

Ionosphere monitoring using NOAA's CORS network



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Topics of Discussion



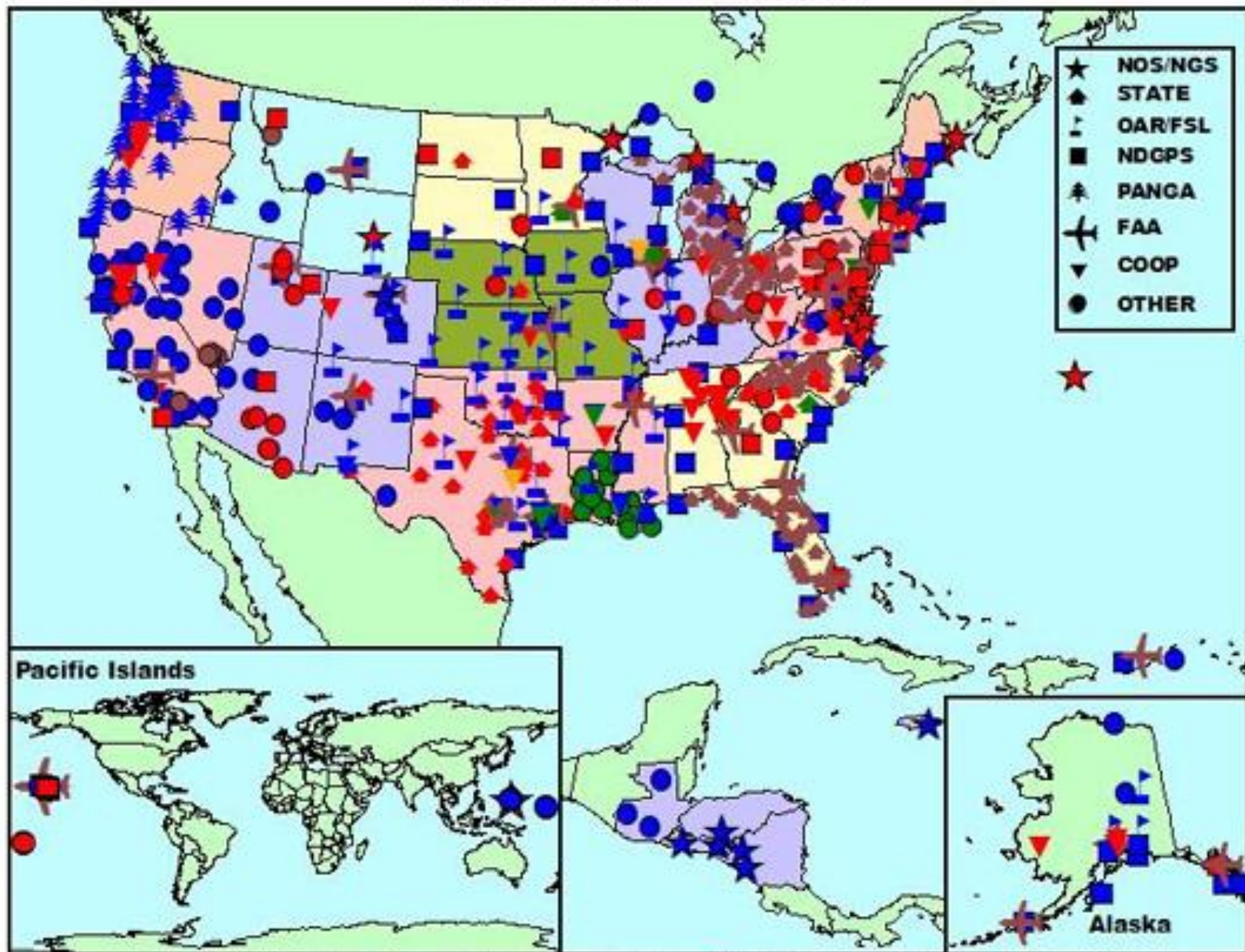
- Geodetic need for Ionosphere
- Model/Equations
- Initial tests
- Full day solution
- Future directions

Geodetic need for ionosphere delays



- Frequency-dependent signals in GPS:
 - Ambiguities
 - Ionosphere
 - Multi-path (assumed zero initially)
- NOAA has developed an innovative new method for modeling absolute Ionosphere delays from ambiguous carrier phase data
- All data from NOAA's CORS network

CORS Coverage - June 2004



Symbol color denotes sampling rates: (1 sec) (5 sec) (10 sec) (15 sec) (30 sec)

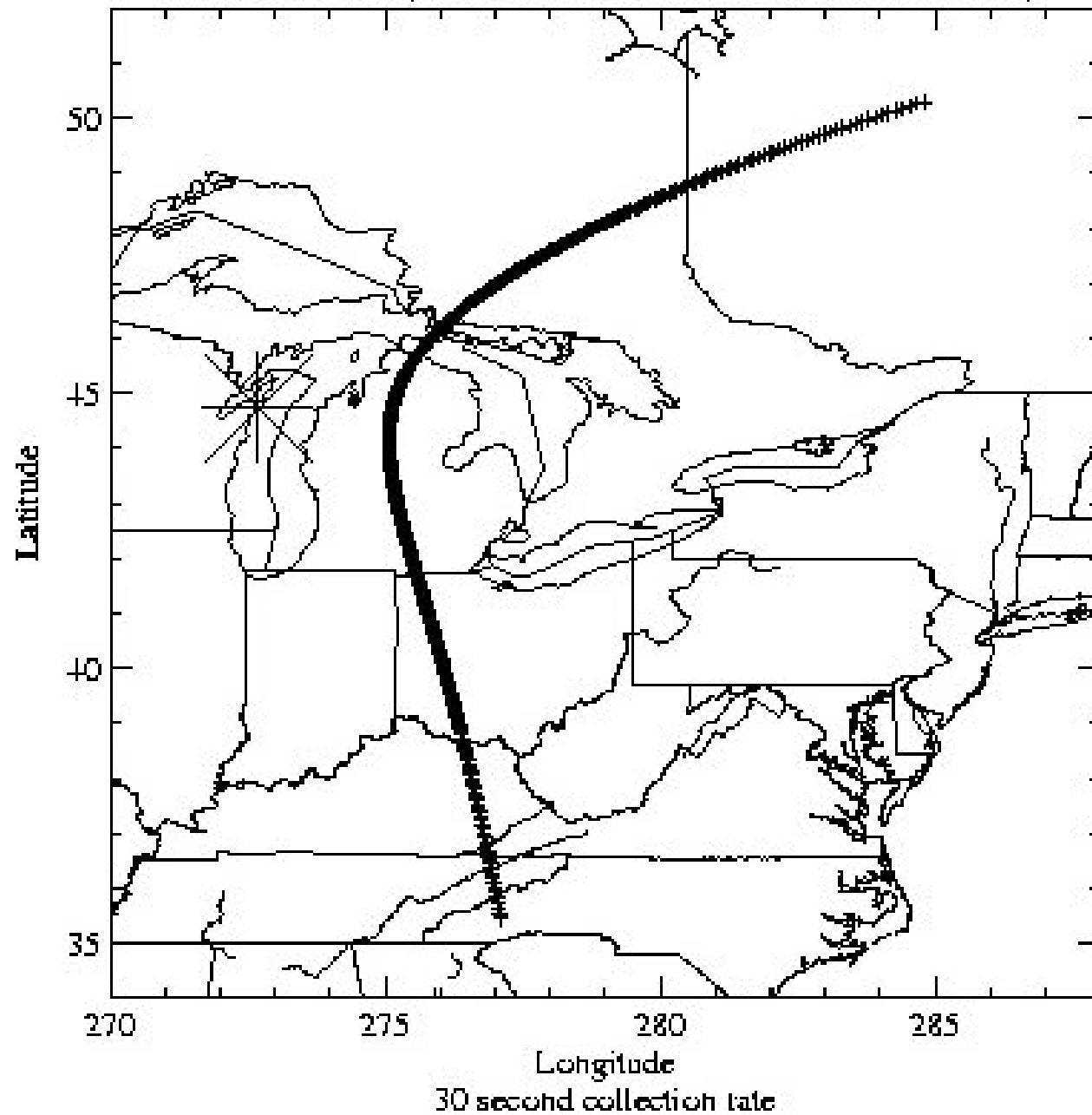
Craig 6/04/2004

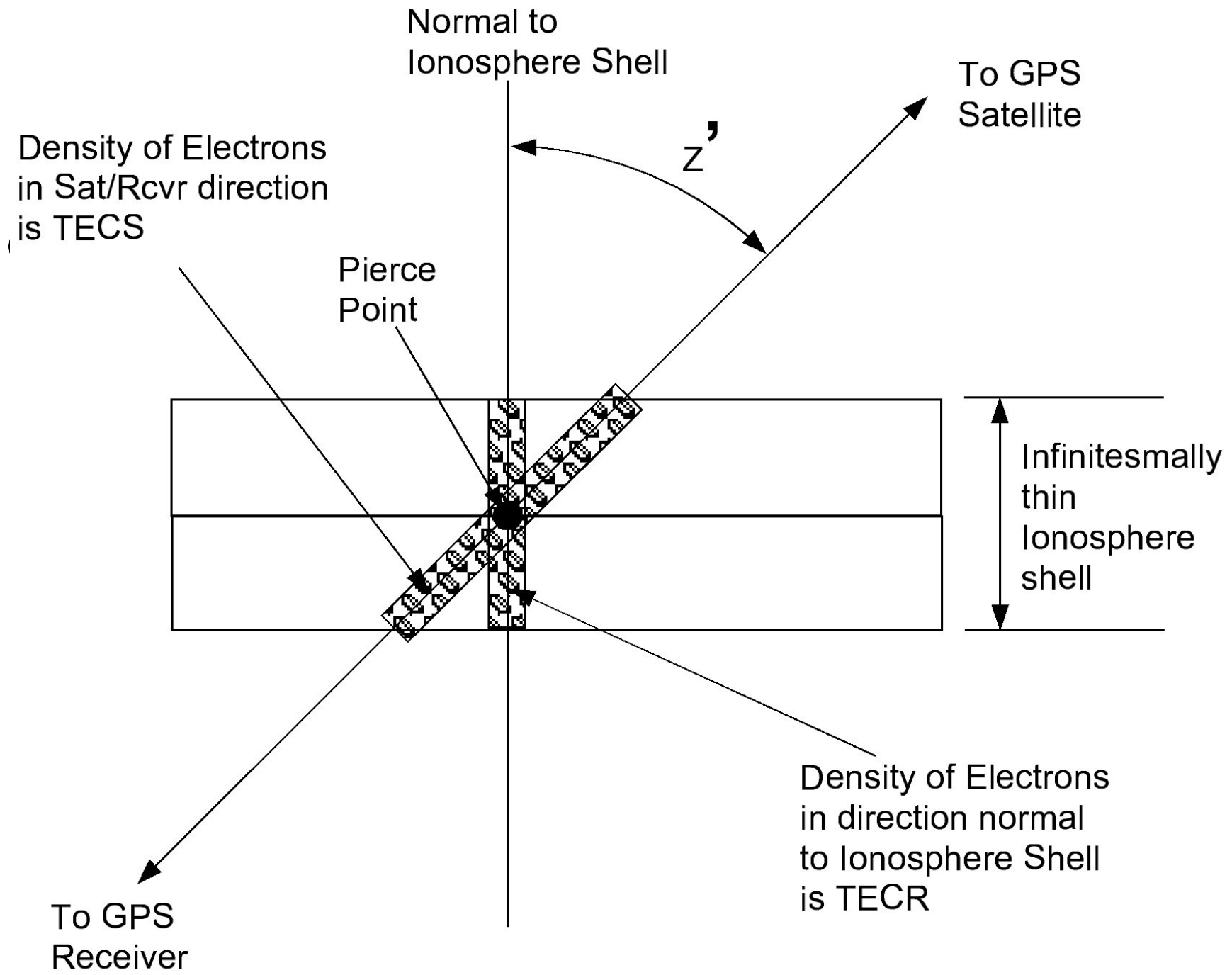
Assumptions and model



- 2-D “condensed” TEC shell (epoch = pierce point)
- Focus on *fast, accurate* ionosphere delays; not on realistic 4-D electron distribution
- Mapping pierce points without loss of lock yields a track
- CORS yields about 20,000 tracks every day

Track 10610 (CORS Station STB1 and GPS SV3)





Normal to Ionosphere Shell

To GPS Satellite

Density of Electrons in Sat/Rcvr direction is TECS

z'

