



GNSS Surveying Update in Oregon

**Civil GPS Service Interface Committee
States & Local Government Session
20 September, 2010**

**Ken Bays, PLS
Lead Geodetic Surveyor, Oregon DOT**



Oregon DOT Geometronics Unit



Ron Singh, Chief of Surveys, Manager

Geometronics

Photogrammetry

Survey Operations

Right-of-Way Engineering

Geodetic Control



Oregon DOT Geometronics Unit Geodetic Team's Mission

- ◆ Revive and enhance Vertical and Horizontal Geodetic Control in Oregon
 - Application of Height Modernization to move towards accurate GPS-derived heights rather than replacing passive benchmarks
- ◆ Develop a state network of Continuously Operating GPS Stations

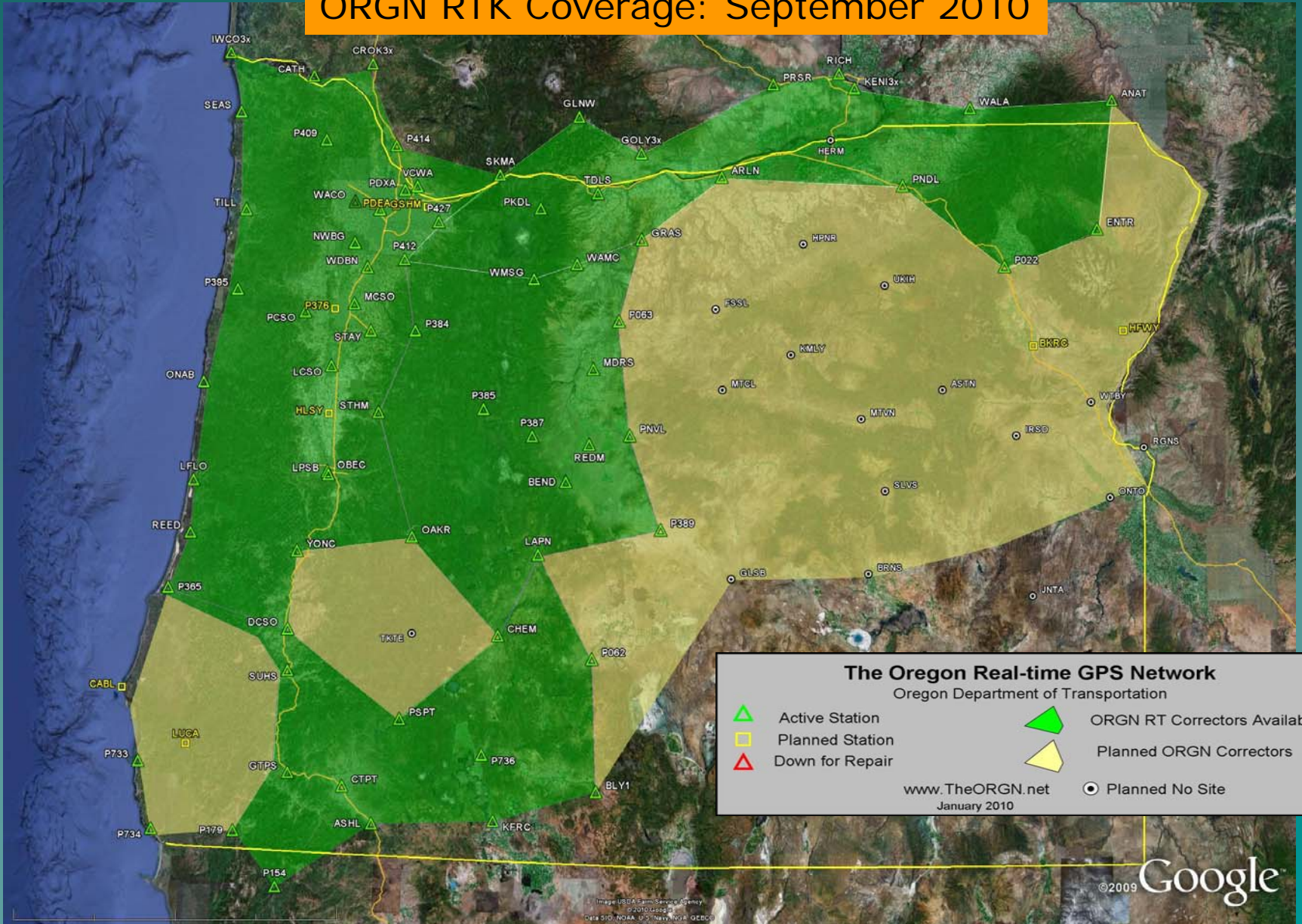


Summary

- ◆ Update on status of the Oregon Real-time GPS Network (ORGN)
- ◆ The Oregon Coordinate Reference System (OCRS)
 - Low distortion mapping projections
- ◆ Design to Dozer: Computer Controlled Heavy Machinery Demo
- ◆ ORGN preparations for the upcoming change in NAD 83 datum realization for the NGS National Spatial Reference System:
 - a software “tool” for data conversion between the new and the superseded datum realizations.

