



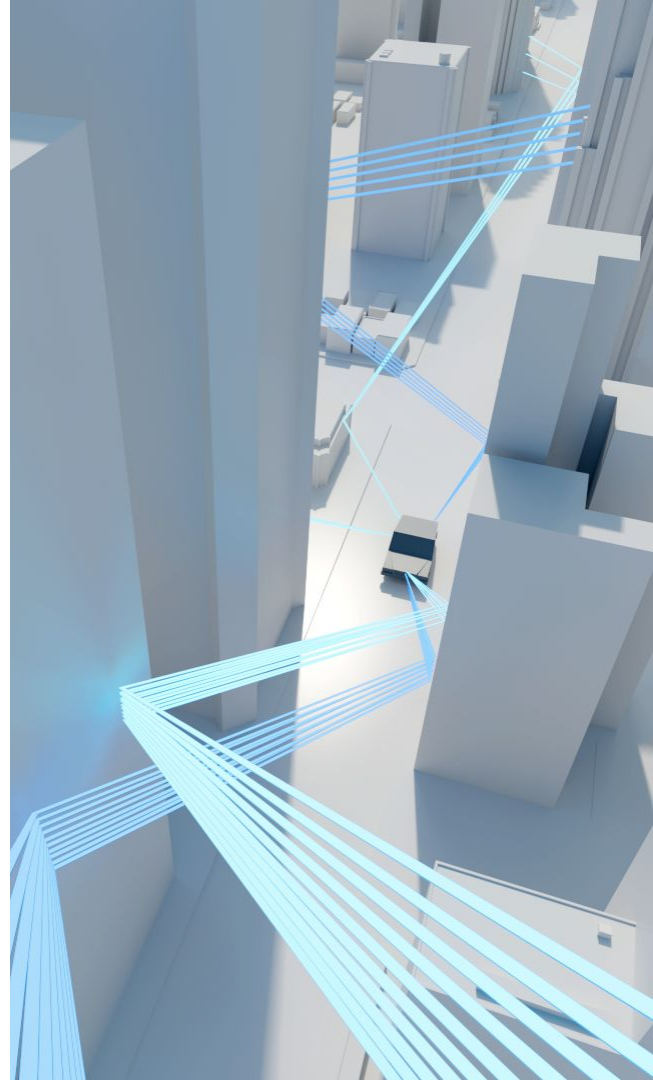
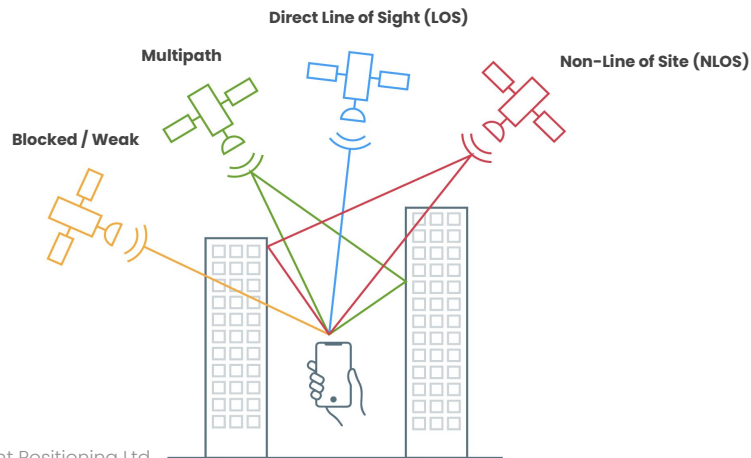
Supercorrelation: A Software Upgrade to Toughen GNSS Receivers