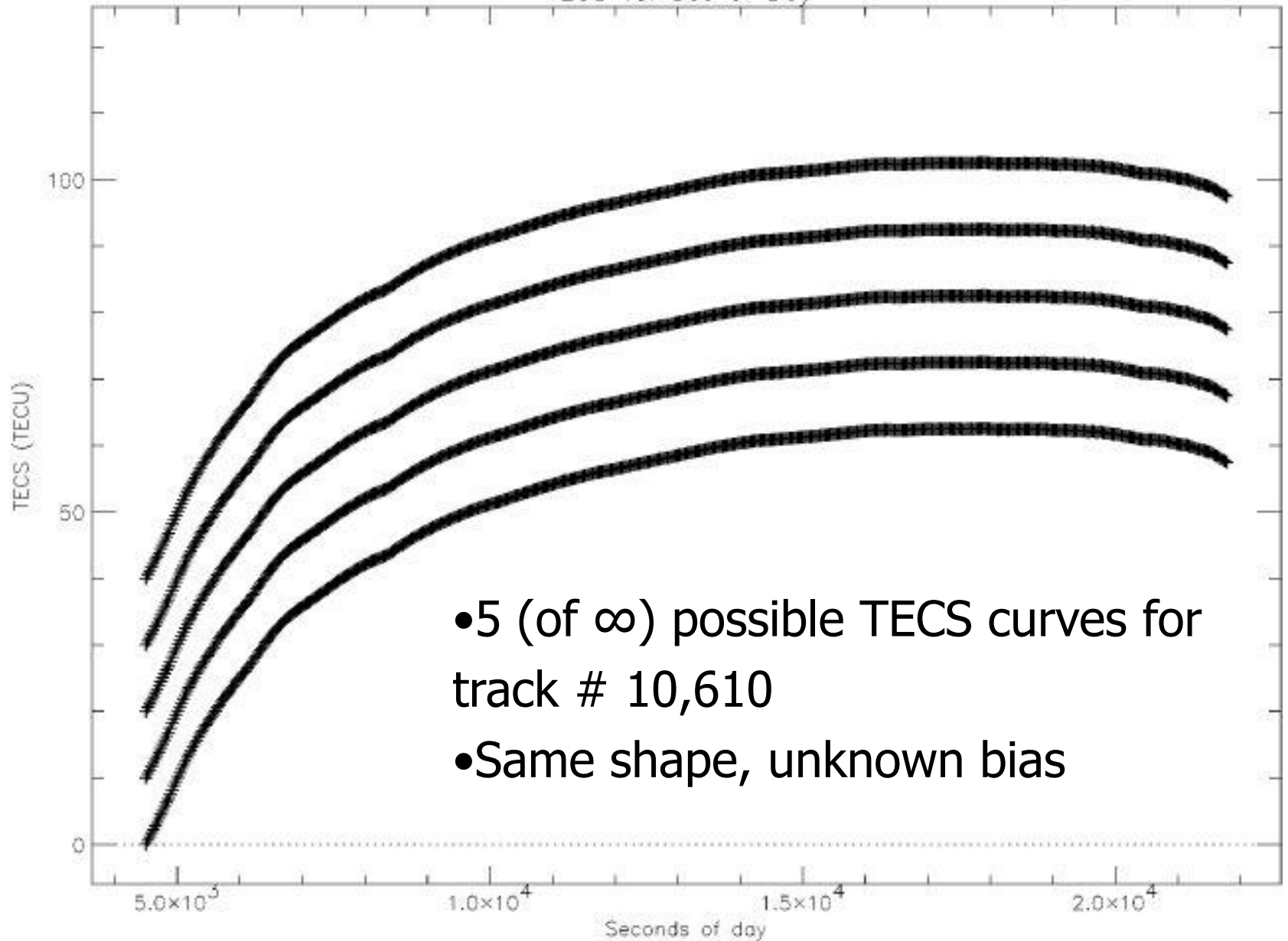
Pierce Point

Infinitesimally thin Ionosphere shell

To GPS Receiver

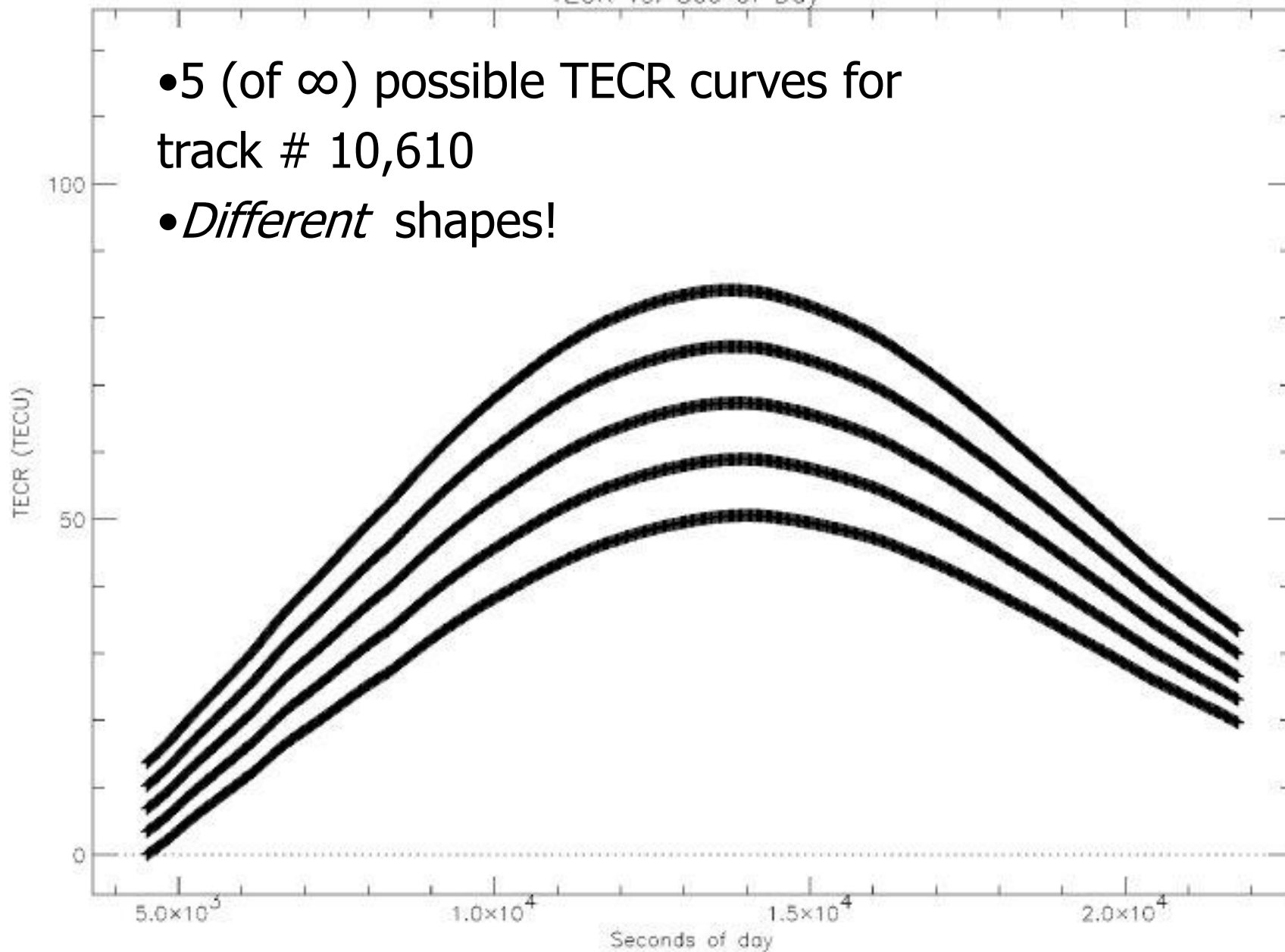
Density of Electrons in direction normal to Ionosphere Shell is TECR

TECS vs. Sec of Day



TECR vs. Sec of Day

- 5 (of ∞) possible TECR curves for track # 10,610
- *Different* shapes!



Solving for biases with crossovers

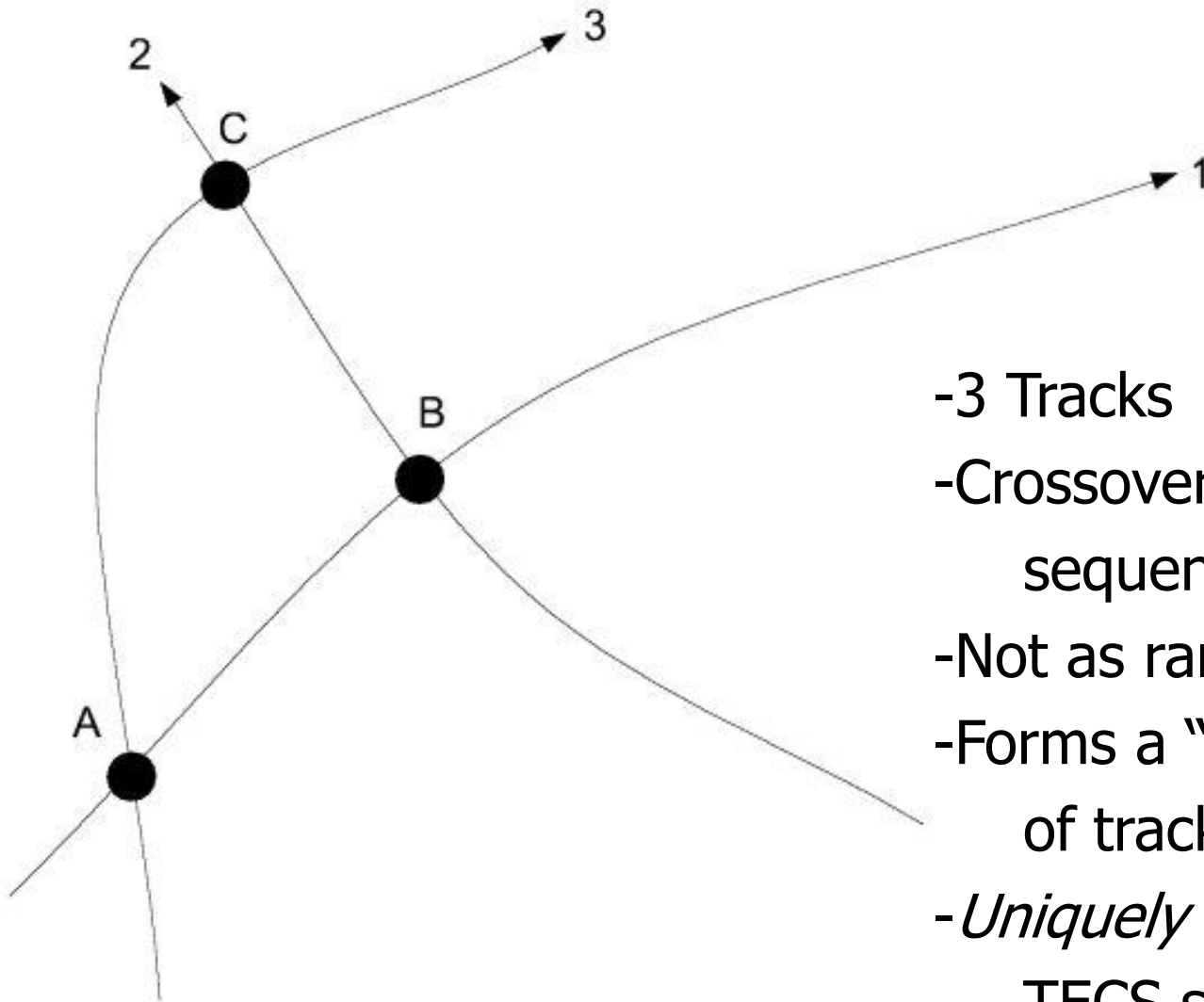


- Solve:
 - 1 TECS bias per track
- Consider two tracks that pierce the ionosphere at the same place, at the same time (i.e. a “crossover”)
 - $\text{TECS}(\phi, \lambda, t, \text{track a}) \neq \text{TECS}(\phi, \lambda, t, \text{track b})$
 - $\text{TECR}(\phi, \lambda, t, \text{track a}) = \text{TECR}(\phi, \lambda, t, \text{track b})$