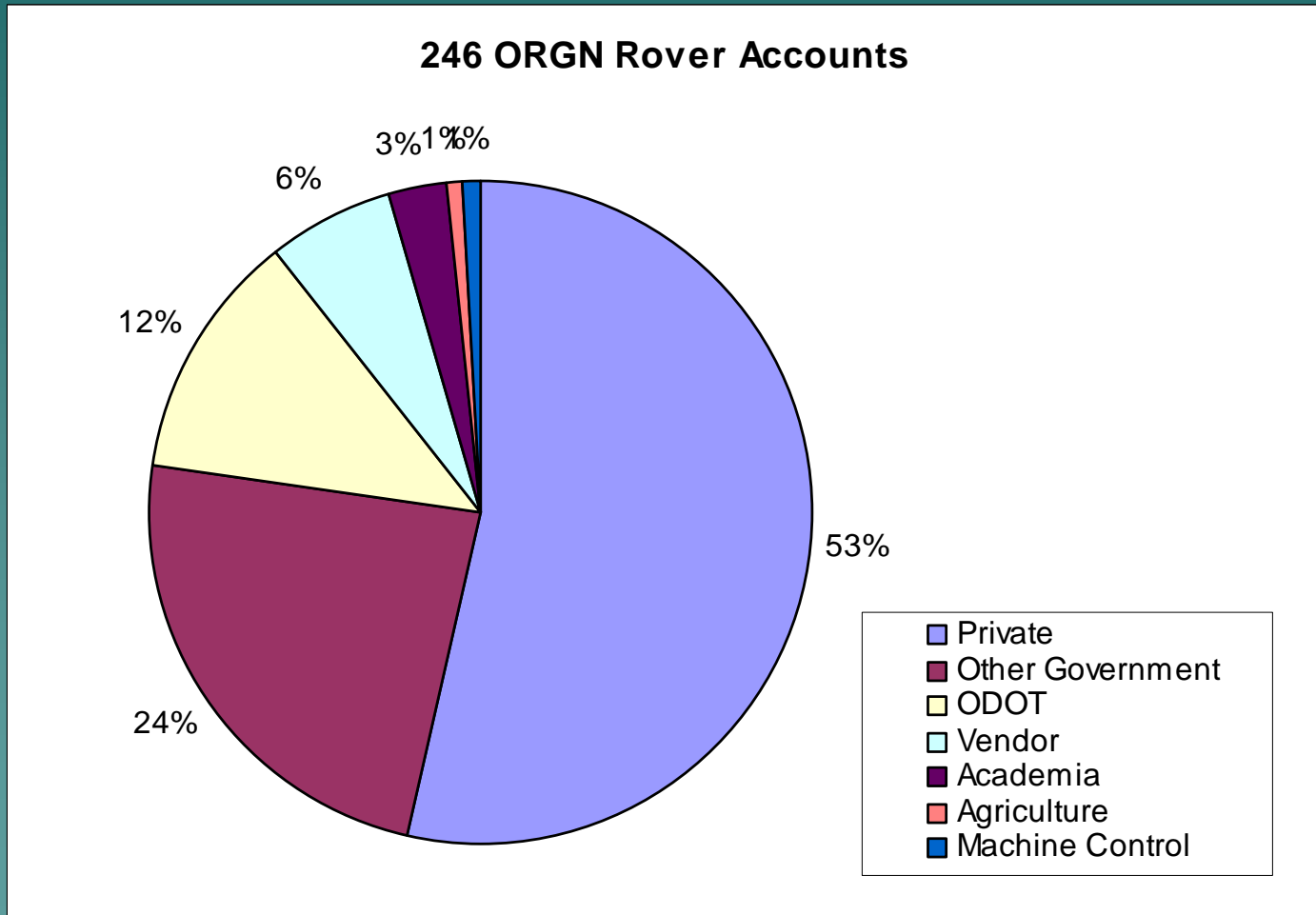


ORGN RTK Coverage: September 2010



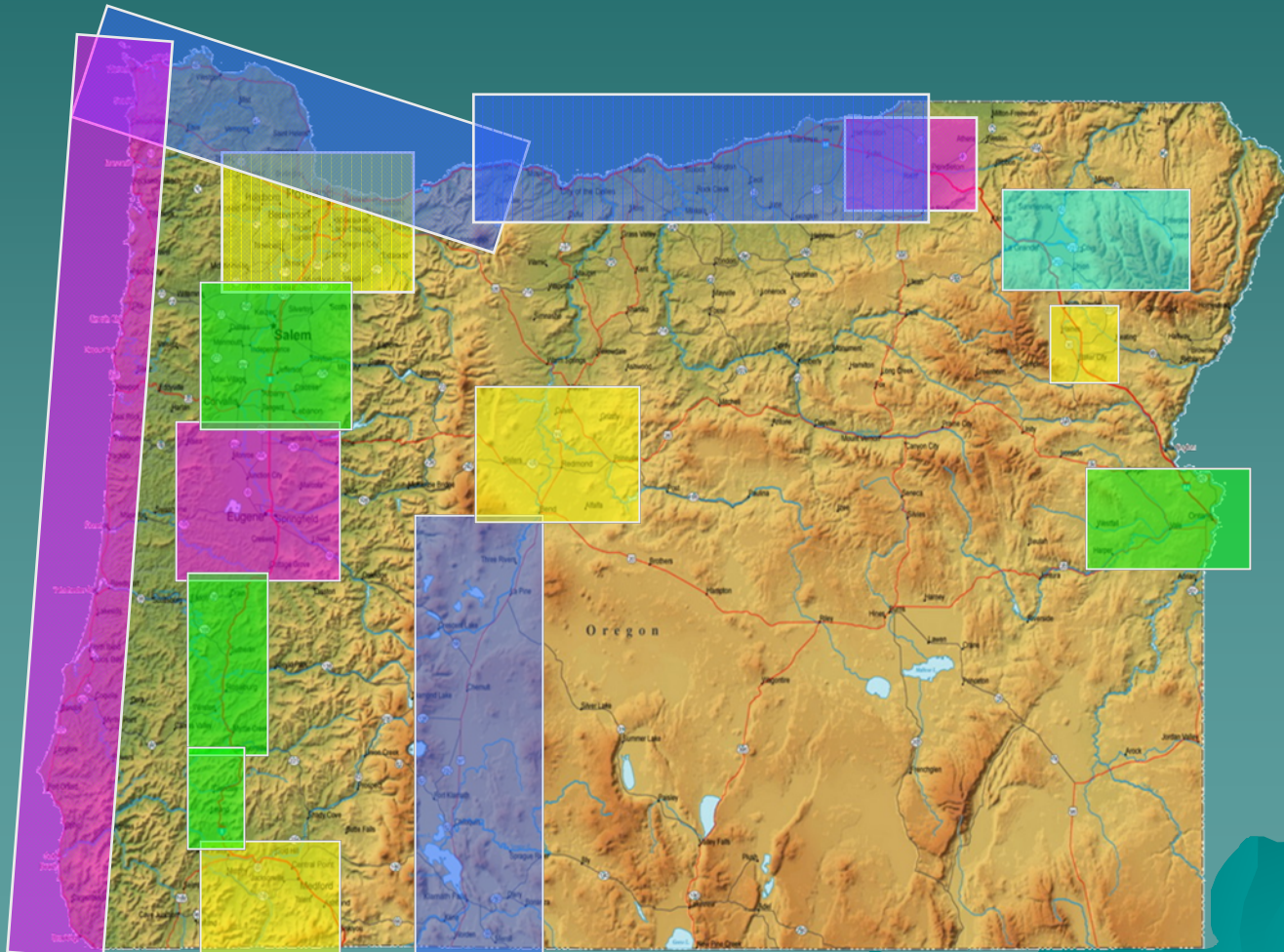


ORGN Rover Accounts: Sept 2010





Oregon Coordinate Reference System



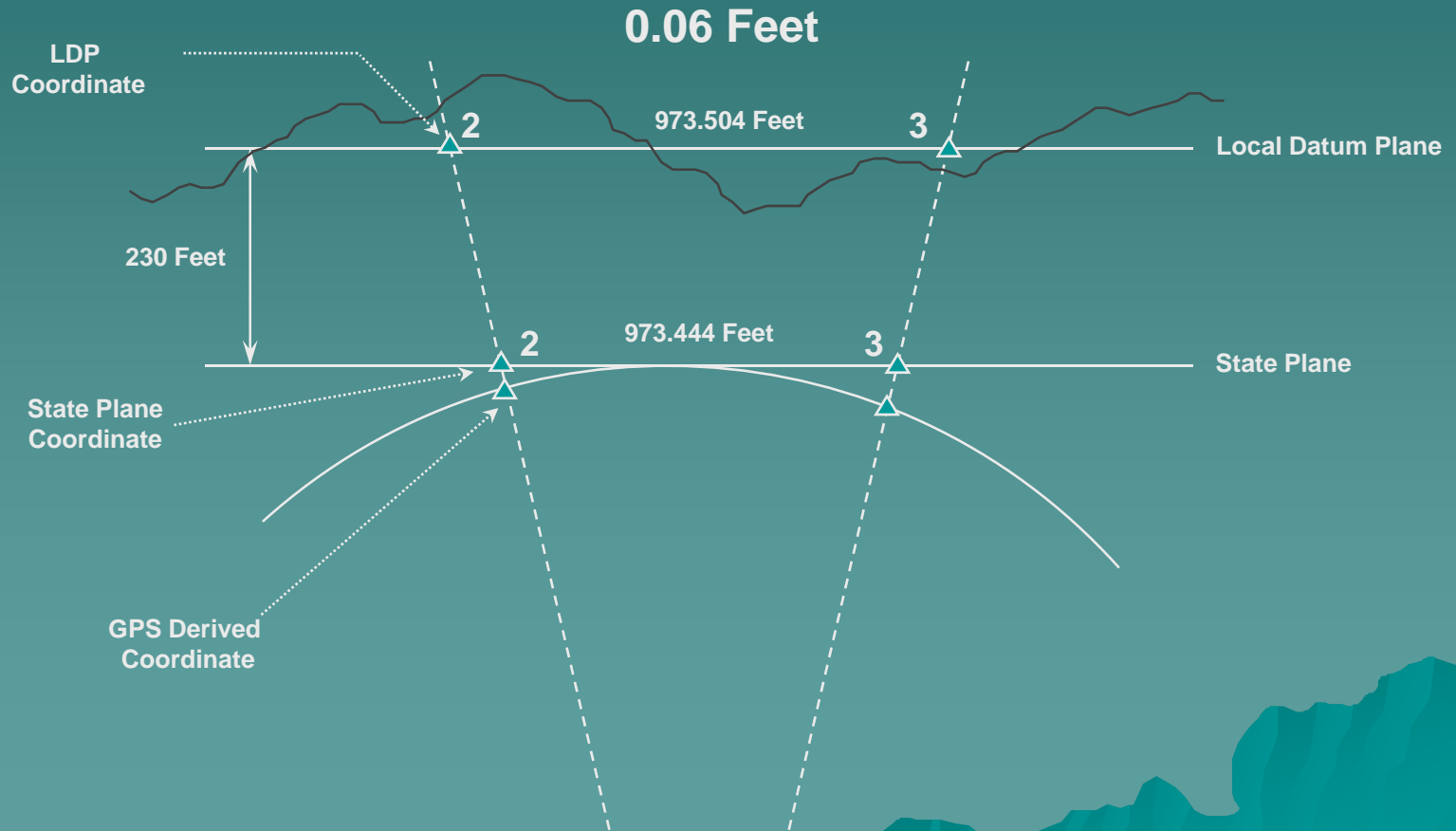