Ramsey Faragher MA MSci PhD CPhys FRIN MION
Founder, President and CTO



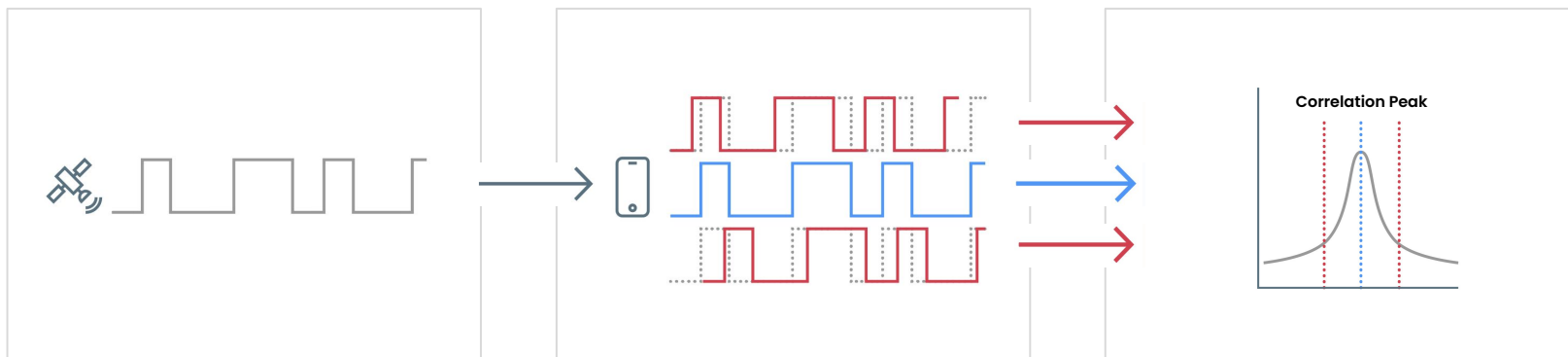
There is a big, structural problem with GNSS in cities.

- GNSS performs poorly in cities because signals are blocked or reflected from buildings
- The reflected signals dominate or interfere with the true line-of-sight (LOS) signals
- Receivers cannot rely on power level to distinguish between LOS and NLOS (e.g. weak LOS penetrating a canopy, versus lossless reflections from metal)





Correlation is at the core of the problem – and the solution



Step 1

Satellite sends out unique coded signal

Step 2

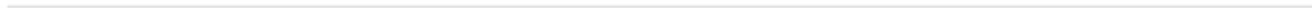
Device matches received signal with internal replicas with varying time delays

Step 3

The correct time delay replica gives the strongest correlation, allowing the device to estimate the distance to each satellite, and thus the device's position



What the satellite sends



What the receiver looks for



What the receiver actually receives





Real received signal



Supercorrelator replica



Reflected signal





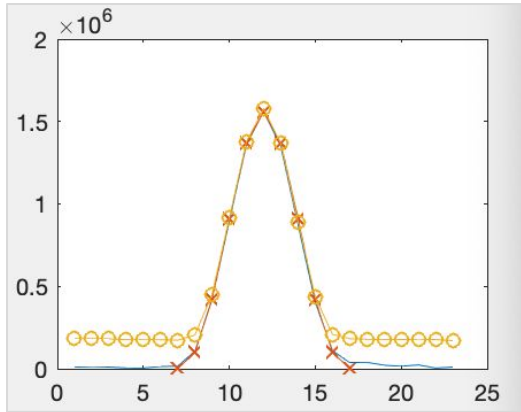
Real received signal



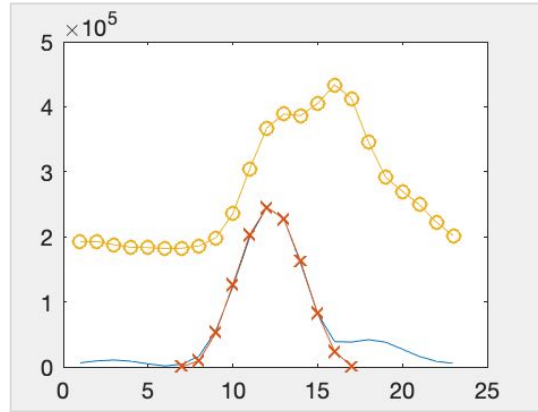
Supercorrelator replica



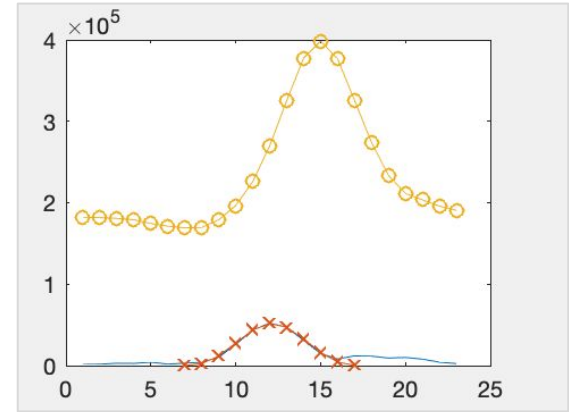
Actual correlation peaks - GPS L1



Clean signal



Multipath interference



Non-line-of-sight signal overpowering the LOS (e.g spoofing)