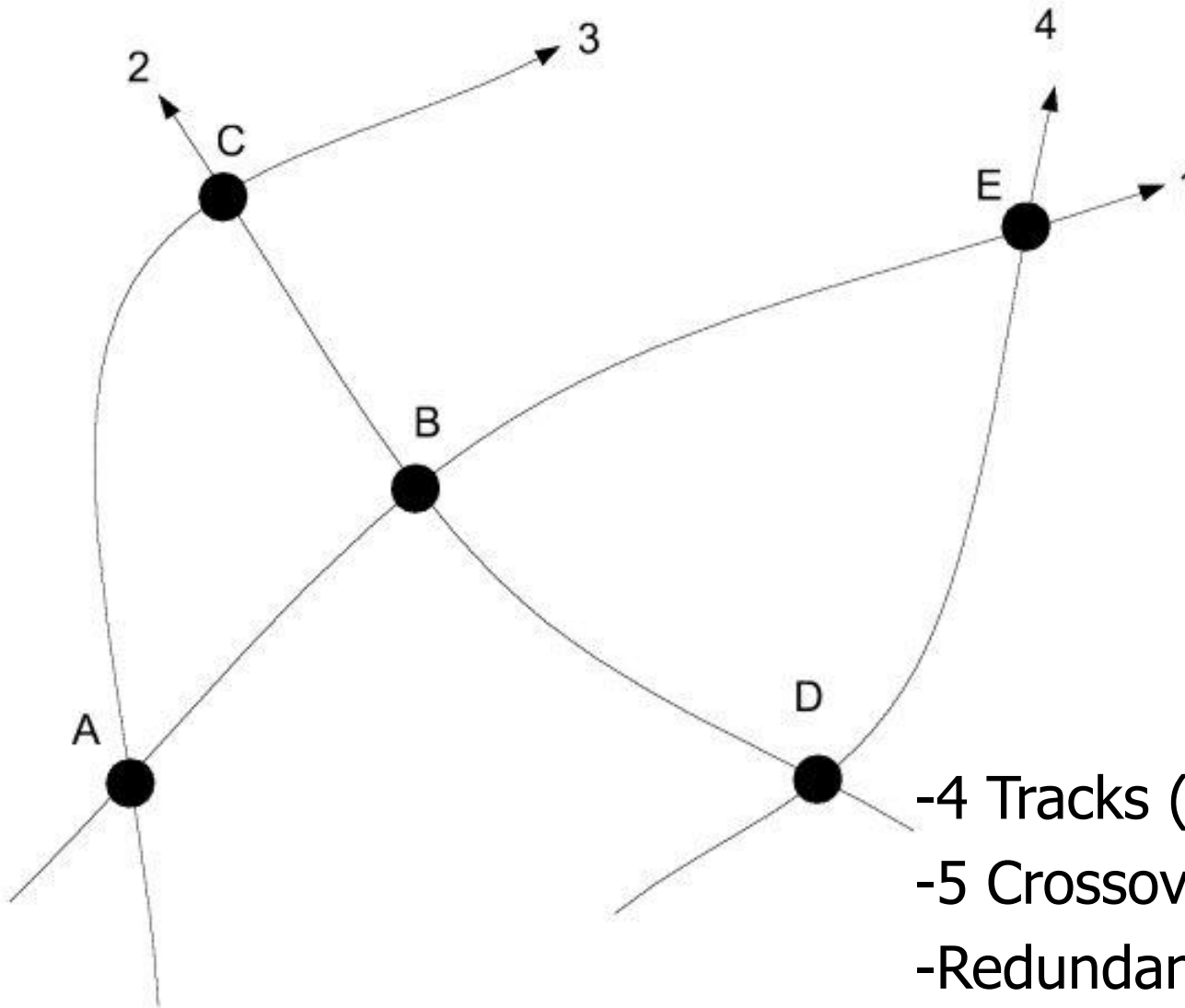
Using Crossovers



- By itself, one crossover has:
 - 1 condition (TECR equality)
 - 2 unknowns (TECS biases for 2 tracks)
 - Thus, unsolvable as is
- Need conditions \geq unknowns
- Closed polygons is the solution



- 3 Tracks
- Crossovers A,B,C occur in sequential order
- Not as rare as it looks
- Forms a "closed polygon" of tracks
- Uniquely* solvable in *absolute* TECS space

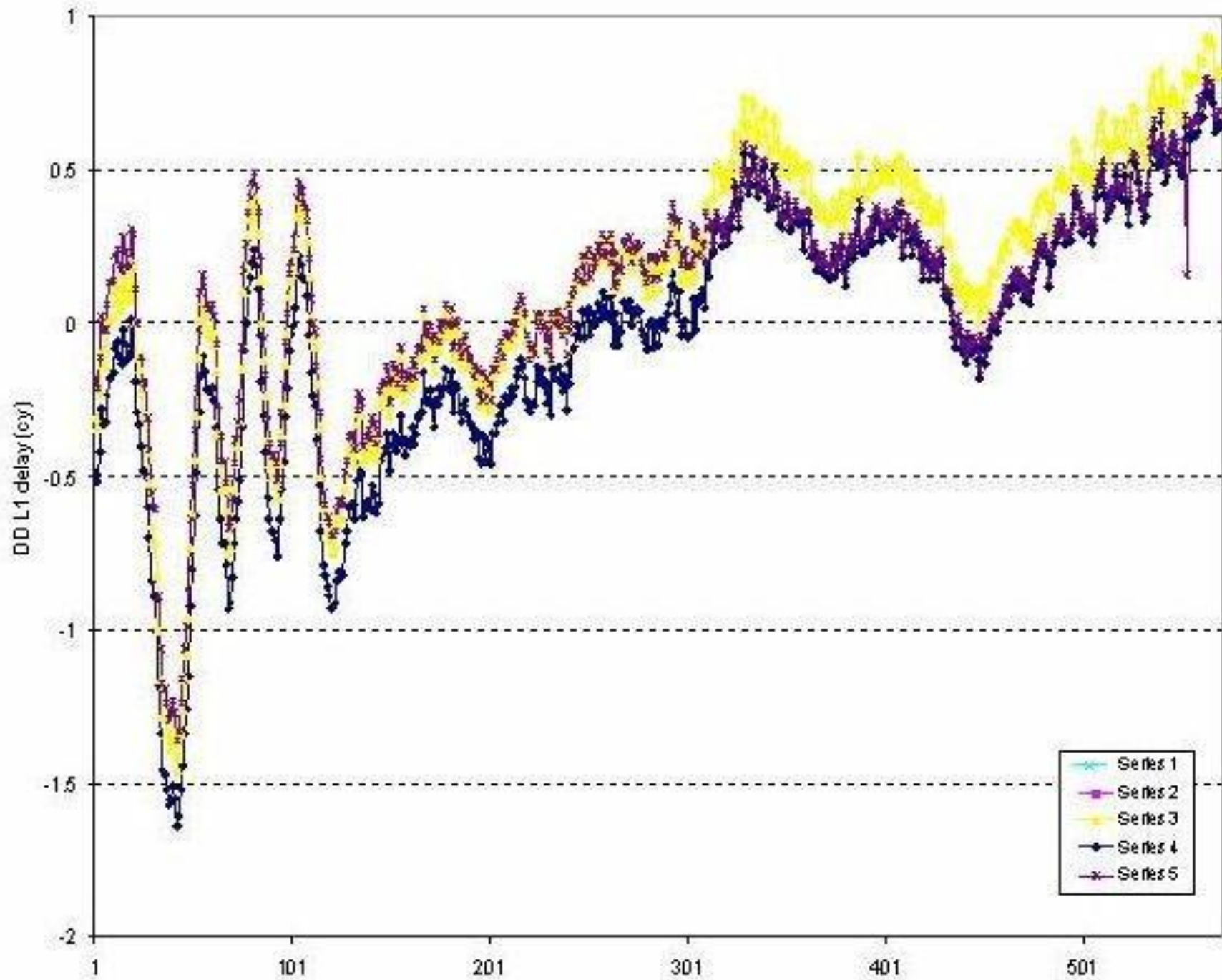


-4 Tracks (unknowns)
-5 Crossovers (conditions)
-Redundancy = Least Squares
Adjustment in *absolute*
TECS space

Initial Tests



- Small “tracknets” of 10-12 tracks formed
- Proof-of-concept
- Absolute delays converted to double difference delays
- DD delays good to 0.1 – 0.01 TECUs against “truth” (Ambiguity resolving software)



Full day solution



- Day 193 (July 12) of 2002
- 307 CORS stations
- 16,896 Crossovers (conditions)
- 8298 Tracks (unknowns)

Full day solution

- Unzip/read hundreds of RINEX.gz files
 - 2 hours
- Clean 11 Million data pts (cycle slips, etc)
 - 30 min
- Solve 8298 x 16896 sparse linear system
 - 30 seconds to get 8298 biases
 - 10 minutes to get σ_{bias}

Full day solution (cont)

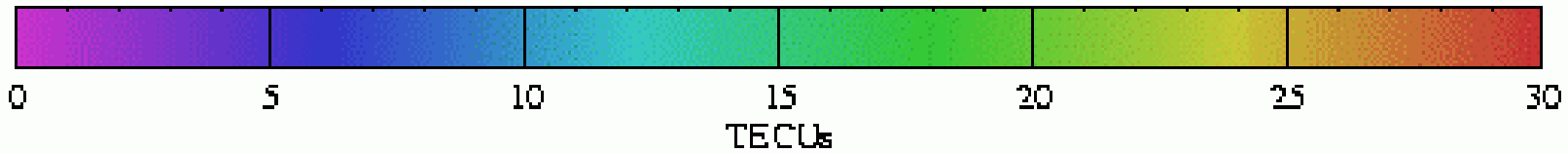
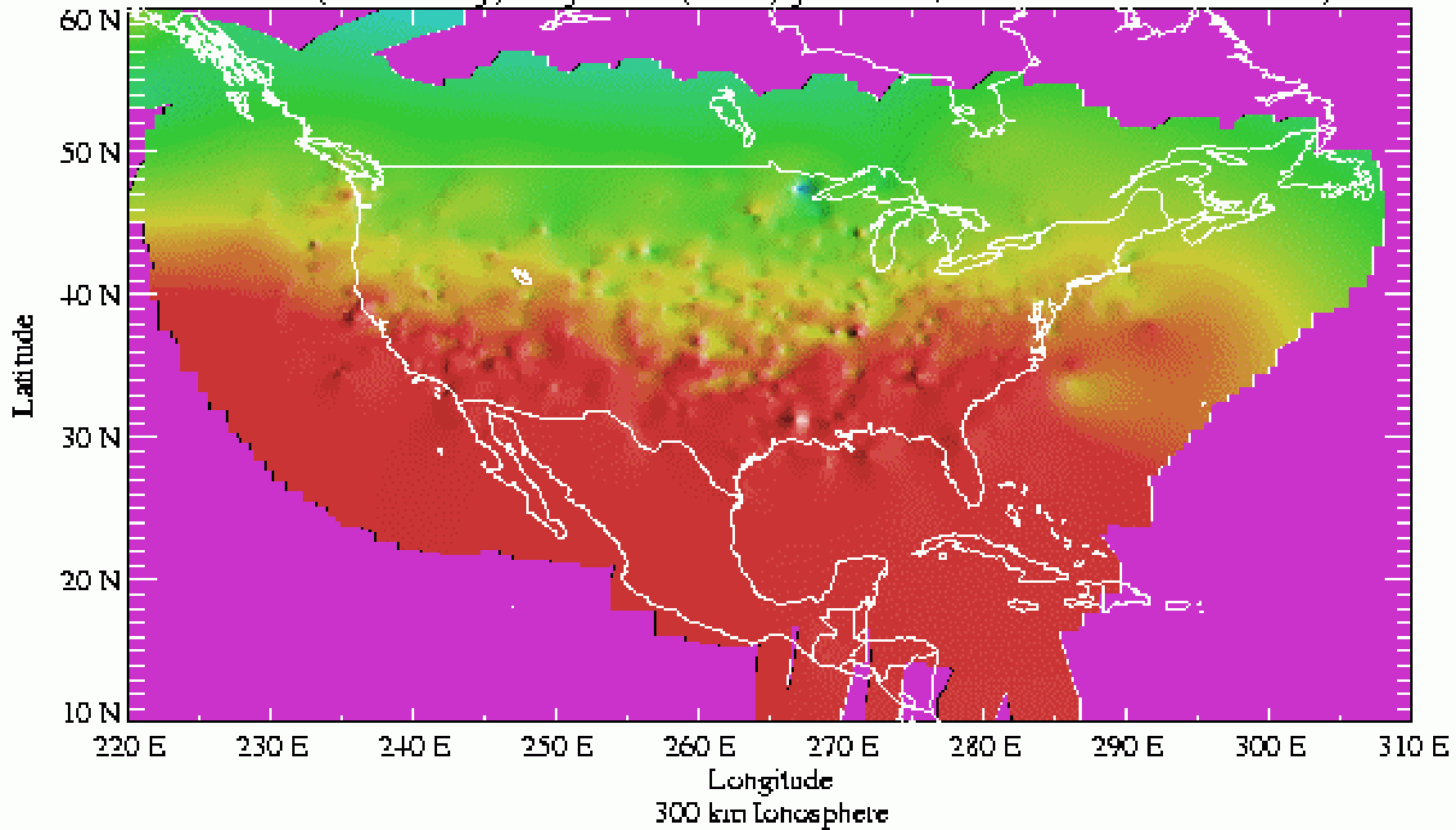
- Post Fit Crossover stats (TECUs)
 - -0.004 0.51 (Min -3.7; Max +4.0)
- A-posteriori σ_{bias} estimates:
 - Ave(σ_{bias}) = 1.1 TECU (Min 0.22, Max 10.7)