Oregon State Plane Coordinate System



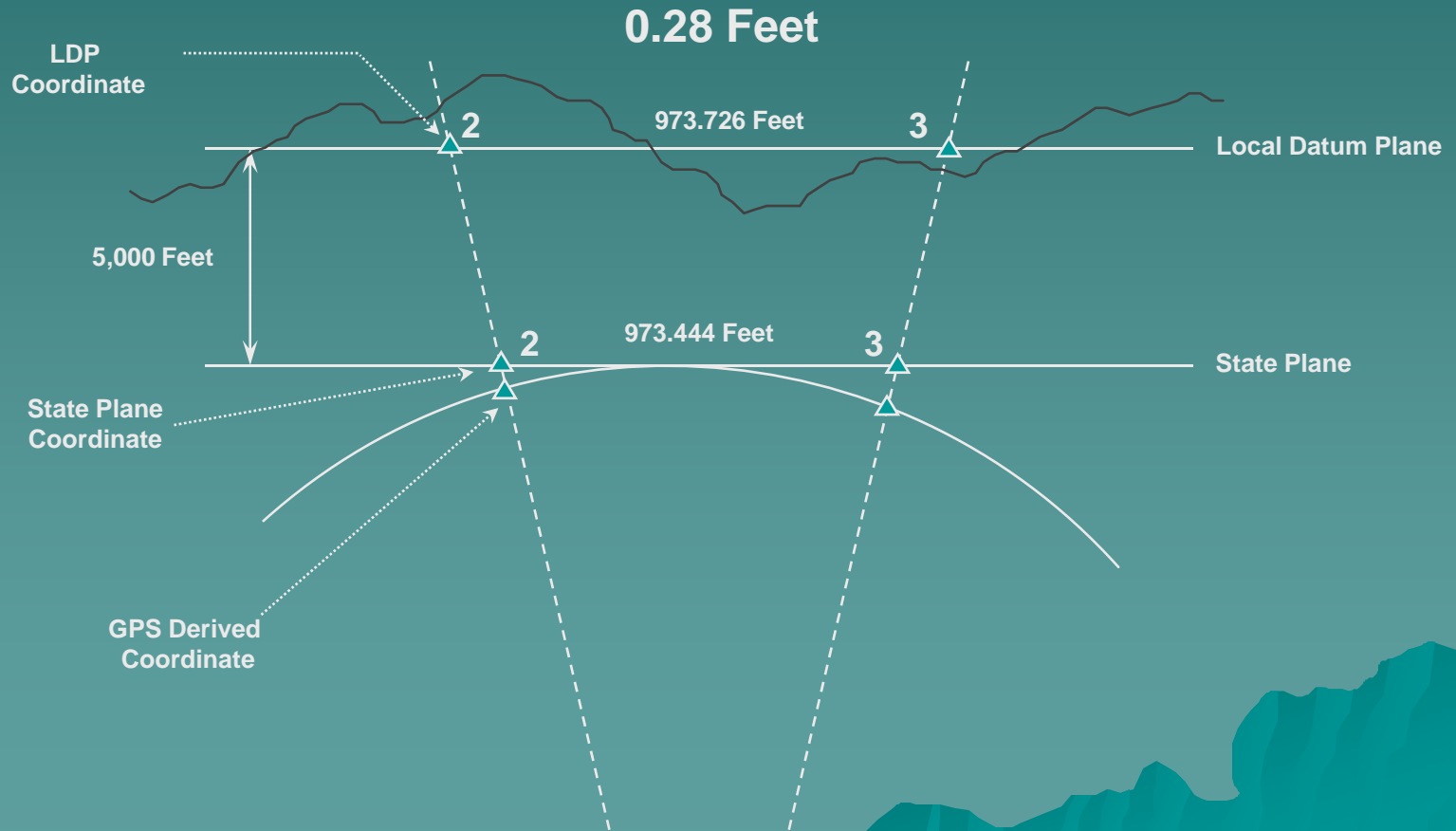


Distortion Due to Elevation



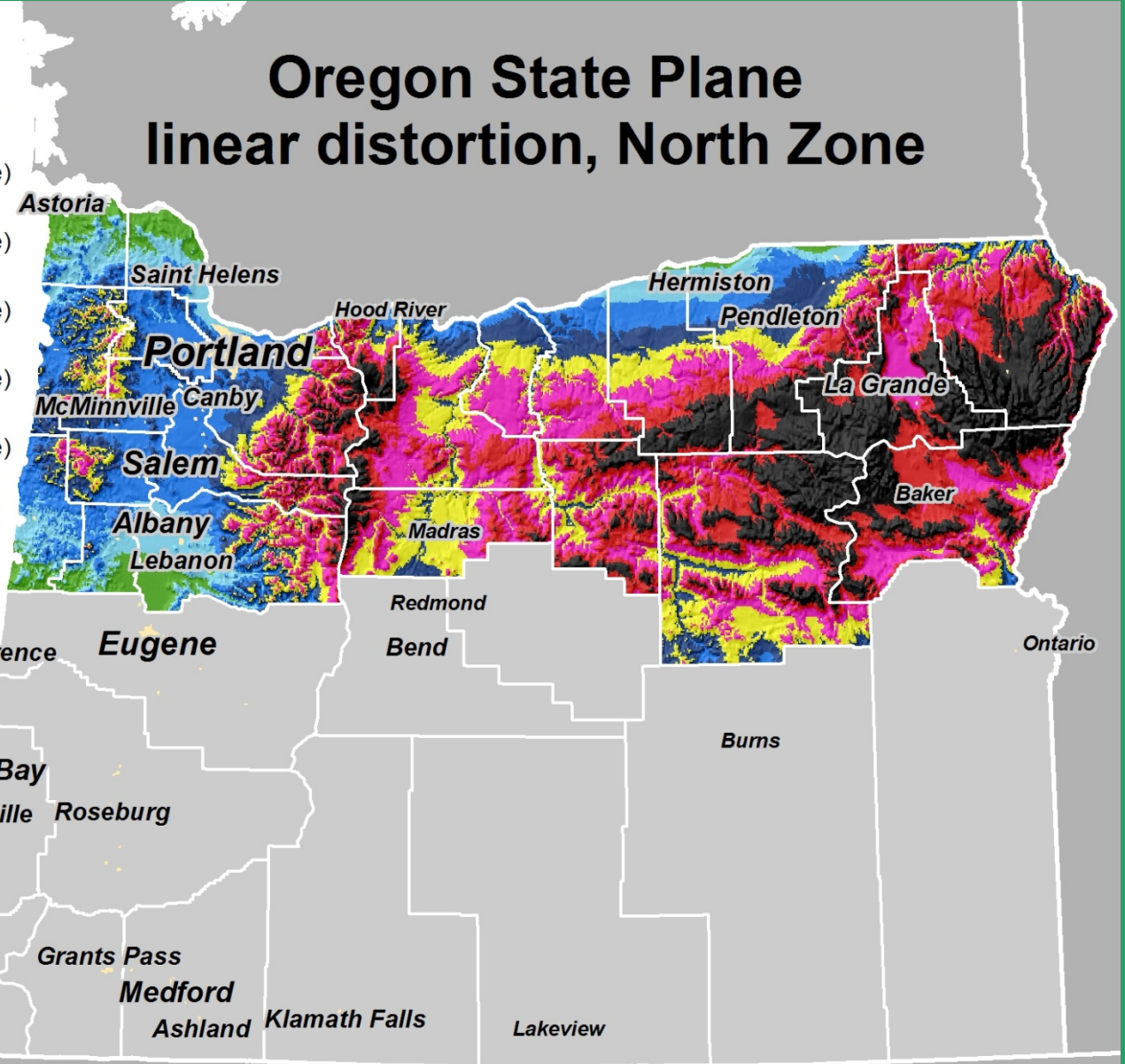
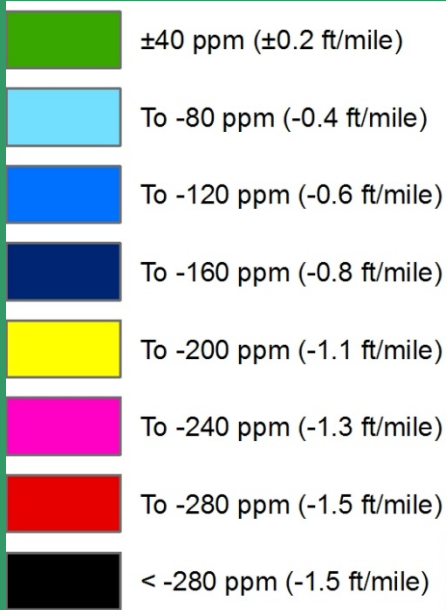


