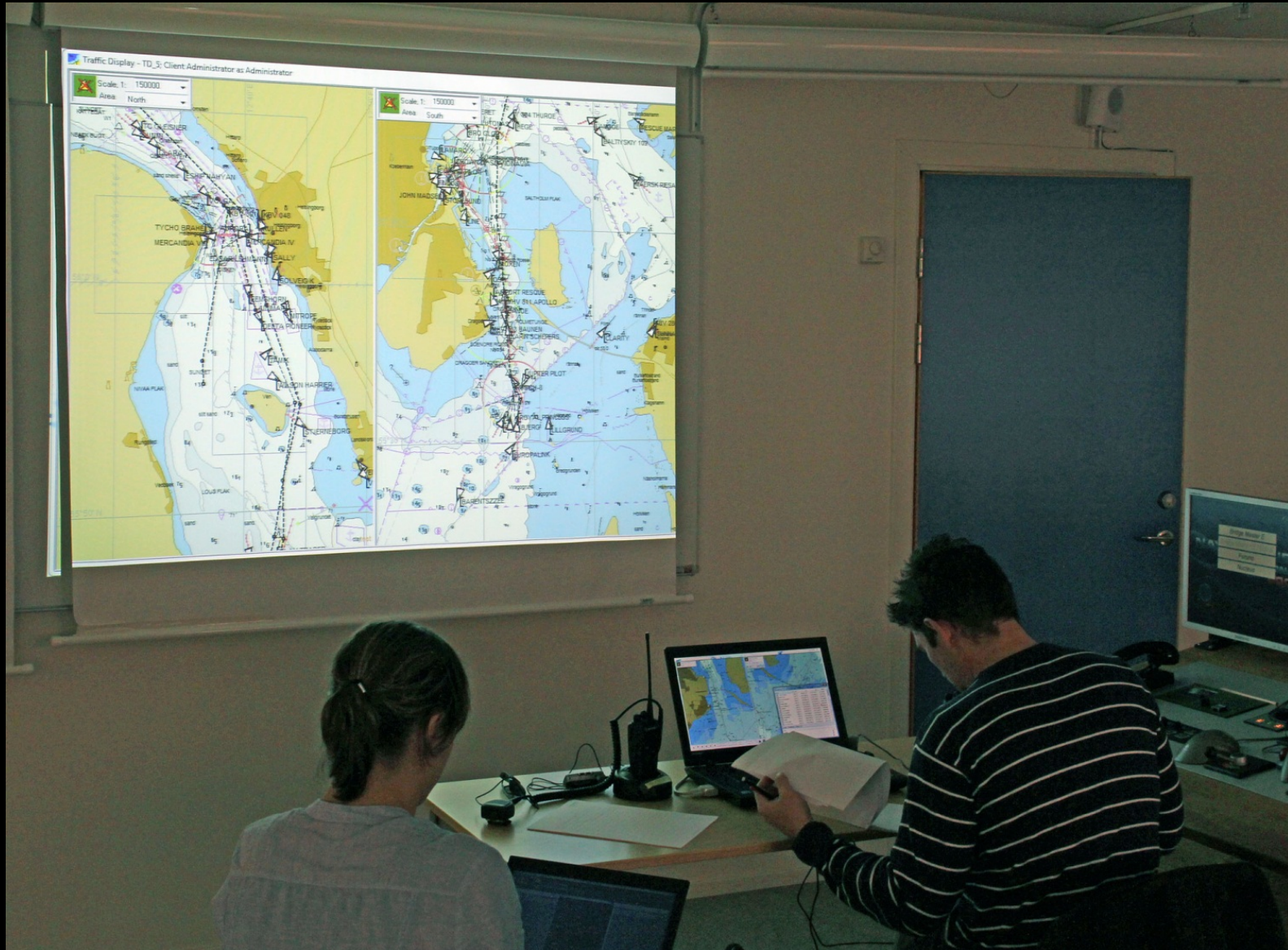




<http://www.marintraffic.com> 2011-09-06, 21:56













Distributing search patterns using ECDIS

Thomas Porathe
Chalmers University of Technology

Fredrik Forsman,
Swedish Sea Rescue Society

Ole Borup,
Danish Maritime Safety Administration



INTERNATIONAL