Full day solution Animations

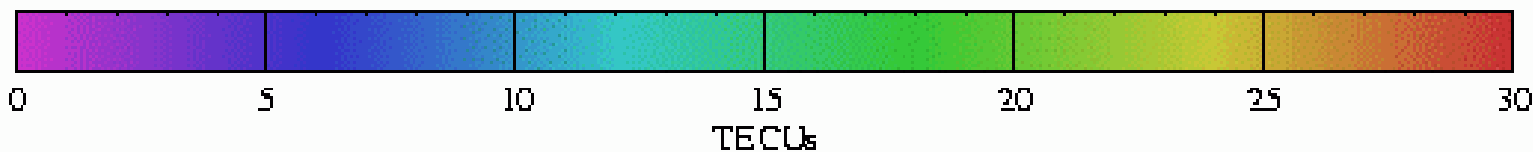
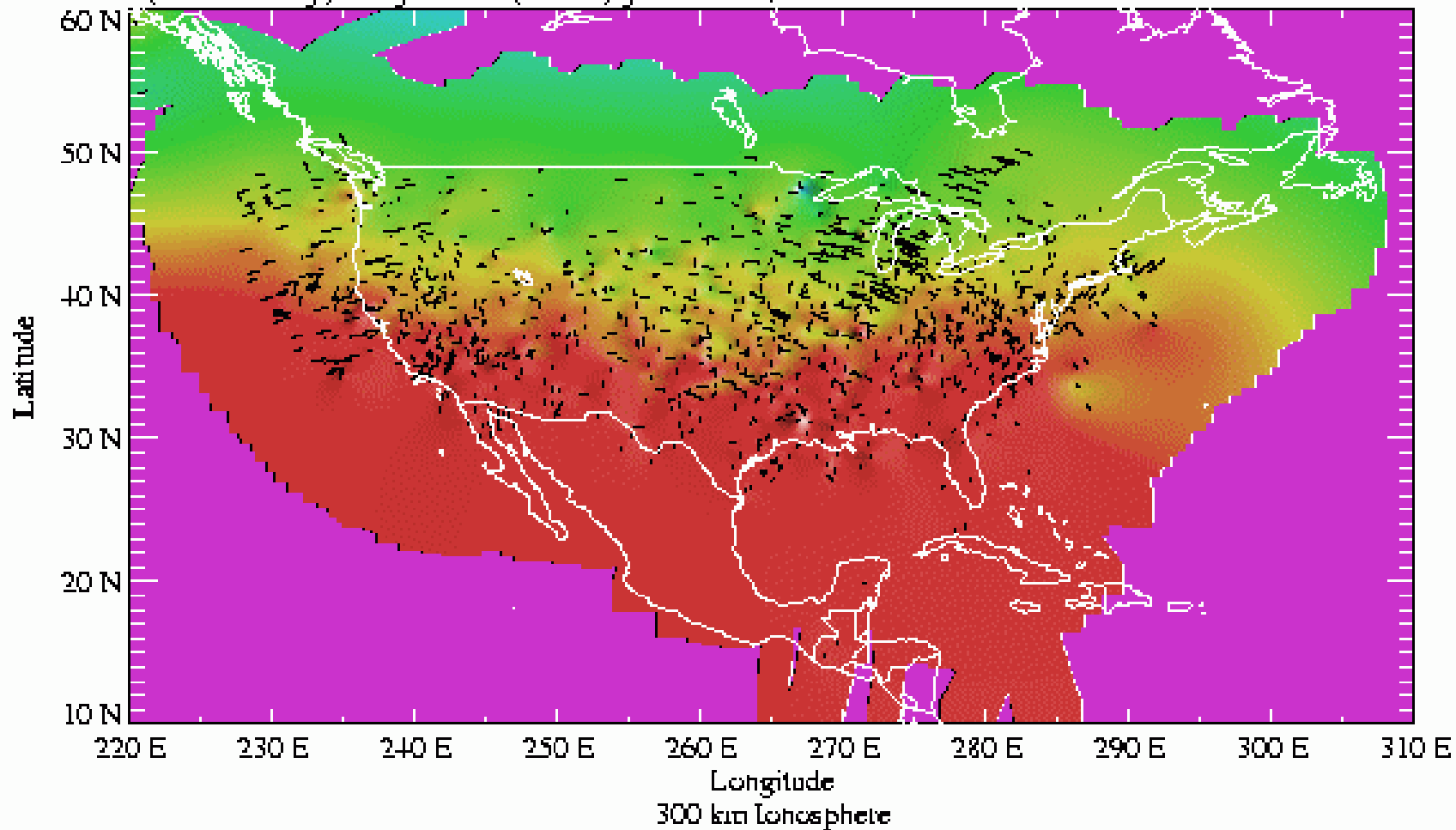


- Animation without tracks
 - gif
 - avi
- Animation with tracks
 - gif
 - avi

TECR (Phase only, Poly RCR (1/1/1) y2002 d193 Tension=0.1 t=00000)



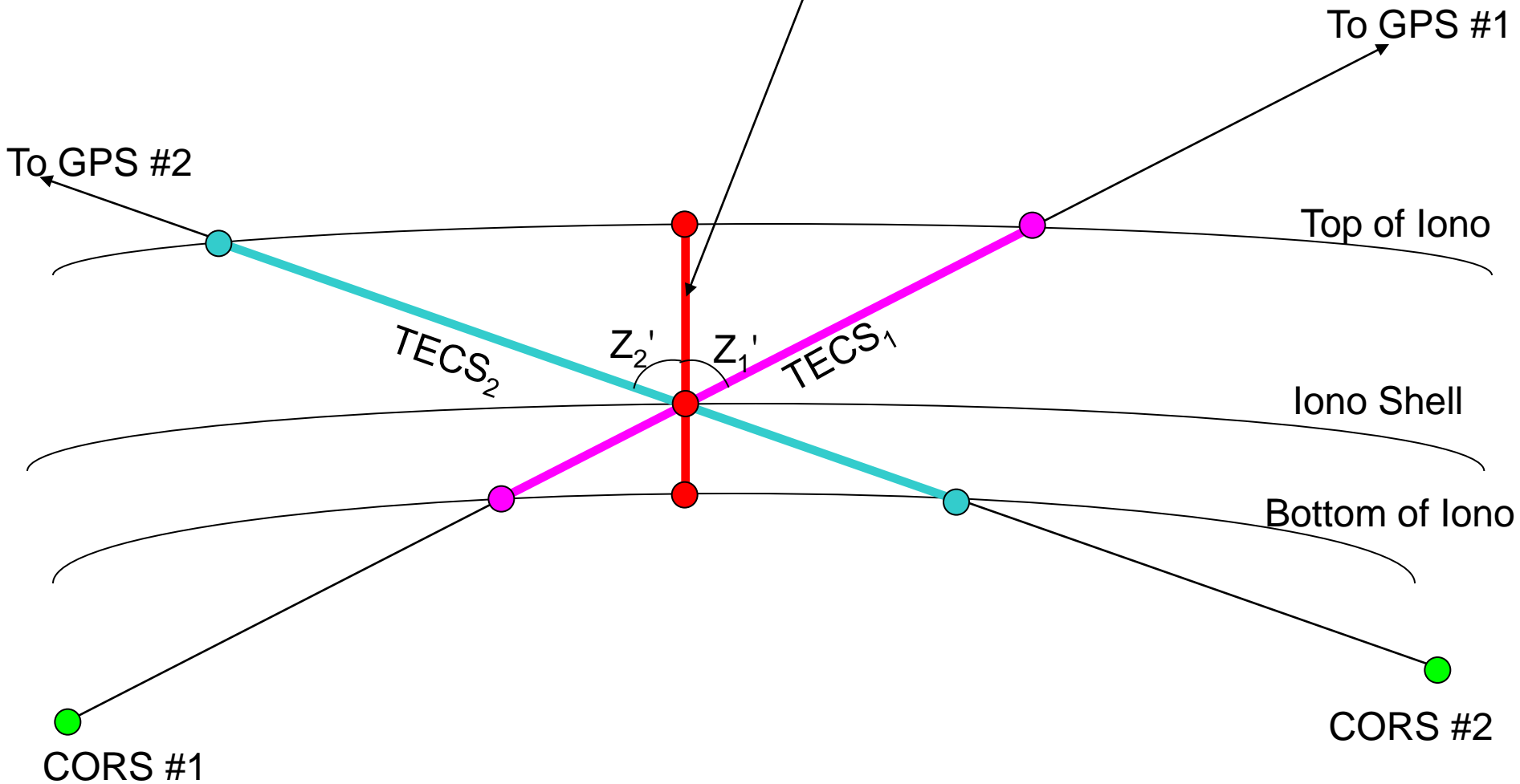
TECR (Phase only, Poly RCR (1/1/1) y2002 d193 Tension=0.1 t=00000 w/Raw Tracks shown)



Full day solution (cont)

- Average a-posteriori σ_{bias} of 1.1 TECU reasonable, but larger than hoped for
- Sub-TECU crossover residuals show tight “locking” or consistency of tracknet
- Overall noise in grids needs improvement
- General conclusion:
 - “Promising” but not by any means “done”
 - Initial analysis indicates **near-horizon crossovers are the primary error source** (TECS=TECR/cos z’ unreliable)

$$\text{TECS}_1 \times \cos(z_1') = \underline{\text{TECR}_1 = \text{TECR}_2} = \text{TECS}_2 \times \cos(z_2')$$



“Large” z' makes the TECR equality questionable

$$\text{TECS}_1 \times \cos(z_1') = \underline{\text{TECR}_1 = \text{TECR}_2} = \text{TECS}_2 \times \cos(z_2')$$

To GPS #2

To GPS #1

Top of Iono

Iono Shell

Bottom of Iono

TECS₂

TECS₁

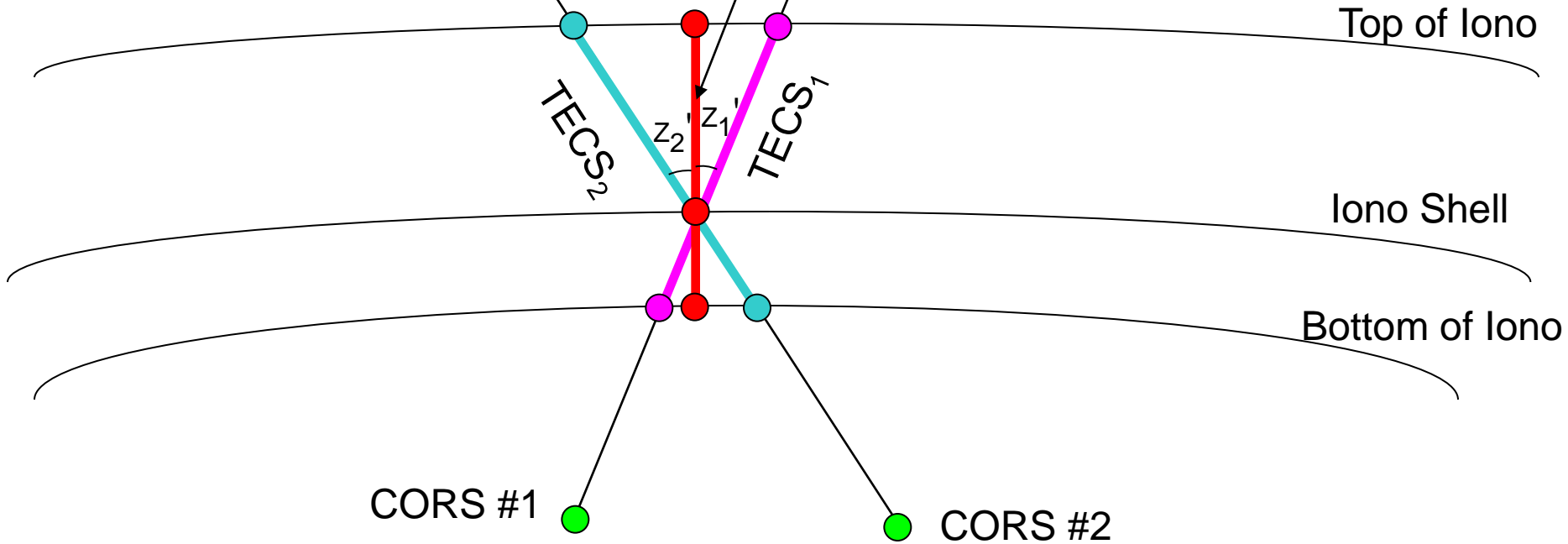
z_2'

z_1'

CORS #1

CORS #2

“Small” z' makes the TECR
equality more reliable



Latest Results



- Ohio State University compared various Ionosphere estimates at Ohio CORS stations
- Crossovers restricted to 40 degrees above the horizon
 - Avoids erroneous biases from low-elevation crossovers
 - Reduces number of tracks immediately solvable from tracknets (unsolved tracks need interpolation from nearby solved tracks)

Report for NOAA/NGS

On:

Accuracy analysis of various NGS ionosphere estimation models

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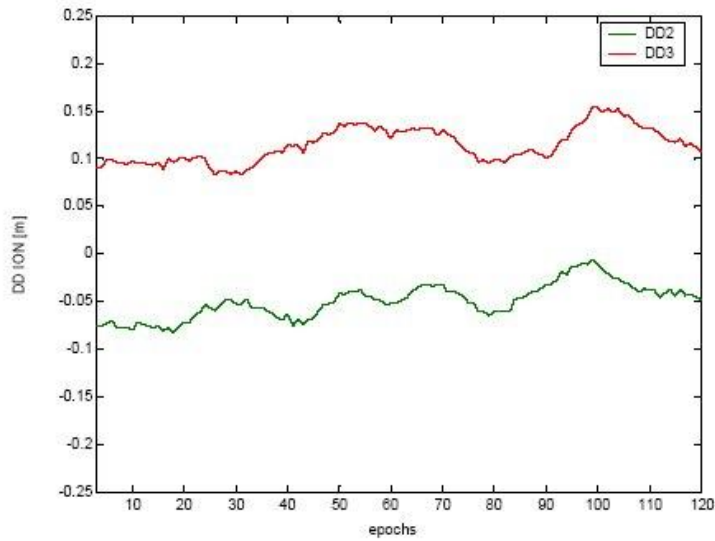


Fig. 22 NGSa DD iono (day-time)

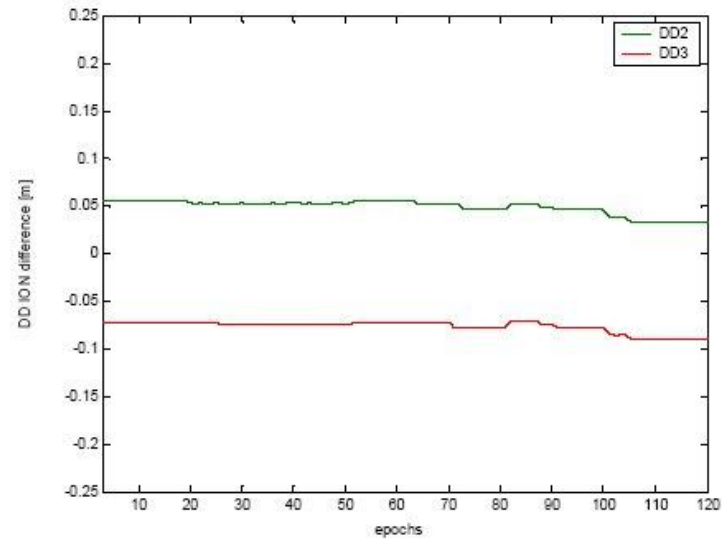


Fig. 23 NGSa DD iono differences from the "truth" (day-time)

This model

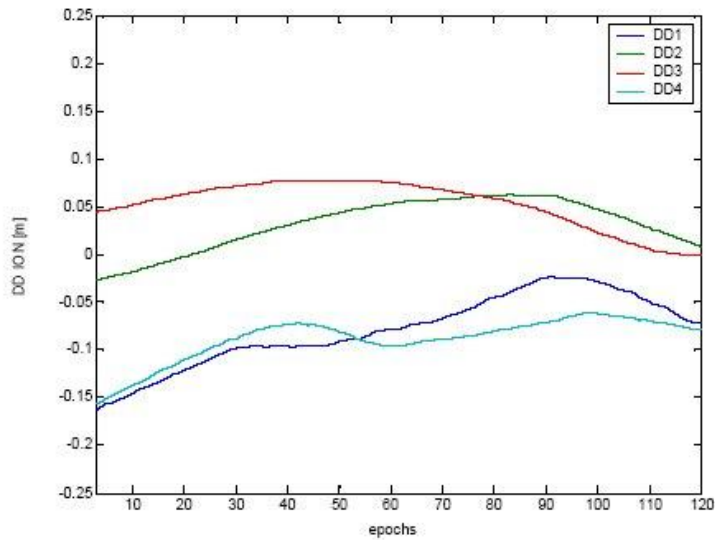


Fig. 24 NGSb DD iono (day-time)

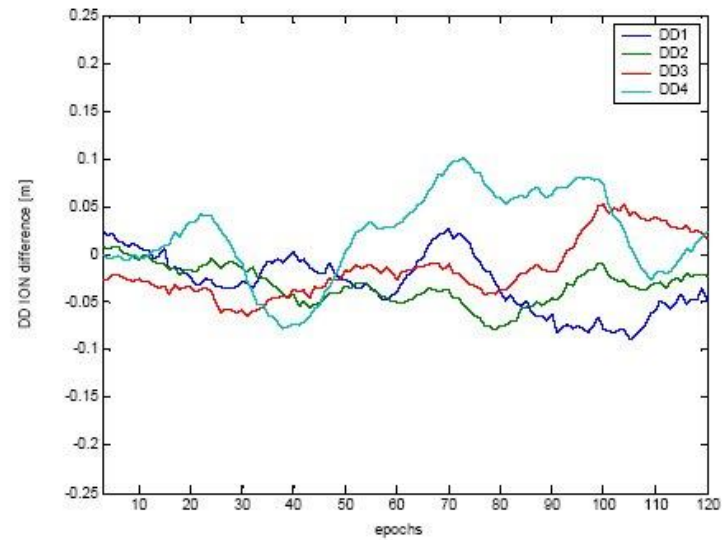


Fig. 25 NGSb DD iono differences from the "truth" (day-time)

NOAA's
"Magic"
model

Summary and Conclusions

- With certain assumptions, a model for the ionosphere can be computed as an entire network
 - to ~ 1 TECU (absolute)
 - to $\sim 0.3 - 0.06$ TECU (5 cm - 1 mm on L1)
agreement with Double Difference estimates,
subject to cycle-slip fixing
- Interpolation can yield ~ 5 cm (L1) biases from nearby tracks

Summary and Conclusions (cont)



- Further sensitivity studies:
 - Removing near-horizon crossovers (nearly done)
 - Shell height
 - CORS thinning
- Independent tests forthcoming:
 - Against other ionosphere models
 - In ambiguity resolving software
- Production:
 - Daily solutions expected to begin in Fall 2004

```

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XXX MARKER NUMBER
CORS/NGS/NOAA OAR/FSL OBSERVER / AGENCY
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3328A68603 TRM14532.00 ANT # / TYPE
-395445.7142 -5271710.3365 3556709.0313 APPROX POSITION XYZ
0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N
1 1 WAVELENGTH FACT L1/2
8 C1 L1 L2 P1 P2 D1 D2 I1 # / TYPES OF OBSERV
30.0000 INTERVAL
Forced Modulo Decimation to 30 seconds COMMENT
2004 1 7 0 0 0.0000000 GPS TIME OF FIRST OBS
This is an IINEX file, not strictly RINEX. COMMENT
The difference is that an I1 variable, representing COMMENT
the computed Ionosphere delay on L1, in cycles of L1, COMMENT
has been introduced. This value should generally COMMENT
always be positive. COMMENT
I1 was computed by Dru Smith, NOAA/NGS with the following COMMENT
parameters (see D. Smith for details): COMMENT
Year = 2004 Day of Year = 007 COMMENT
Shell Height (km) = 0300 COMMENT
Track Cleaning Criteria Index : 001 COMMENT
Crossover Spacing Criteria Index : 001 COMMENT
Tracknet Formation Criteria Index : 009 COMMENT
LSA Weighting Scheme Index : 004 COMMENT
Flag for post-LSA interpolation : 000 COMMENT
END OF HEADER
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-4100.07840 0.00000 15.799
25107871.38340 3708841.58542 2259556.02945 0.00000 25107875.26240
-3307.67240 0.00000 -99999.000
21512358.68840 18328193.84048 14366529.97347 0.00000 21512363.50440
-3686.29740 0.00000 -99999.000
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-1809.82840 0.00000 9.850
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24034690.15640 41863677.08547 32692773.82046 0.00000 24034694.44540
-4906.23440 0.00000 -99999.000
21762273.85940 -282123.29347 -147989.82246 0.00000 21762278.34840
-1713.00040 0.00000 16.644
24560456.50840 -45620.85743 0.00000 0.00000 0.00000
704.09440 0.00000 -99999.000

```

Contact Information



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- Dru.Smith@noaa.gov

Questions?

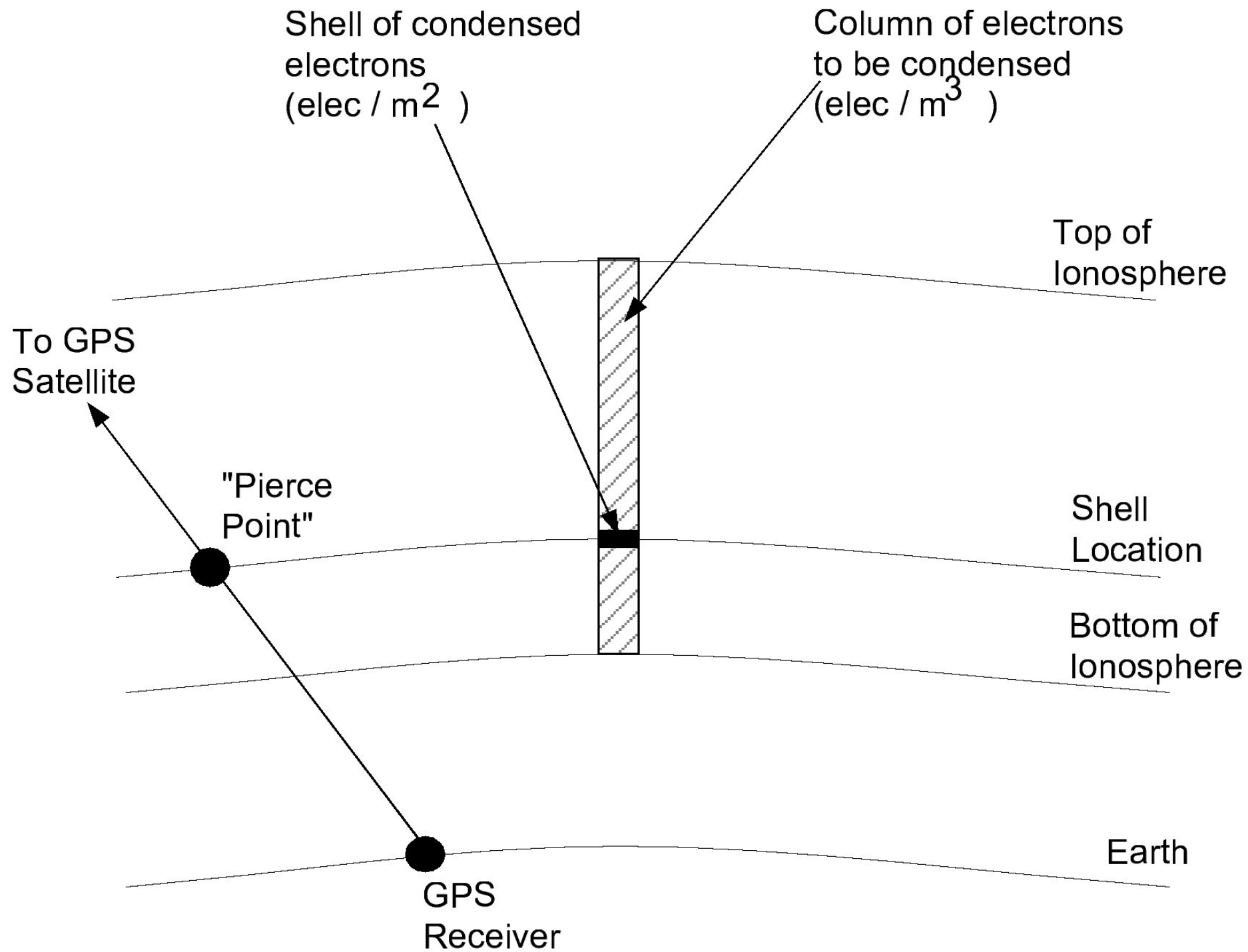
Extra Slides



CORS Network



- Currently 400+ 24/7 receivers
 - Dual frequency, carrier-phase
 - Multi-agency
 - Administered by NGS
 - All 50 states, Central America, others
 - *Ideally suited to serve as an ionosphere monitoring network for geodetic applications in the USA*



Pierce Points and Tracks



- A pierce point occurs at ionosphere shell for each data epoch
- Mapping pierce points without loss of lock yields a track
- CORS yields about 20,000 tracks every day

TECS and TECR

- TECS is the TEC value seen in the satellite-receiver direction
- TECR is the vertical TEC value at the shell
 - $TECS = TECR / \cos z'$
 - Questionable usefulness at low elevation angles