Distortion Due to Elevation

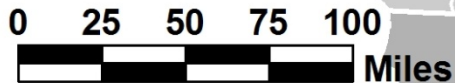




Oregon State Plane linear distortion, North Zone

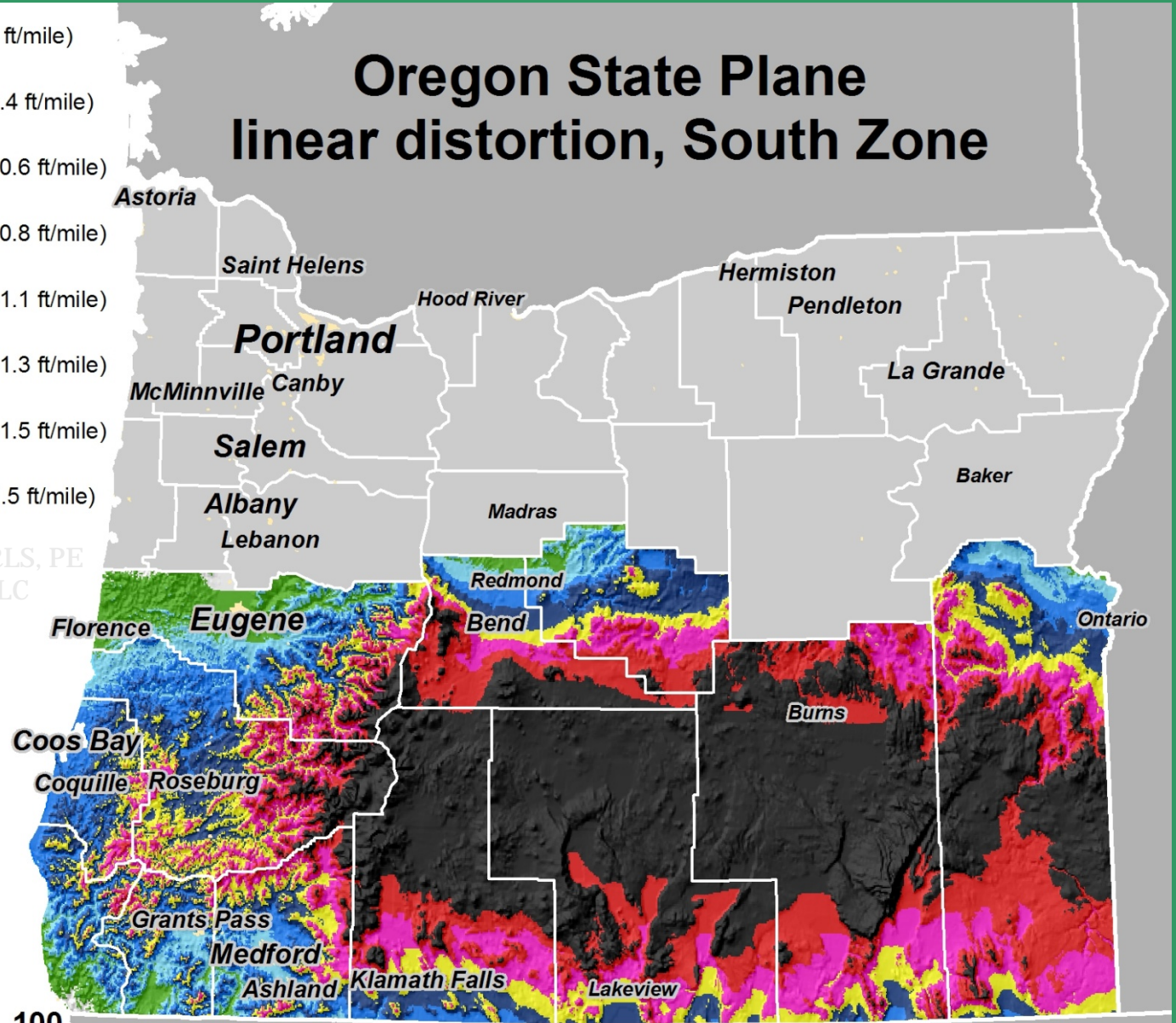
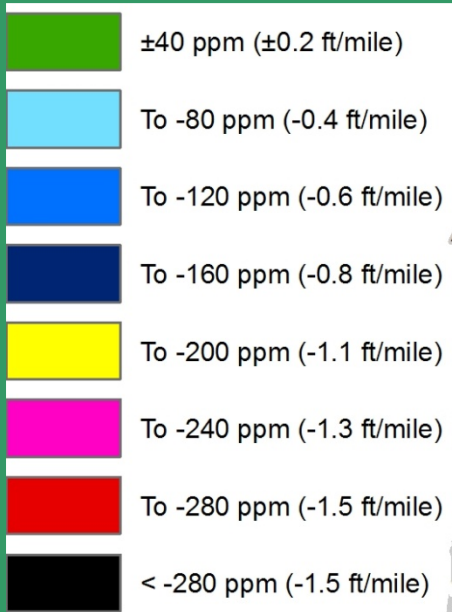


Michael L. Dennis, RLS, PE
Geodetic Analysis, LLC

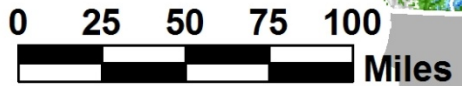




Oregon State Plane linear distortion, South Zone



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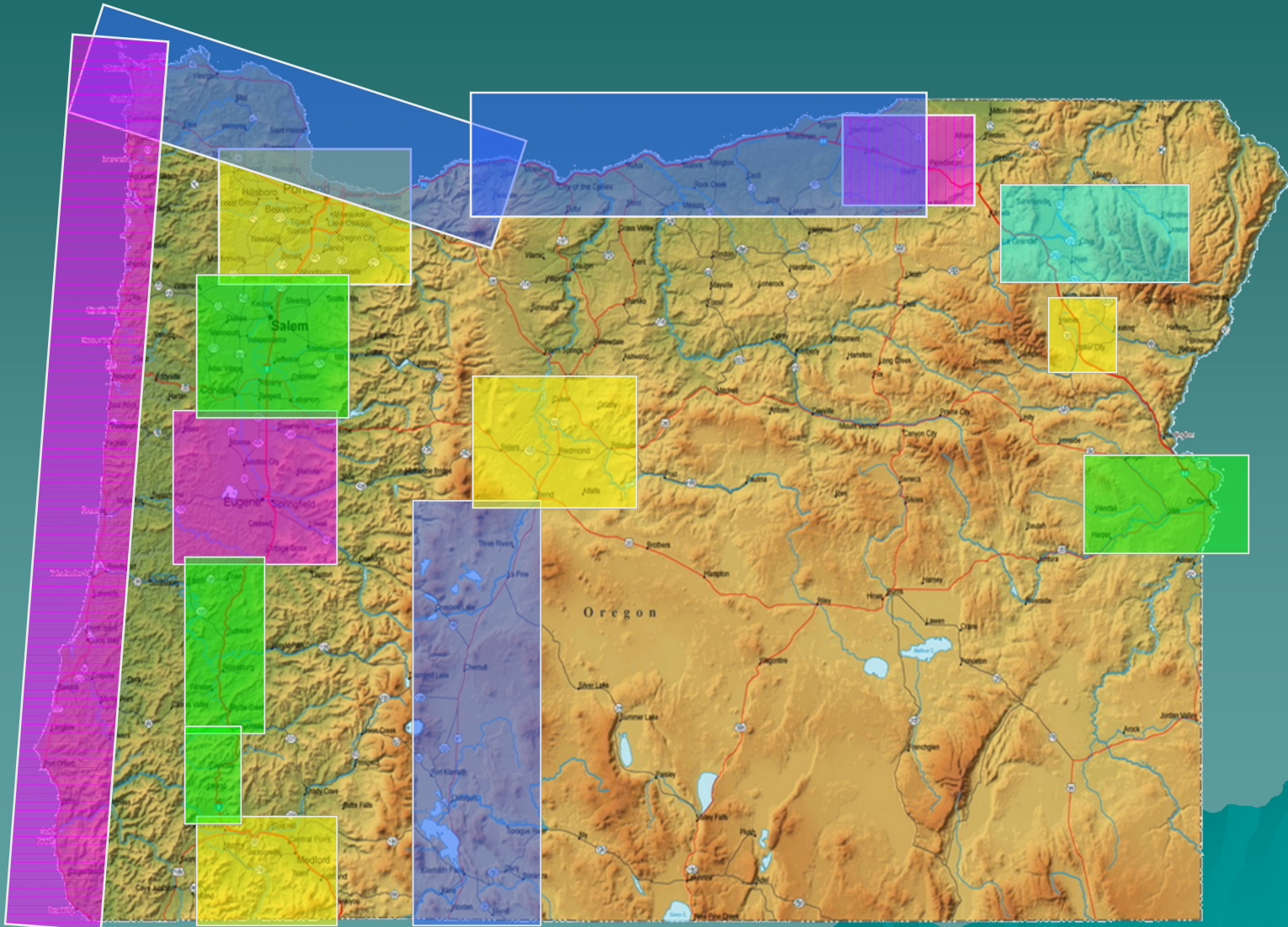


Problems with SPC System

- Does not represent ground distances
- Does not minimize distortion over large areas
- Does not support modern surveying accuracy requirements



Oregon Coordinate Reference System (OCRS)





Initial Steps

- Determined interest amongst the Surveying and GIS community in Oregon
- ODOT/ Oregon GPS User Group Co-sponsored statewide informational workshop on low distortion projections
 - Speakers from NGS, academia, private
- Developed test zones
- Field tested initial zones
- Developed 15 initial zones to cover major transportation corridors.