Yellow = incoherent integration

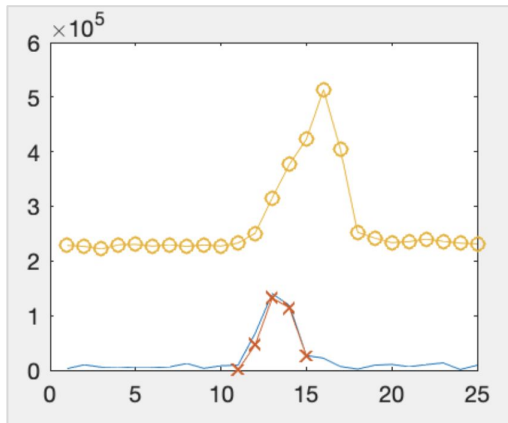
Blue = supercorrelation

Red = a clean (multipath-free) template correlation peak

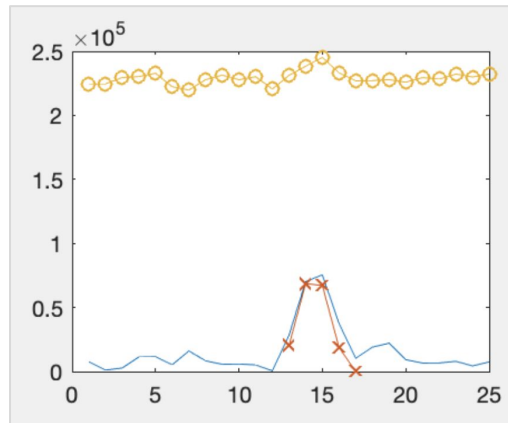


Actual correlation peaks - GPS L5

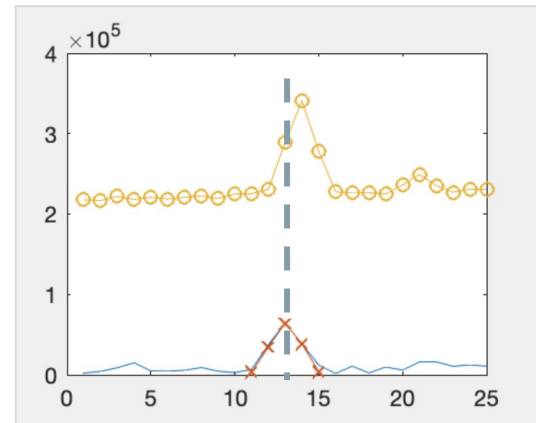
L5 coherence length is 10x shorter than L1, but the correlation peaks can still be distorted and displaced



Multipath interference



Sensitivity boost
(helps with the L5 antenna
problem)