Equations

$${}^iR_k = b_k + {}^i r + c({}^i \delta t) + {}^i T + {}^i I_k (+ {}^i m_k) = \lambda_k {}^i \Phi_k^{\text{RINEX}} \quad (\text{biased range, m, epoch "i", freq "k"})$$

$$I_k = -\frac{40.3}{f_k^2} \text{TECS} \quad (\text{m})$$

$$\therefore \lambda_1 {}^i \Phi_1^{\text{RINEX}} - \lambda_2 {}^i \Phi_2^{\text{RINEX}} = (b_1 - b_2) + ({}^i I_1 - {}^i I_2)$$

$$\begin{aligned} \therefore {}^i \text{TECS} &= \left(\frac{1}{40.3} \right) \left(\frac{1}{f_1^2} - \frac{1}{f_2^2} \right)^{-1} \left[\lambda_1 {}^i \Phi_1^{\text{RINEX}} - \lambda_2 {}^i \Phi_2^{\text{RINEX}} \right] \\ &\quad - \left(\frac{1}{40.3} \right) \left(\frac{1}{f_1^2} - \frac{1}{f_2^2} \right)^{-1} (b_1 - b_2) \end{aligned}$$

$$\therefore {}^{i,j} \Delta \text{TECS} = {}^j \text{TECS} - {}^i \text{TECS}$$

$$= \left(\frac{1}{40.3} \right) \left(\frac{1}{f_1^2} - \frac{1}{f_2^2} \right)^{-1} \left(\lambda_1 {}^{i,j} \Delta \Phi_1^{\text{RINEX}} - \lambda_2 {}^{i,j} \Delta \Phi_2^{\text{RINEX}} \right)$$

Implications of Equations



- Knowing Δ TECS:
 - Shape of “TECS vs time” curve known
 - Absolute level unknown
- Single, unknown bias per “track”

$\Delta TECR$ vs $\Delta TECS$



$${}^i TECS = {}^i TECR / \cos^i z'$$

$${}^{i,j} \Delta TECR = {}^j TECR - {}^i TECR$$

$$\therefore {}^{i,j} \Delta TECR = {}^{i,j} \Delta TECS \cos^j z' + {}^i TECS (\cos^j z' - \cos^i z')$$

Implications



- Epoch-dependent $\cos z'$ in TECR:
 - Shape of “TECR vs time” curve is *unknown*
 - Absolute level unknown

Closed Polygons

- Altimetry or Leveling (ΔH & H-equality):
 - # conditions = # vertices – 1
- Ionosphere (ΔTECS & TECR -equality)
 - # conditions = # vertices
- Any time that a closed polygon is formed on the ionosphere “shell” we have:
 - # Conditions = # Unknowns

Polygon Crossover Equations

$$\begin{bmatrix} A_1 \Delta TECS \cos \frac{A_1 z'_1 - A_3 \Delta TECS}{A_3 z'_3} \\ B_1 \Delta TECS \cos \frac{B_1 z'_1 - B_2 \Delta TECS}{B_2 z'_2} \\ C_2 \Delta TECS \cos \frac{C_2 z'_2 - C_3 \Delta TECS}{C_3 z'_3} \end{bmatrix}$$

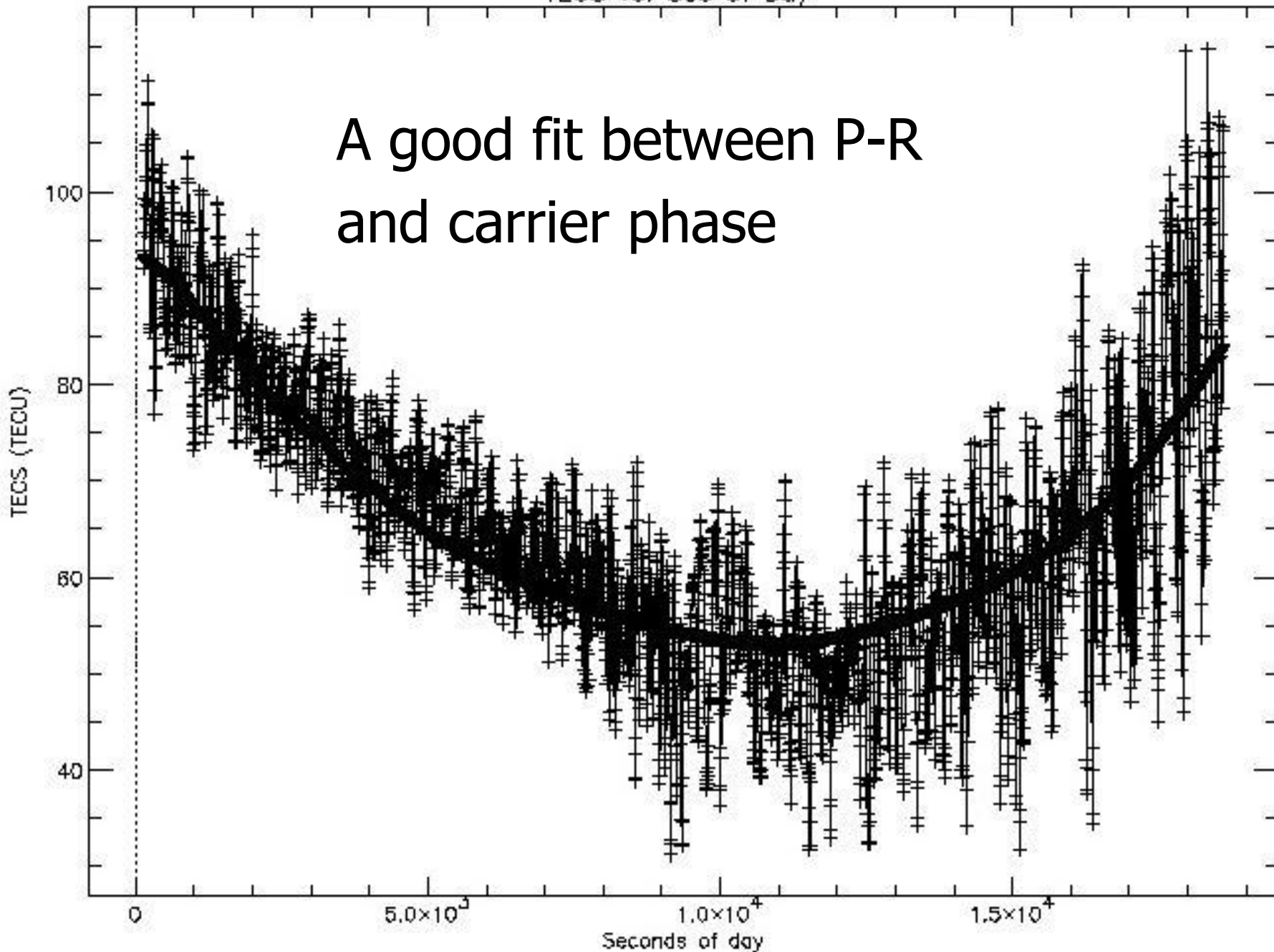
$$= \begin{bmatrix} -\cos \frac{A_1 z'_1}{A_3 z'_3} & 0 & +\cos \frac{A_1 z'_1}{A_3 z'_3} \\ -\cos \frac{B_1 z'_1}{B_2 z'_2} & +\cos \frac{B_1 z'_1}{B_2 z'_2} & 0 \\ 0 & -\cos \frac{C_2 z'_2}{C_3 z'_3} & +\cos \frac{C_2 z'_2}{C_3 z'_3} \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

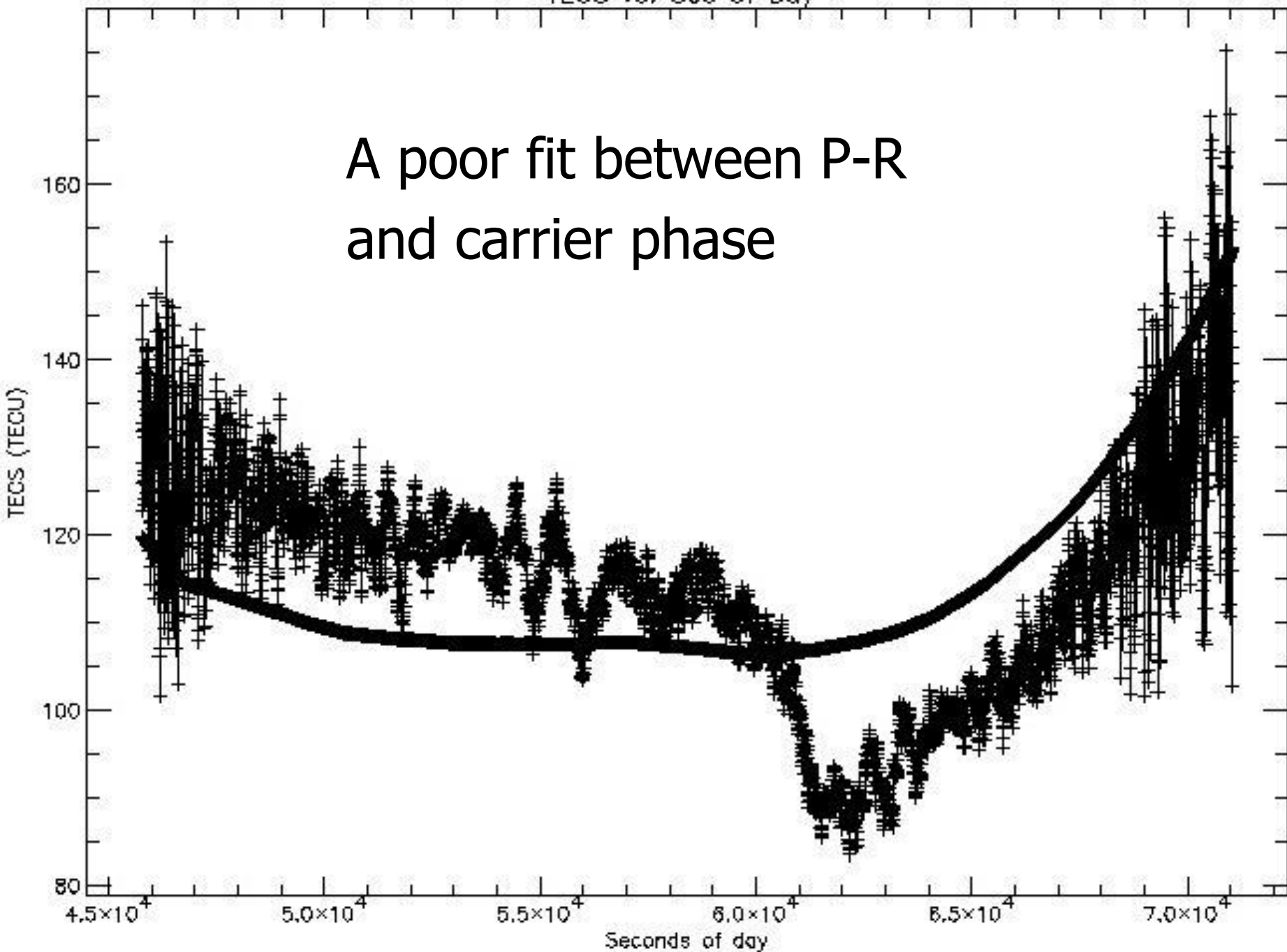
Polygon Crossover Equations



- The existence of the $\cos z'$ values on the RHS allows for matrix inversion
 - (as opposed to +1,0 and -1 for altimetry)
- Solvability
- Can we have redundancy?
 - YES

TECS vs. Sec of Day





Initial Tests



- Parameters:
 - Shell height = 300 km
 - Crossover definition: 0.1 x 0.1 x 1 min
 - Cut-off angle: 10 (for data and crossovers)

Initial Tests

(all contain the 4 base tracks)