Best Practices

- Should be tied to the National Spatial Reference System
- Must be a collaborative effort with Federal, State, Local, academic, and private parties
- The Oregon Real-Time GPS Network must facilitate the use of the OCRS
- Not constrained to monuments



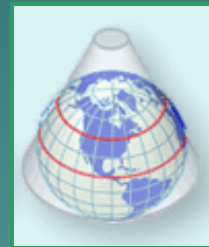
Best Practices

- Identify all custom projections in use in Oregon
 - Attempt to incorporate these existing projections into the statewide system
- Involve NGS
- Involve GIS community
- Involve the local users
- Involve the software vendors



Best Practices

- Use a single reference ellipsoid – GRS80
- NAD83 utilizes GRS80
- Use 3 projections types:
 - Lambert Conformal Conic
 - Oblique Mercator
 - Transverse Mercator





Best Practices

- Select maximum distortion values
- Select Distance Units
 - Meters
 - 1 International Foot = 0.3048 meters exactly
- Metadata – document thoroughly
- Register OCRS with NGS

Although the projection is defined in meters, the resulting coordinates are in International Feet

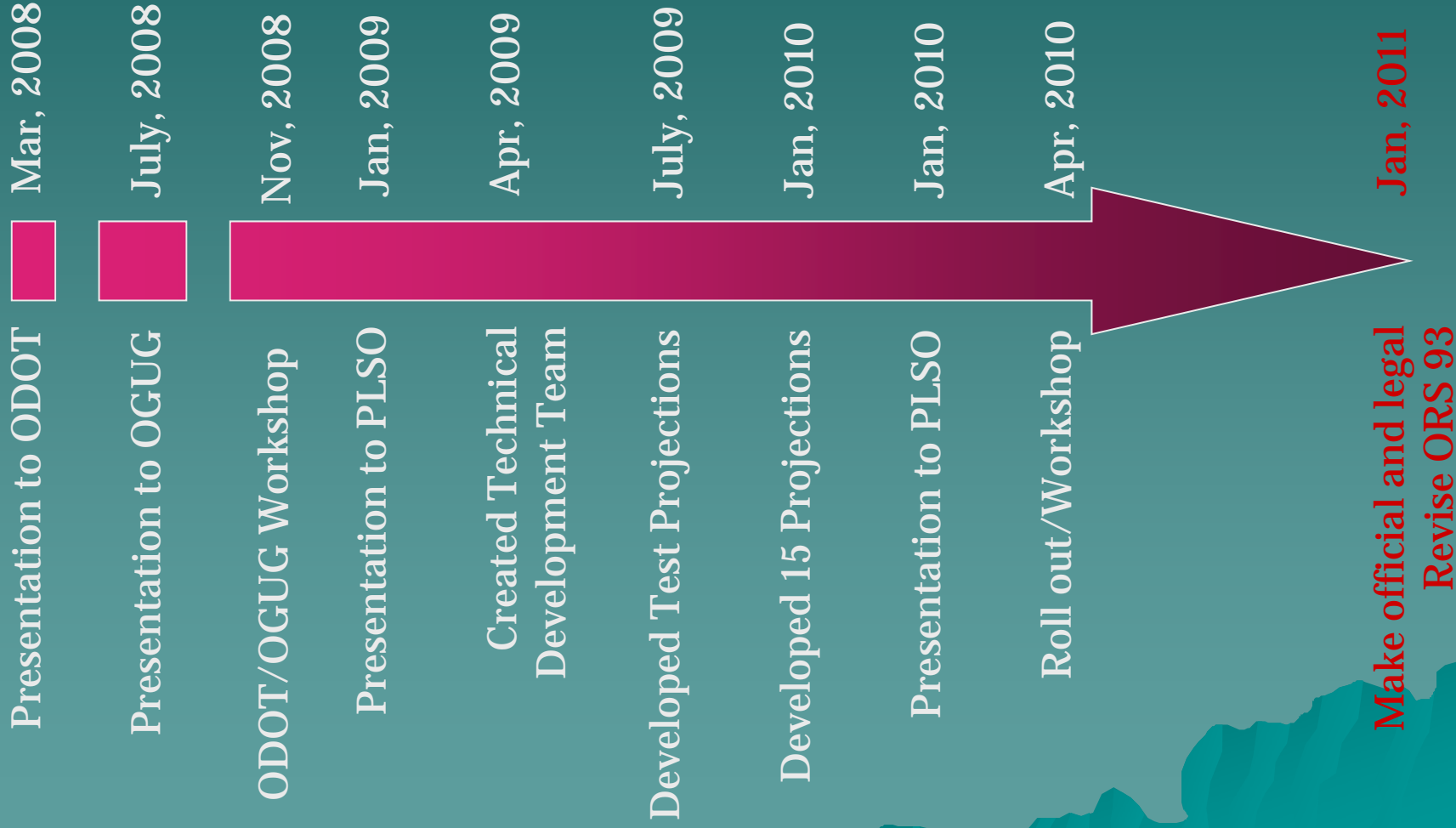


Next Steps

- Supplement – not replace - the existing Oregon State Plane System with multiple predefined Low Distortion Projections
- Evaluate integration with the ORGN
- Develop User Handbook
- Roll-out and Training
- Legislative changes to authorize use
 - Revise Oregon Revised Statutes 93 and 209

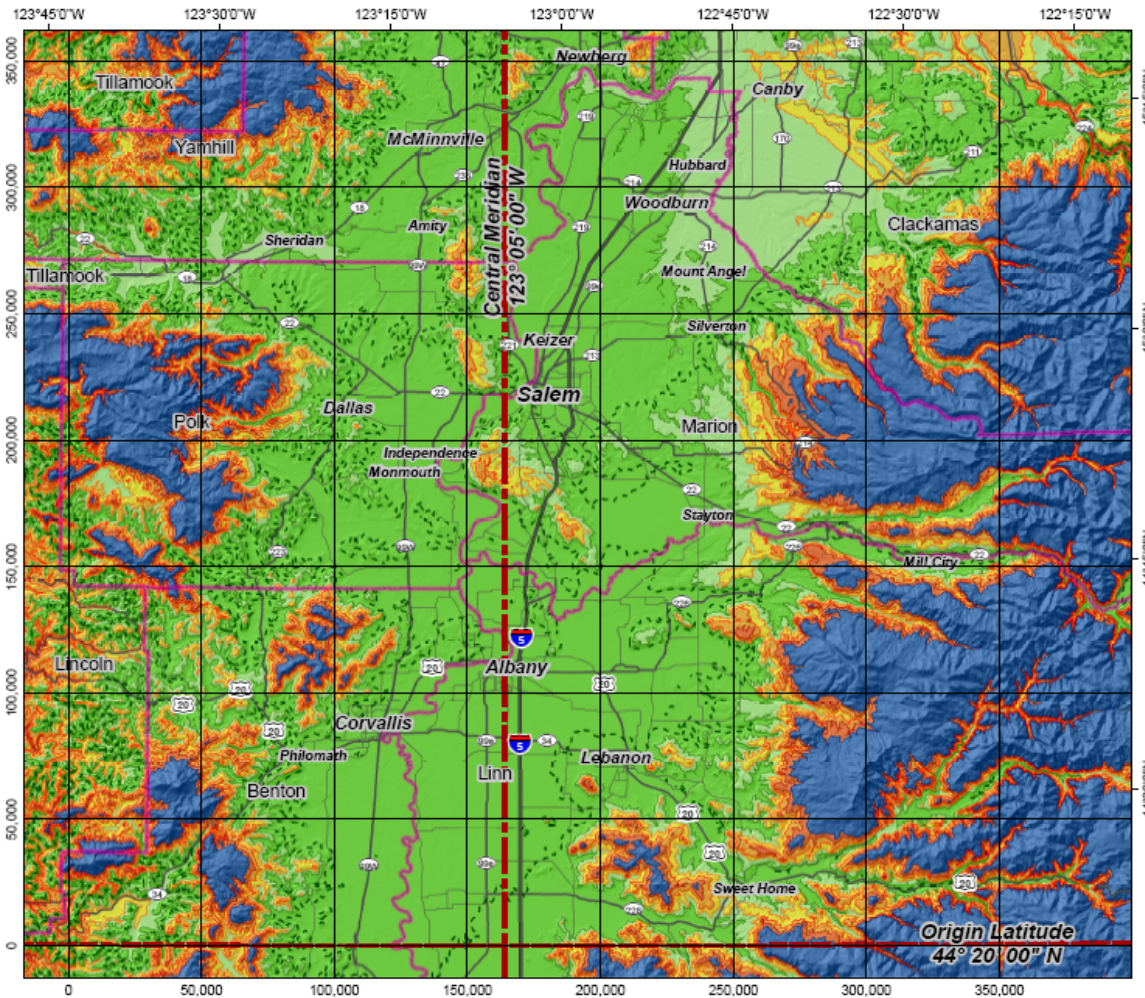


History





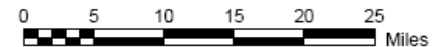
Oregon Coordinate Reference System



Oregon Coordinate Reference System Salem Zone

**Transverse Mercator projection
North American Datum of 1983**

Latitude of grid origin: 44° 20' 00" N
Central meridian: 123° 05' 00" W
False northing: 0.000 m
False easting: 50 000.000 m
Central meridian scale: 1.000 010 (exact)



NOTE: Map grid is shown in units of international feet.