NLOS overpowering the LOS

Yellow = incoherent integration

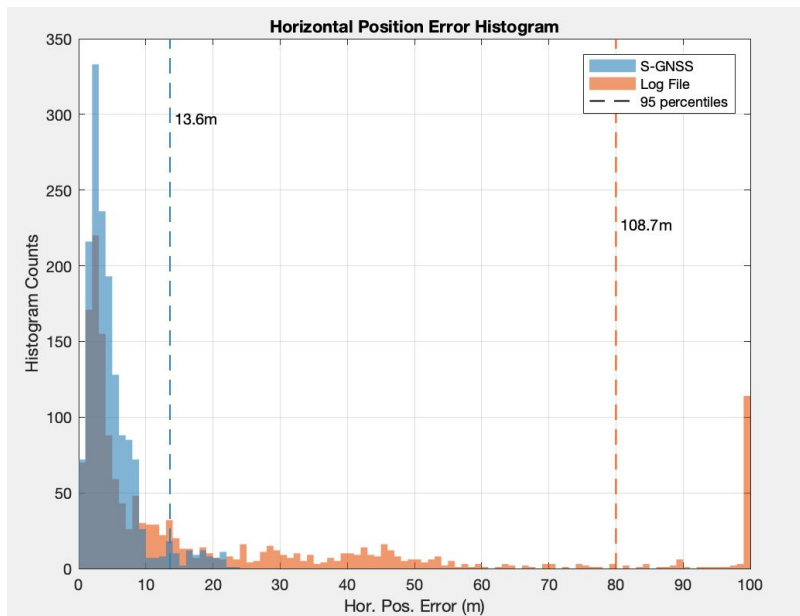
Blue = supercorrelation

Red = a clean (multipath-free) template correlation peak

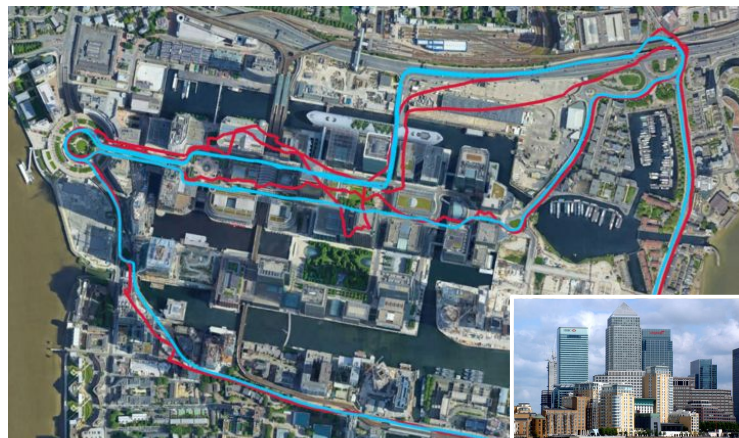




Trials in Canary Wharf, London, UK using GPS L1



Canary Wharf, London undocked drive test with and without Supercorrelation



Supercorrelation vs standard GPS chipset

- Smartphone GPS chipset
- FocalPoint S-GNSS (GPS L1 only)



Driving test in Canary Wharf, London with undocked smartphone (not using strapdown inertials)

Typical improvements



Sensitivity boost of 5-10 dB depending on settings chosen



Accuracy improvements of 2x to 12x across pseudoranges and Doppler depending on environment



Integrity improvements of 3x to 10x depending on environment



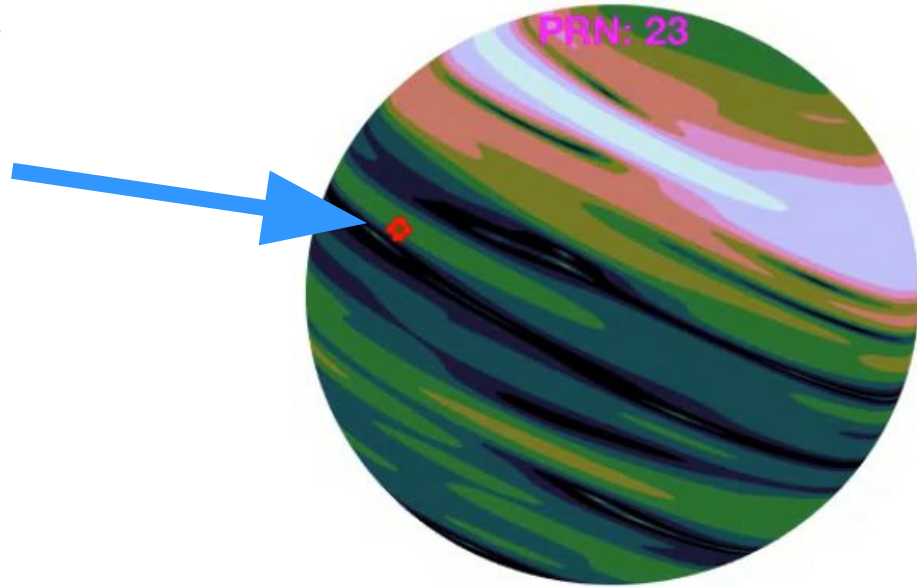
BOM savings on XO, antenna, L5 requirements, silicon area, power consumption, etc