MARITIME RESCUE

**World Maritime
Rescue Congress**

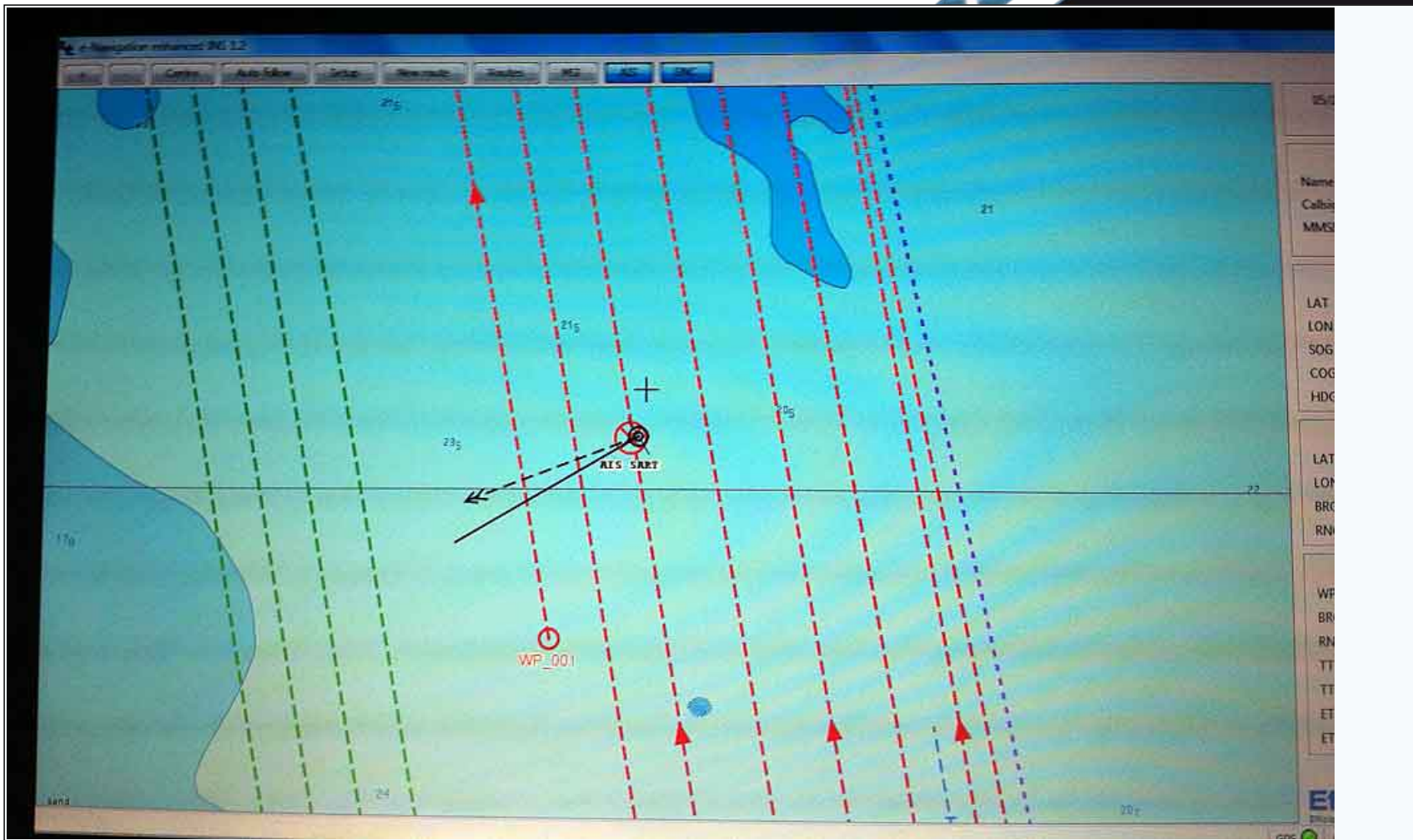
Shanghai 24-28 August 2011













A 14 min. long video cut down to 1.5 min.



The 3D chart as a HUD in the windscreen

My dissertation can be downloaded free from:

www.diva-portal.org Search for author "Porathe"