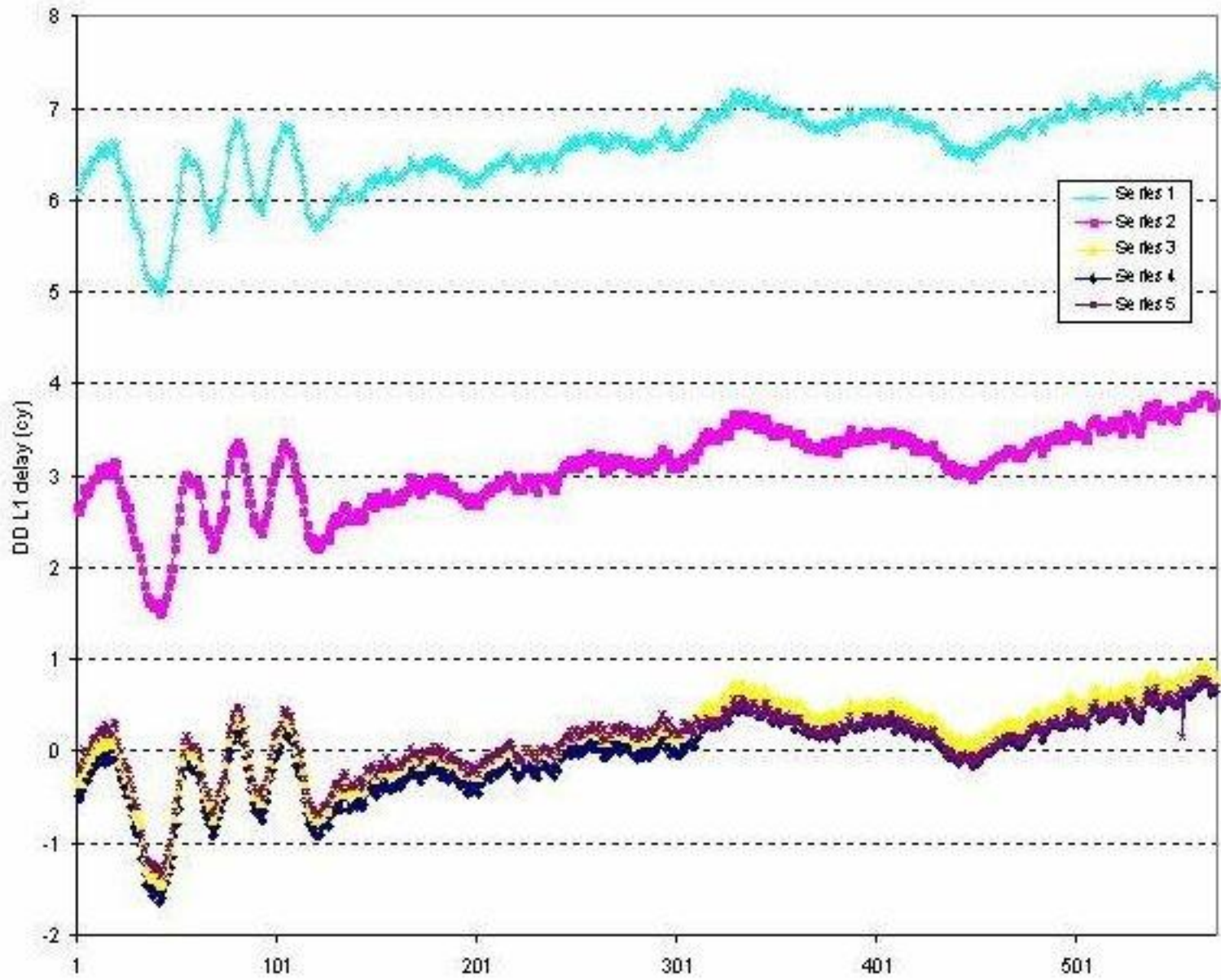
- Solution 1 (smallest tracknet possible containing the 4 base tracks)
 - 8 tracks, No polygons, PR-fit 6 of 8 tracks
- Solution 2
 - 10 tracks, 2 polygons, PR-fit 7 of 10 tracks
- Solution 3
 - 10 tracks, 2 polygons, no PR-fitting
- Solution 4
 - 10 tracks, 2 polygons, PR-fit 1 of 10 tracks

Formal σ_{bias} estimates for first tracknet tests (in TECU)

Track #	Soln 1 (PR fit to 6 of 8; no polygons)	Soln 2 (PR fit to 7 of 10; 2 polygons)	Soln 3 (No PR fit; 2 polygons)	Soln 4 (PR fit to 1 of 10; 2 polygons)
4300 (base)	3.5	2.9	0.1	1.2
4303 (base)	8.8	4.7	0.2	2.1
9484 (base)	9.3	4.6	0.2	2.0
9487 (base)	9.4	3.1	0.1	1.3
2253	13.6	5.9	0.3	2.5
10146	9.7	3.3	0.1	1.4
11416	6.5	4.9	0.2	2.0
12565	6.1	3.9	0.2	1.6
2224	-	4.3	0.2	1.7
11580	-	3.0	0.1	1.2

Initial Tests (cont)

- Individual ionosphere delays for each SV/CORS combo were estimated:
 - $I_{4300}(SV1/GODE)$, $I_{4303}(SV2/GODE)$, $I_{9484}(SV1/RED1)$, $I_{9487}(SV2/RED1)$ all estimated individually (as well as for all other tracks in the tracknet)
- Double Difference delays were then computed:
 - $I_{DD}=(I_{4300}-I_{9484})-(I_{4303}-I_{9487})$ computed and compared to independent estimates from NGS ambiguity resolving software



First tracknet tests



- Pseudo-range fitting tends to bias the tracknet
- Better fit to Double Difference estimated ionosphere by using just polygons and no P-R fitting

Full day solution (cont)

- Interpolation from tracks to grids and/or other tracks:
 - Track-to-grid-to-Track
 - Useful for grid-distributed Ionosphere model and animations
 - 0.00 – 0.38 TECU (6 cm on L1)
 - Track-to-Track
 - Useful for RINEX-distributed Ionosphere model
 - 0.00 – 0.25 TECU (5 cm on L1)
- Full day solution was gridded and animated

Example 2. 17:00-18:00 UT (day-time)

The “truth” DD ionospheric delays are presented in figure 14 with the corresponding satellite elevation map in figure 15. Figures 16–25 represents the derived DD ionosphere from each method and the difference from the “truth” (in pairs). The mean and standard deviation of the ionospheric residuals from the “truth” are shown in Table 2.

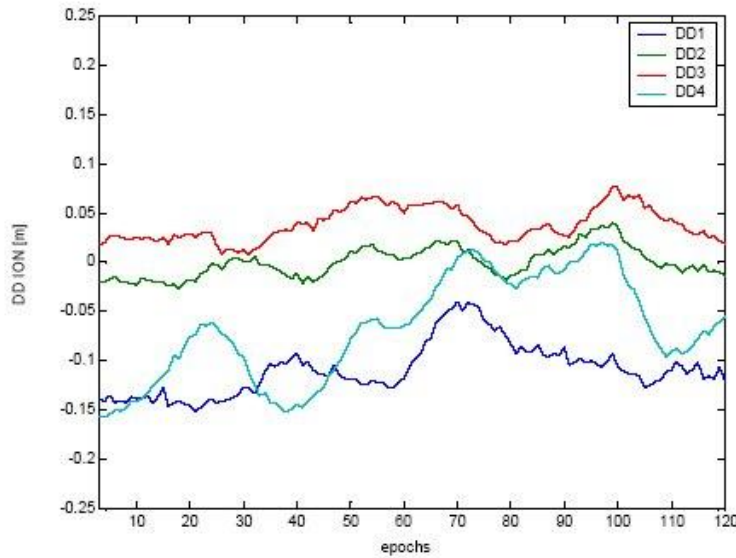


Fig. 14 “Truth” DD iono (day-time)

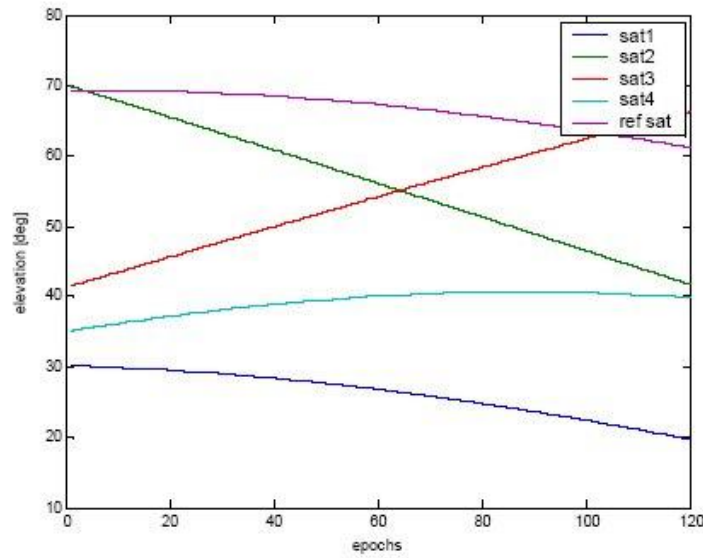


Fig. 15 Satellite elevations

“Truth”
(Iono
after
ambiguity
fixing)

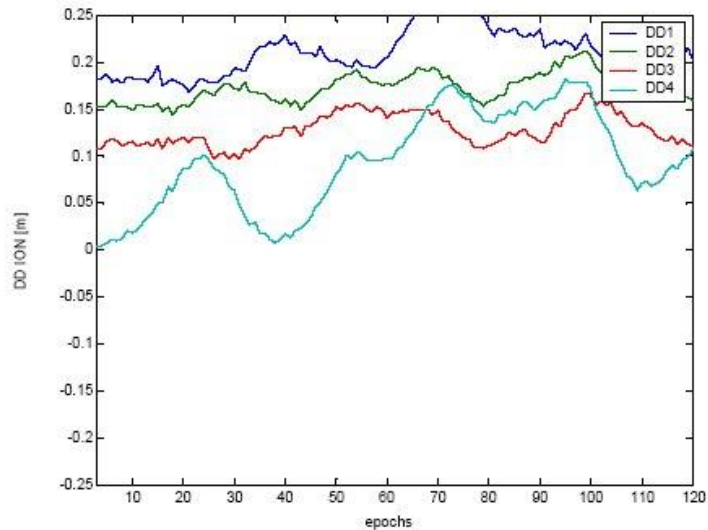


Fig. 16 P4 DD iono (day-time)

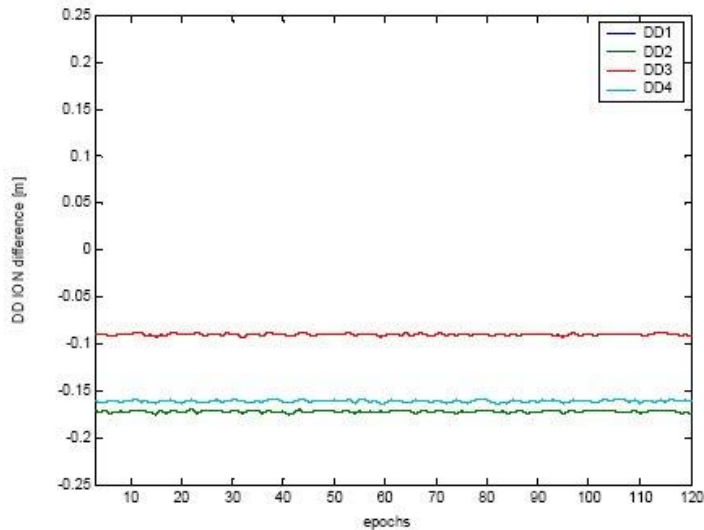


Fig. 17 P4 DD iono differences from the "truth" (day-time)

Smoothed
Pseudorange
Estimates

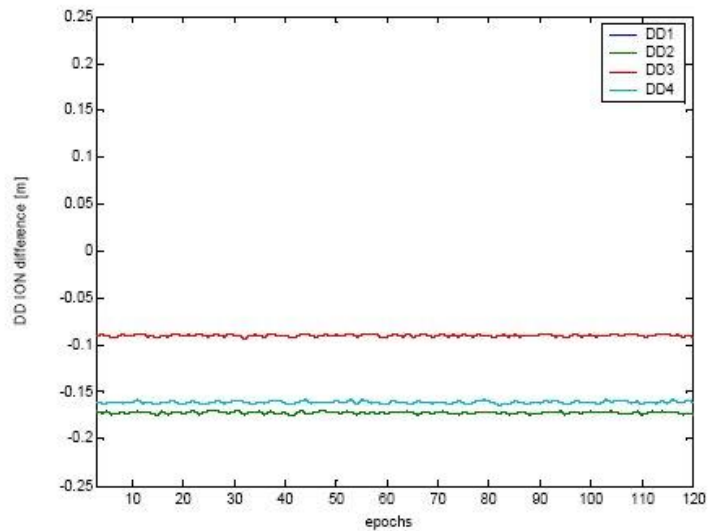


Fig. 18 GIM DD iono (day-time)

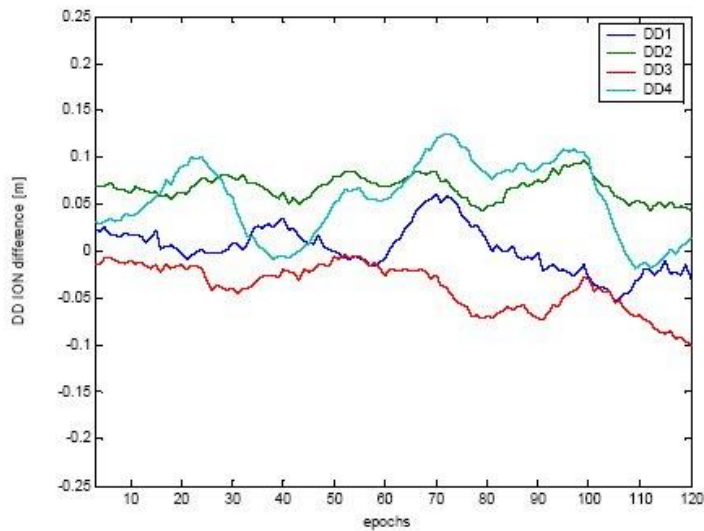


Fig. 19 GIM DD iono differences from the "truth" (day-time)