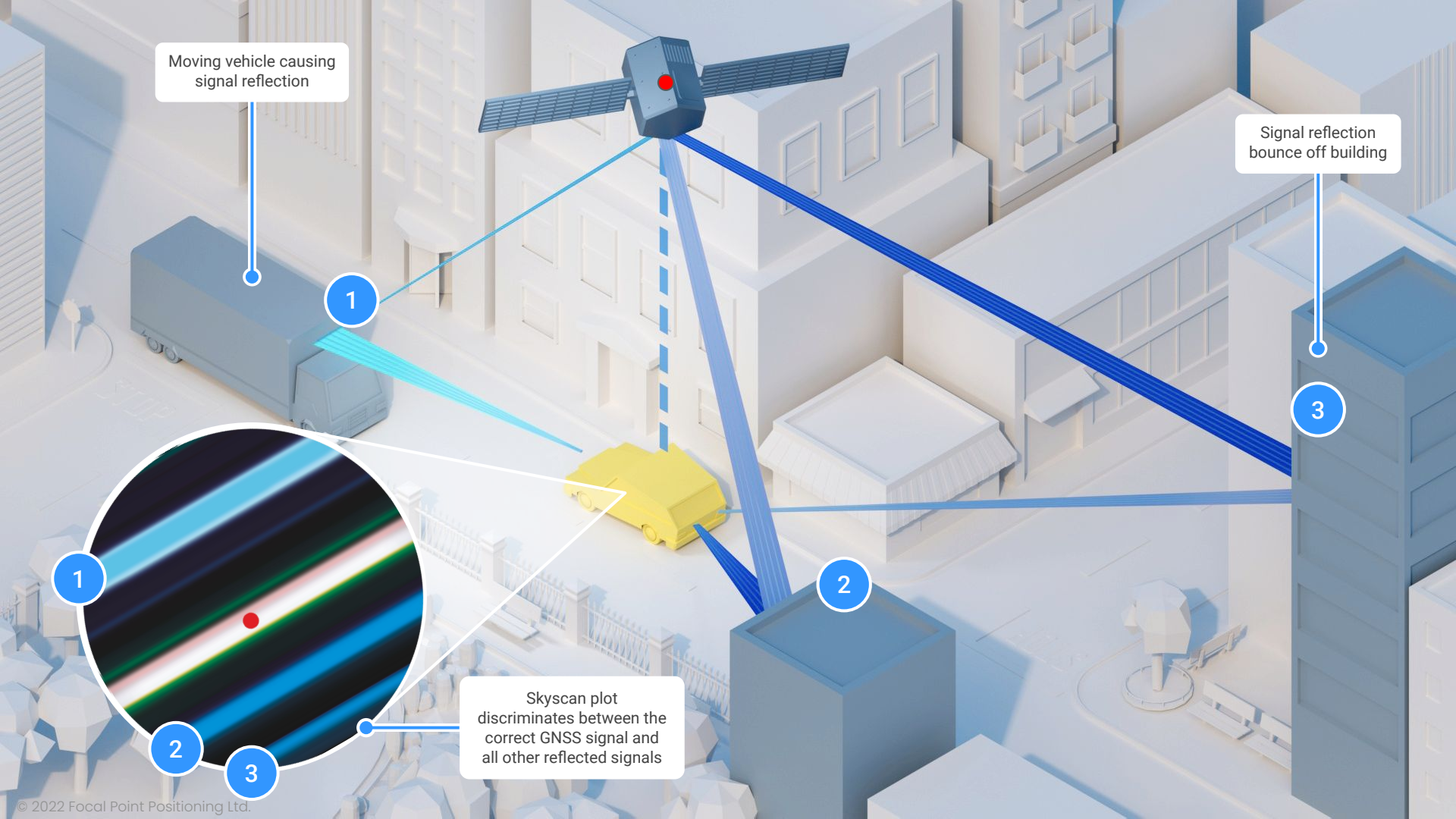
Anatomy of a Skyscan

A skyscan plot is a representation of the incoming power from a given satellite for all azimuth and elevations

The red mark is the true satellite location in the sky

The colours show the power detected from each arrival angle





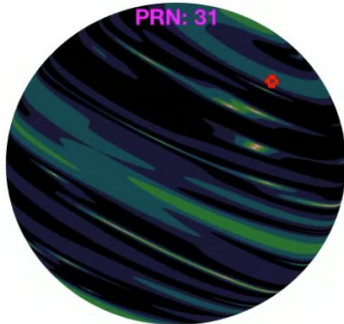
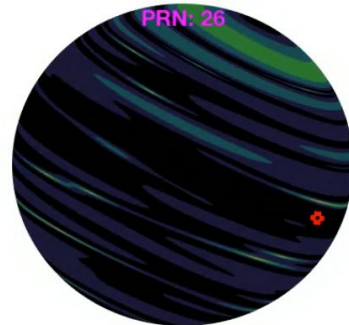
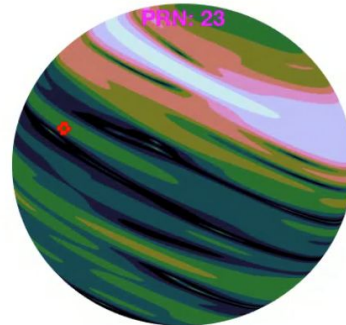
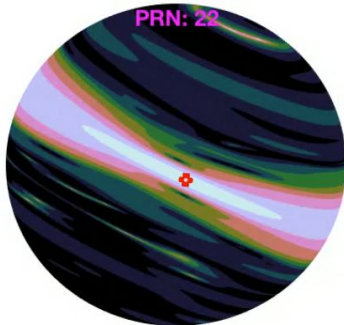
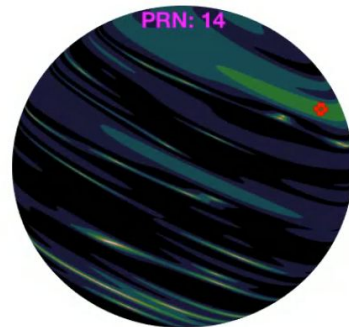
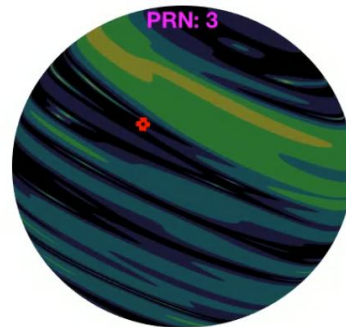
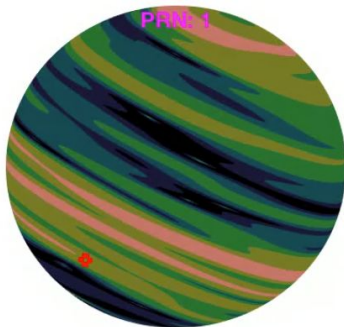
Moving vehicle causing signal reflection