Linear distortion

- Zero distortion
- < -50 ppm (< -0.25 ft/mi)
- ±10 ppm (±0.05 ft/mi)
- 10 - 20 ppm (0.05 - 0.1 ft/mi)
- 20 - 30 ppm (0.1 - 0.15 ft/mi)
- 30 - 40 ppm (0.15 - 0.2 ft/mi)
- 40 - 50 ppm (0.2 - 0.25 ft/mi)
- > +50 ppm (> +0.25 ft/mi)

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Design to Dozer Demonstration Computer Controlled Heavy Equipment



17-18 August, 2010



- ◆ Oregon DOT is poised for automation of:
 - Surveying
 - Design
 - Construction Administration



Demo Team

- ◆ Oregon Department of Transportation –
 - Geometronics Unit Staff
 - Brian Ngo – Region 1 Design
- ◆ Wildish Companies - Land Use and Dozer
- ◆ K&E Excavating, Inc. - Machine Control Construction
- ◆ Pacific Excavation, Inc. - Machine Control Construction
- ◆ PPI Group - Machine Control Support
- ◆ Bentley Systems - 3D Design Support
- ◆ SiTech Norcal - Machine Control Support



Undeveloped site





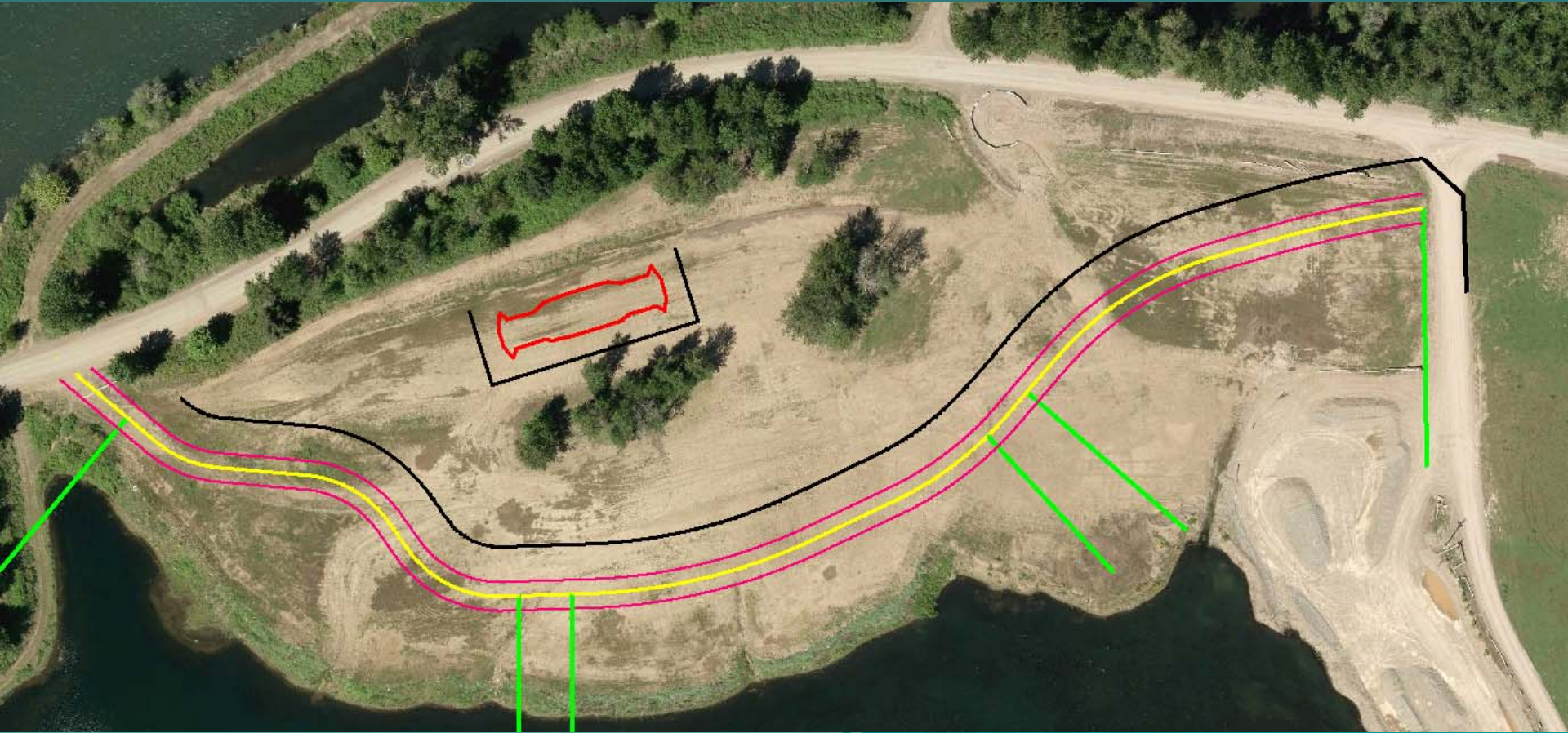
Pre-design Survey



- ◆ Geodetic Control:
 - Oregon Real-time GPS Network
- ◆ Coordinate System:
 - Oregon Coordinate Reference System



3-D Design





3-D Design





Design input into heavy equipment





Computer Controlled Construction





Section of Sub-grade completed





Visualization of Paved Surface





Datum Realization Conversion Software “Tool” for Oregon



What Datum is the ORGN on?

NAD 83 (CORS 96) (Epoch 2002)

The ORGN is aligned with the NGS CORS via OPUS solutions on ORGN stations.



What the “Tool” will do:

- ◆ **Converts users positions back and forth from:**

- NAD 83(CORS96)Epoch2002
[The current OPUS (and ORGN) datum realization]

to/from

- NAD 83(CORS96'a')Epoch2010.5(?)
[The future OPUS (and ORGN) datum realization]



Who will benefit from the “Tool”

- ◆ An ODOT project for the benefit of:
 - Oregon Real-time GPS Network (ORGN) users
 - Oregon OPUS-Static users
 - Oregon high accuracy GIS users
 - Other surveying, engineering stakeholders in the State of Oregon

We are planning ahead!





Who is developing the “Tool”

- ◆ Michael Olsen, Assistant Professor of Geomatics, Oregon State University is developing the mathematical algorithms and software.
- ◆ Cooperation, input, and assistance from:
 - Oregon DOT Geometronics Unit
 - Mark Armstrong, NGS State Geodetic Advisor for Oregon

We are planning ahead!





Why do ORGN users in Oregon need this Tool?

- Will ensure continuity within projects
 - ◆ User may keep a single datum realization for a project spaced over the change from the superseded to the new datum realization.
- Provides an immediate datum realization transition solution until user projects are solely within the new datum realization
- Keep ORGN Manager's phone from ringing off the hook!



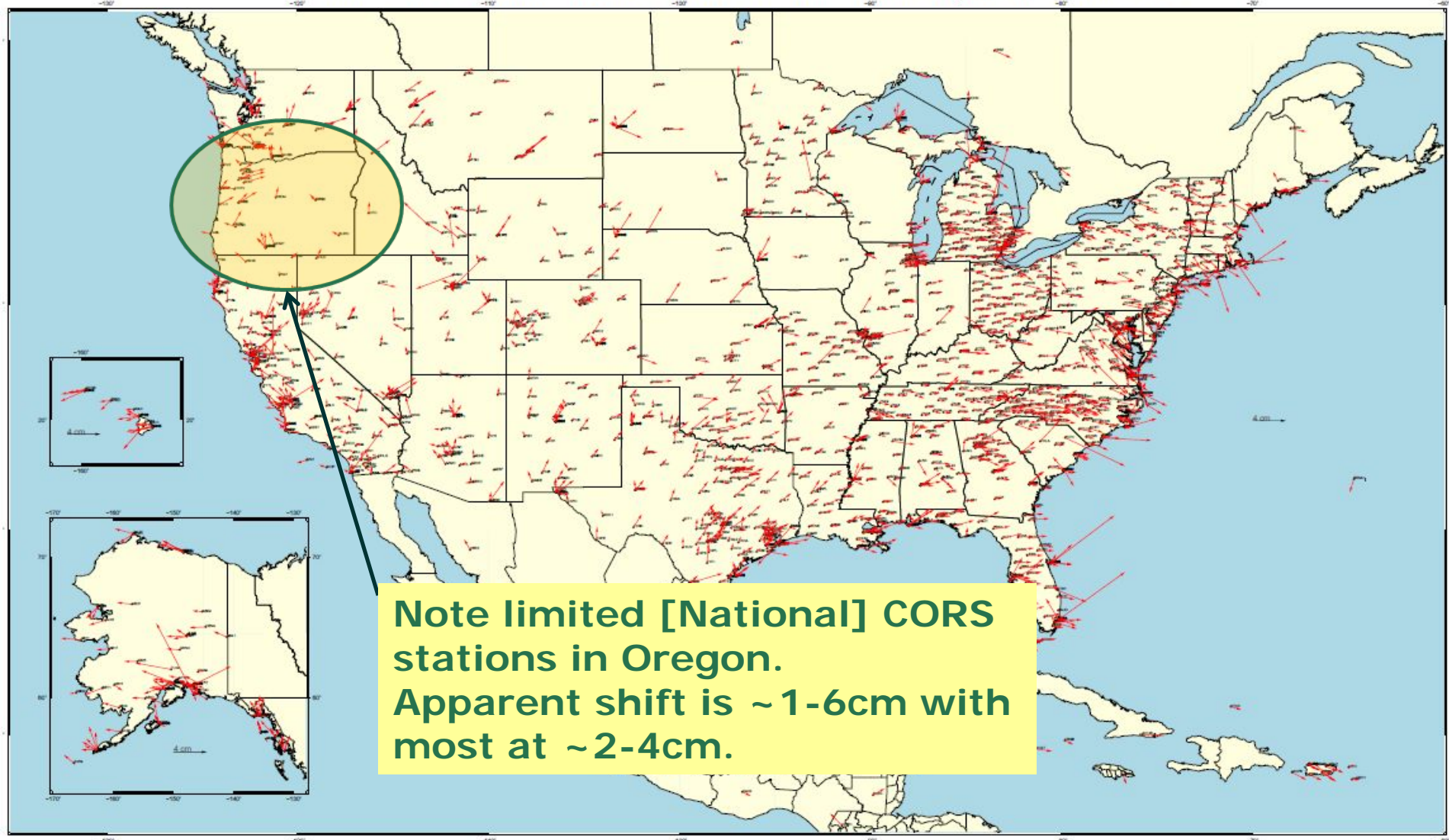
Details of the “Tool”