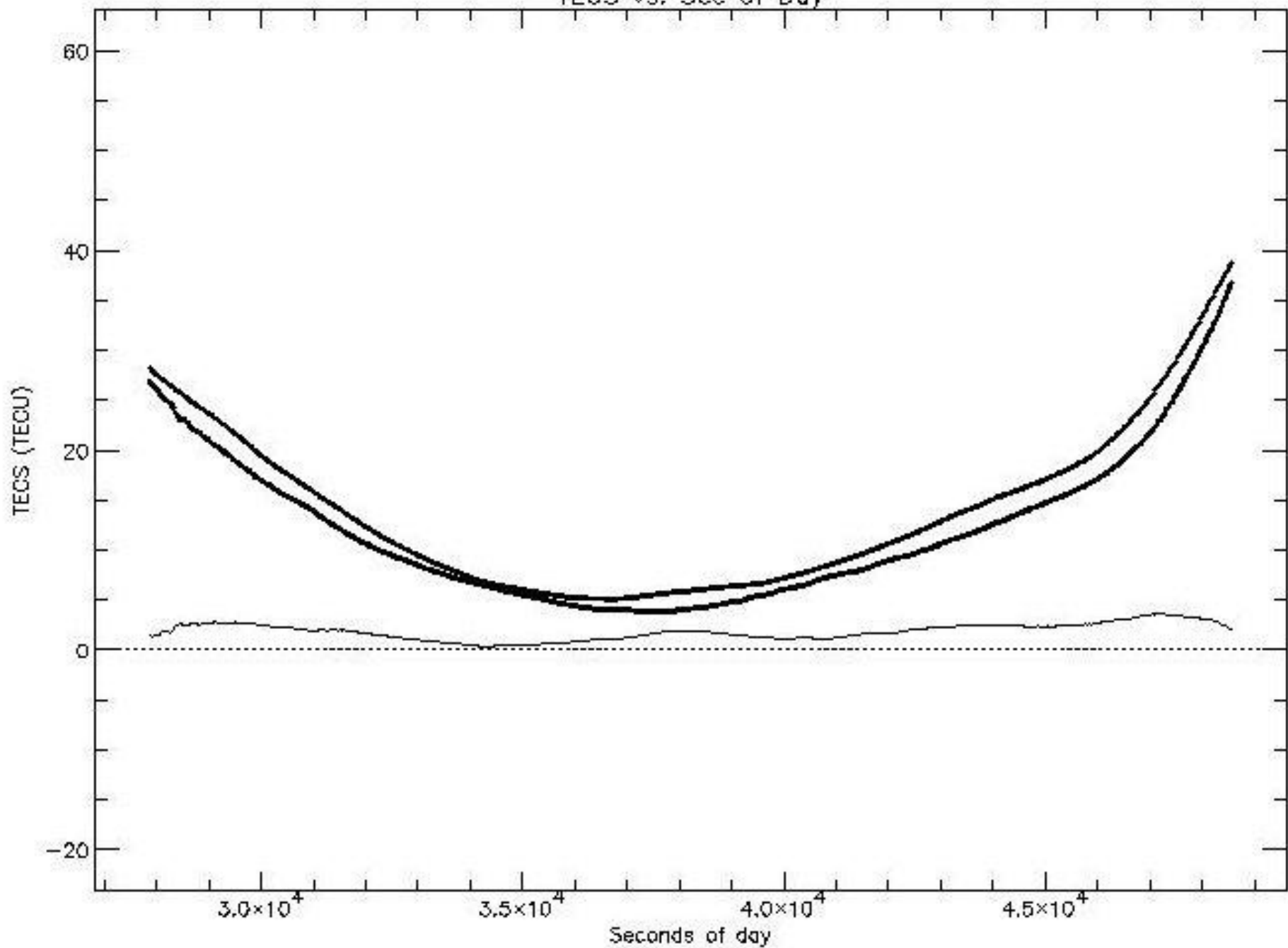
OSU's
MPGPS
method


```

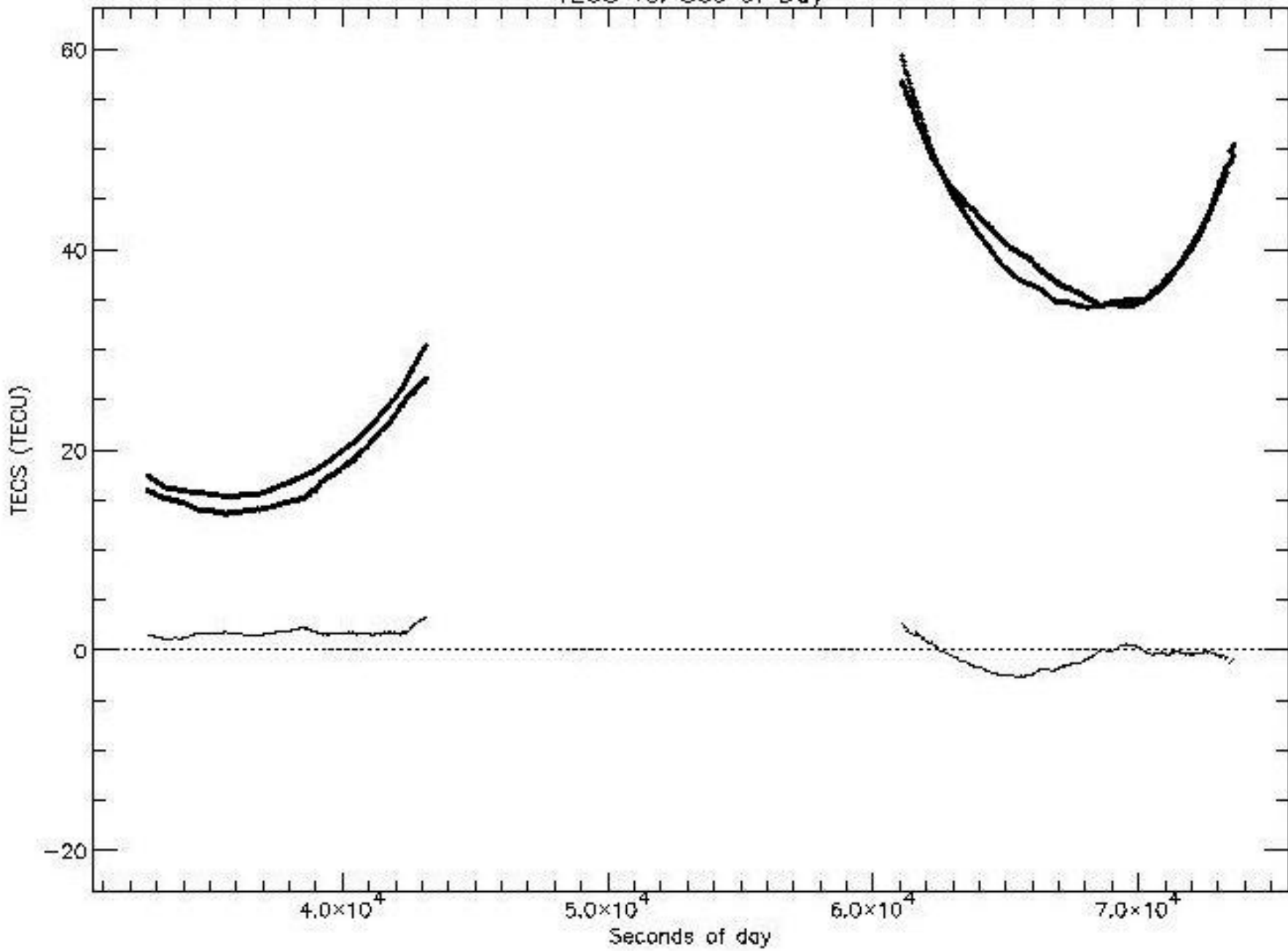
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XXX MARKER NUMBER
CORS/NGS/NOAA OAR/FSL OBSERVER / AGENCY
3735A20424 TRIMBLE 4000SSI 7.19 REC # / TYPE / VERS
3328A68603 TRM14532.00 ANT # / TYPE
-395445.7142 -5271710.3365 3556709.0313 APPROX POSITION XYZ
0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N
1 1 WAVELENGTH FACT L1/2
8 C1 L1 L2 P1 P2 D1 D2 I1 # / TYPES OF OBSERV
30.0000 INTERVAL
Forced Modulo Decimation to 30 seconds COMMENT
2004 1 7 0 0 0.0000000 GPS TIME OF FIRST OBS
This is an IINEX file, not strictly RINEX. COMMENT
The difference is that an I1 variable, representing COMMENT
the computed Ionosphere delay on L1, in cycles of L1, COMMENT
has been introduced. This value should generally COMMENT
always be positive. COMMENT
I1 was computed by Dru Smith, NOAA/NGS with the following COMMENT
parameters (see D. Smith for details): COMMENT
Year = 2004 Day of Year = 007 COMMENT
Shell Height (km) = 0300 COMMENT
Track Cleaning Criteria Index : 001 COMMENT
Crossover Spacing Criteria Index : 001 COMMENT
Tracknet Formation Criteria Index : 009 COMMENT
LSA Weighting Scheme Index : 004 COMMENT
Flag for post-LSA interpolation : 000 COMMENT
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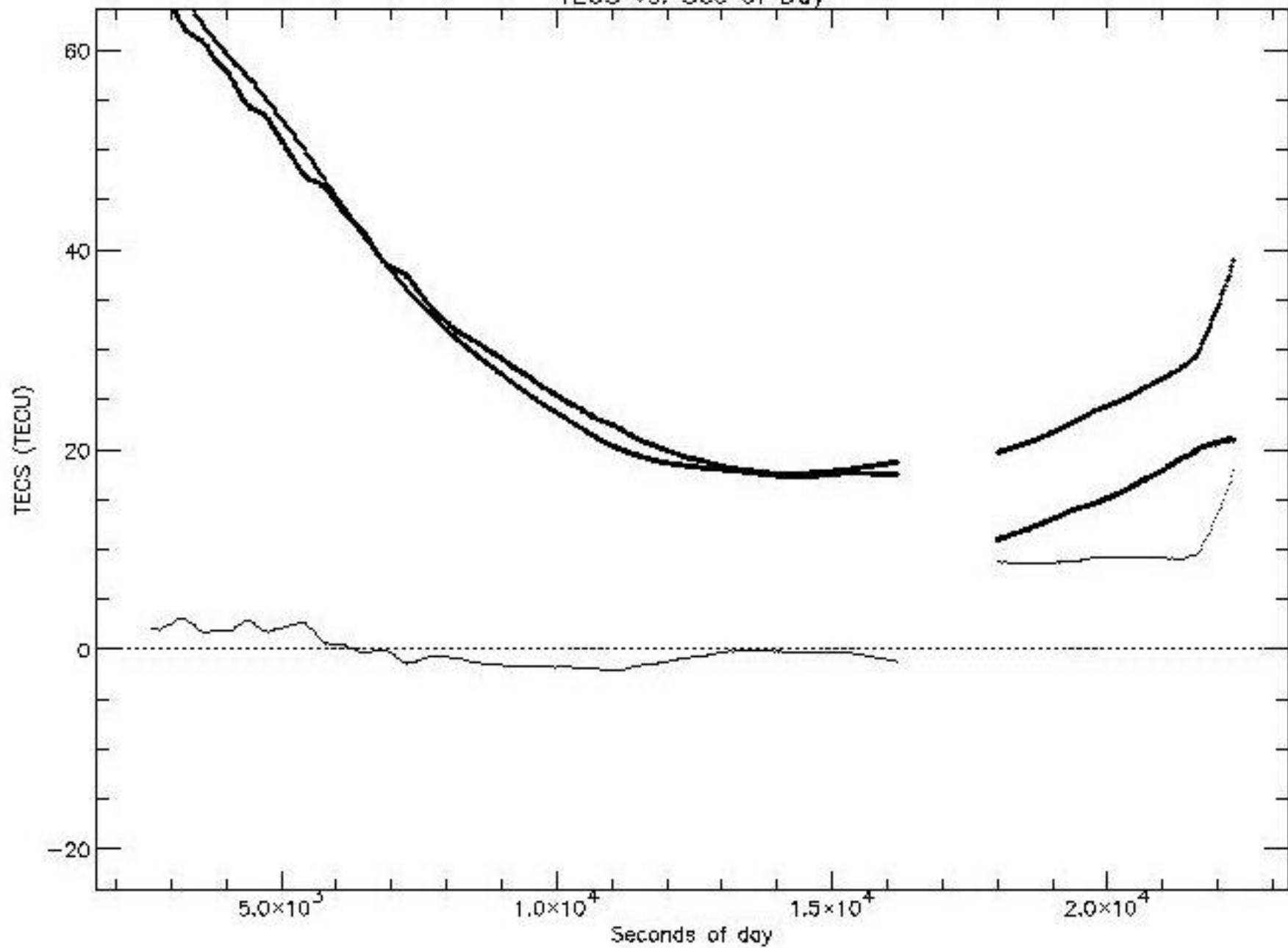
TECS vs. Sec of Day



TECS vs. Sec of Day



TECS vs. Sec of Day



Five IGS Global Models

This model