- ◆ To achieve the required sub-cm level of accuracy, data from all of the ~125 CORS in and surrounding Oregon, not only from the NGS National CORS, will be included in the data model for the “Tool”.
 - **Only ~25 NGS National CORS within Oregon** (not enough data points uniformly spaced for the best solution possible.)
 - The Oregon Real-time GPS Network makes use of many CORS which have not been submitted to the NGS as co-op CORS.
 - Generally speaking, OR, WA, CA (west coast) have more movement (shift) between the two datum realizations than other CONUS regions.



2D differences ITRF2008P(NGS) – ITRF2000 aligned to ITRF2008P @2010.0

Horizontal Geometric Differences [ITRF2008P(NGS) – ITRF2000(NGS)_{aligned to ITRF2008P}] @ 2010.0

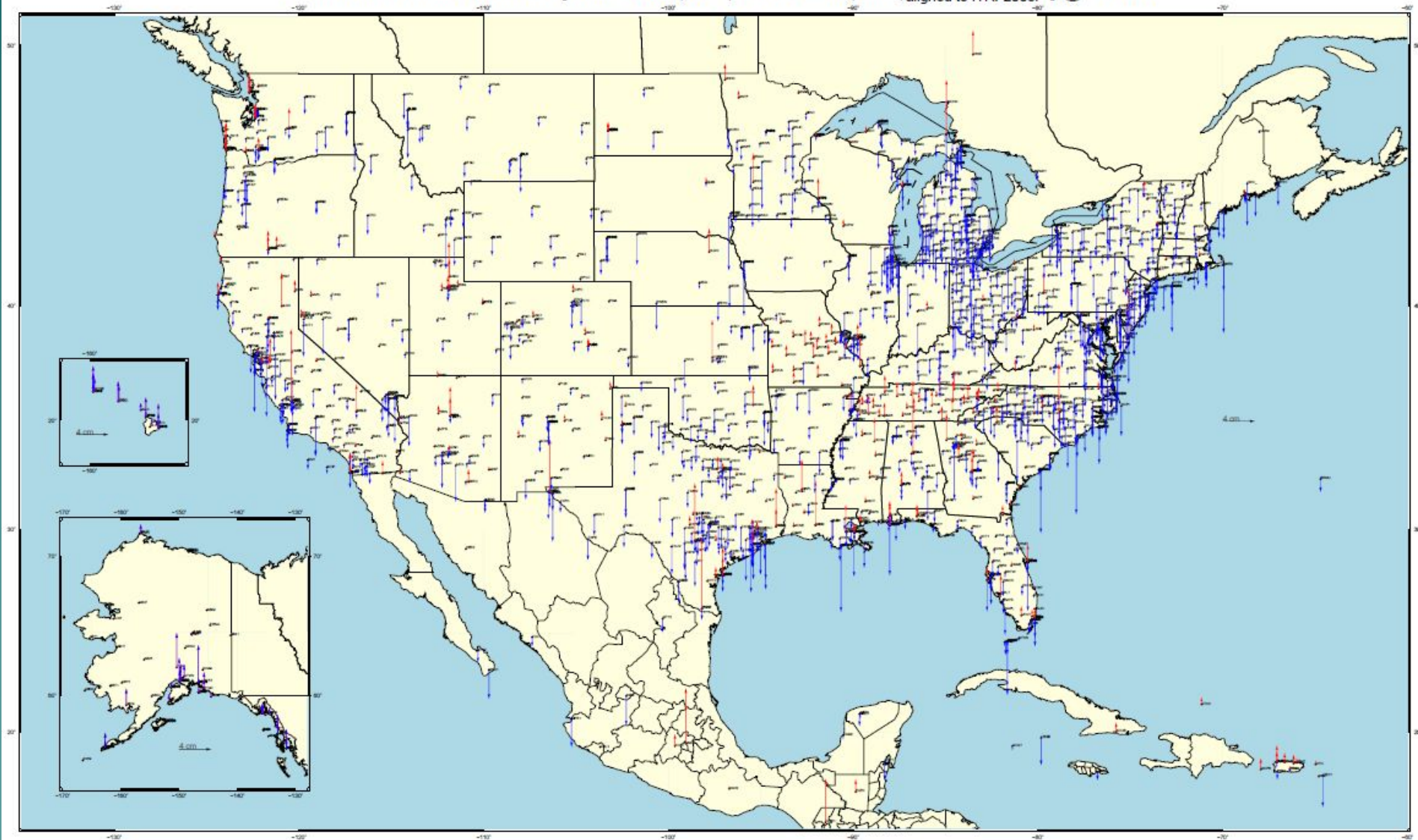


Note limited [National] CORS stations in Oregon. Apparent shift is ~1-6cm with most at ~2-4cm.



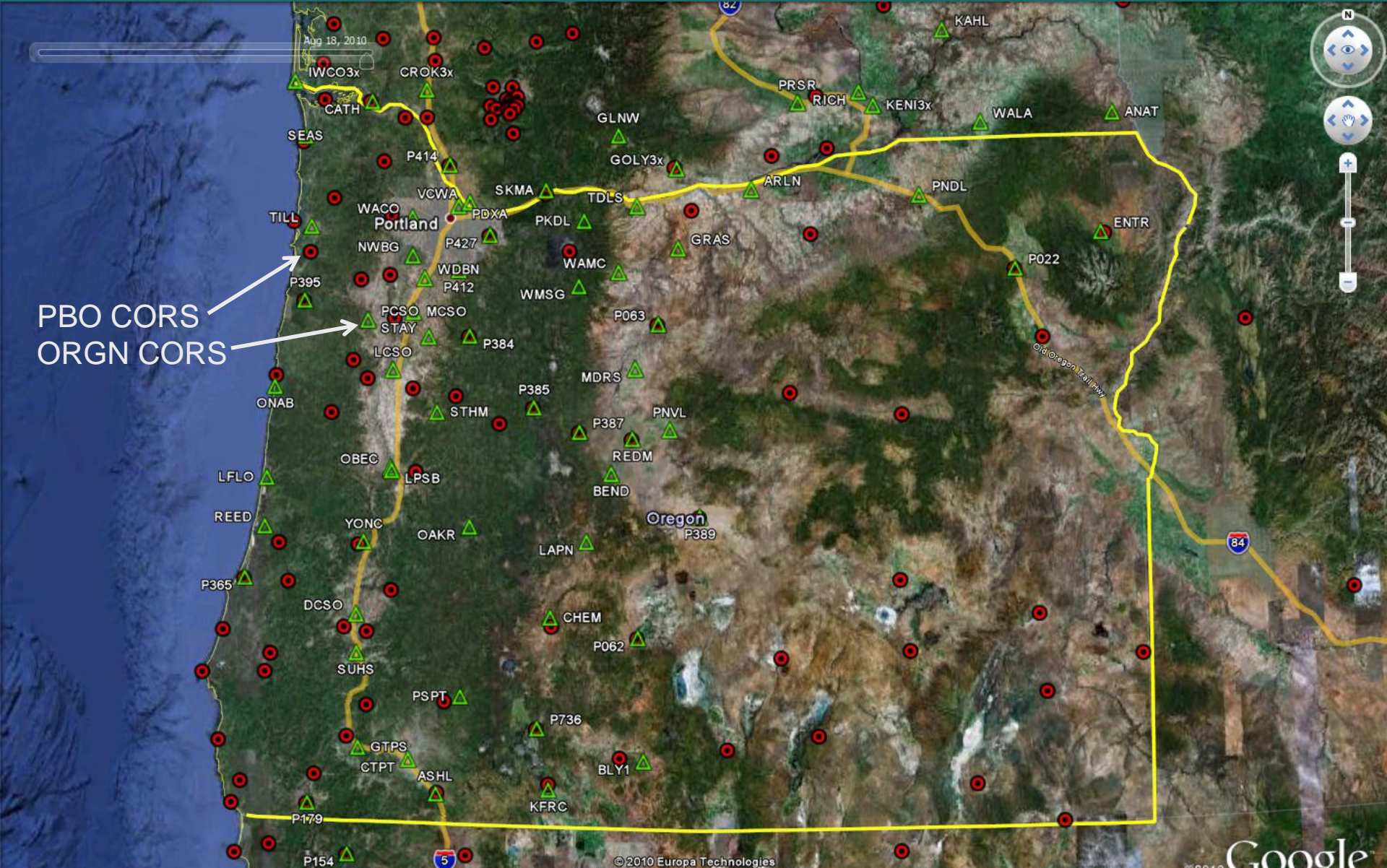
Vertical Differences

Vertical Geometric Differences [ITRF2008P(NGS) – ITRF2000(NGS)_{aligned to ITRF2008P}] @ 2010.0





CORS Used in the "Tool" data model





How the Oregon OPUS Datum Conversion Tool (ODCT-OR) is being developed

◆ For the current OPUS datum realization:

1. For the period August 1-10, 2010, download 10 days of 24-hour RINEX files from the ~125 OR, WA, CA CORS stations: NGS, ORGN, PBO, ORGN, WSRN
2. Submit the ~1250 files to present realization of OPUS-S
3. Mean the 10 daily OPUS solutions for each CORS.
4. The mean 3D position then entered into software as input data.



How the Oregon OPUS Datum Conversion Tool (ODCT-OR) is being developed

- ◆ For the new OPUS datum realization, input data per the same steps as before:
 - Note that for step (3), the submissions to OPUS will occur after OPUS reports solutions in the new NAD 83 (CORS96'a') Epoch 2010.5(?) datum realization.
 - Also, the OPUS engine may use a different process at that time.
- ◆ The two different geodetic positions recorded for each of the CORS will reflect the exact lat/long/elevation differences between the two datum realizations.

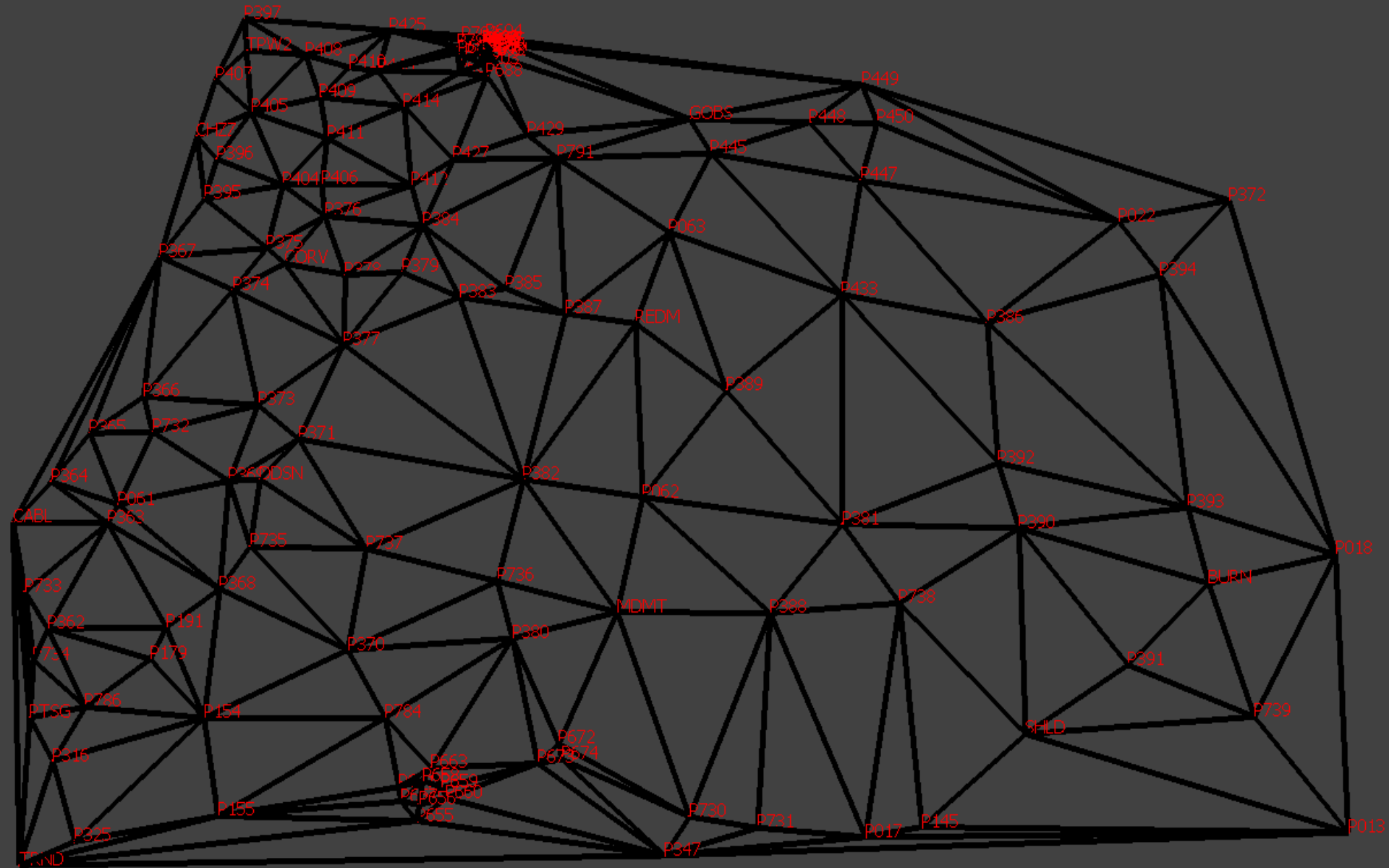


The Software “Tool” will:

- ◆ Calculate ΔX , ΔY , Δh for each CORS station (described previously)
- ◆ Create an optimized Delaunay triangulation using the ~125 CORS stations in Oregon
- ◆ Allow user input of a file of points to convert
- ◆ Program determines which triangle each input data point is in.
- ◆ For each point, ΔX , ΔY , Δh are interpolated from the CORS stations forming the triangle in which the point is located
- ◆ The shift may be applied forwards or backwards
- ◆ Testing of the program can only occur after the new datum realization is working within OPUS.



The CORS Position Delaunay Triangle Network





The Program User Interface

The screenshot displays the 'NAD83CORS conversion - [Data Viewer]' application. The interface is divided into several sections:

- Input Parameters:** Shows the input point file as 'C:/programs/n83cors-build-desktop/mytestdata - Copy.csv' and the mode as '1 = NAD83CORS96 -> NAD83CORS96a'. A 'Convert!' button is visible.
- Output Information:** Lists conversion data for various points (P386 to P018) with their coordinates and completion time (328 ms).
- Model Display:** A central map showing a network of CORS points (e.g., P405, P412, P384, P376, P375, P374, P373, P372, P369, P367, P396, P404, P406, P395, P385, P387, P383, P379, P378, P377, P371, P366, P332, P367) and monument locations (mp1 through mp11). A red arrow points to point P373, and a blue arrow points to monument mp2. A text box at the top of the map reads: 'Last Click: X = -123.0011 Y = 43.9489 Z = 1048.79'.
- Display Controls:** Includes a 'Reset Display' button, 'Vector Length Mult' set to 1500, 'Display Optimization' set to 'Culling', and checkboxes for 'Show Ref Data' (Red), 'Label Points', 'Show Proc Data' (Blue), 'Label Points', 'Show Base Map', and 'Draw Triangles' (Black).
- Light Control:** Shows 'Position' controls for X, Y, and Z, all set to 0.00.

Shift between datum realizations shown at each CORS-- (exaggerated distance)



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 - www.TheORGN.net
- ◆ Oregon Coordinate Reference System
 - www.oregon.gov/ODOT/HWY/GEOMETRONICS/ocrs.shtml
- ◆ Design to Dozer:
 - www.oregon.gov/ODOT/HWY/GEOMETRONICS/dozer.shtml



Questions??