Signal reflection bounce off building

Skyscan plot discriminates between the correct GNSS signal and all other reflected signals

Skyscan

Reveals signals that match the satellite broadcast but are coming from the wrong directions to be the line-of-sight component



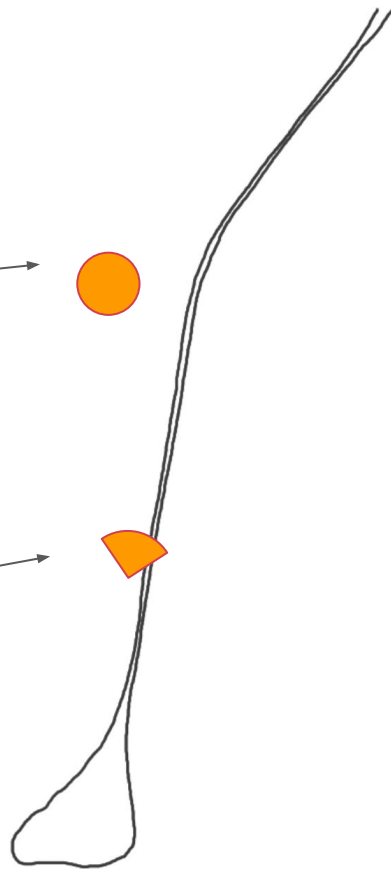
Real-world test

Undisclosed location

Spoofed location



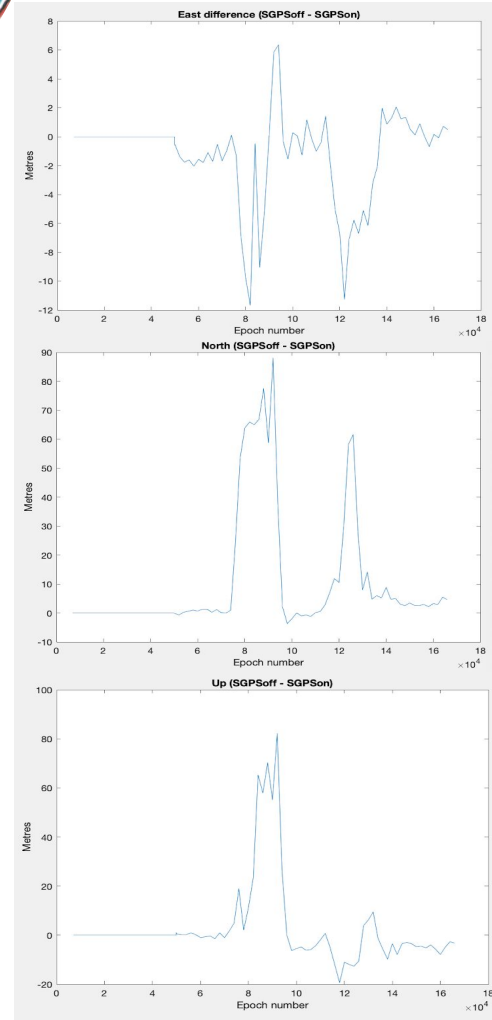
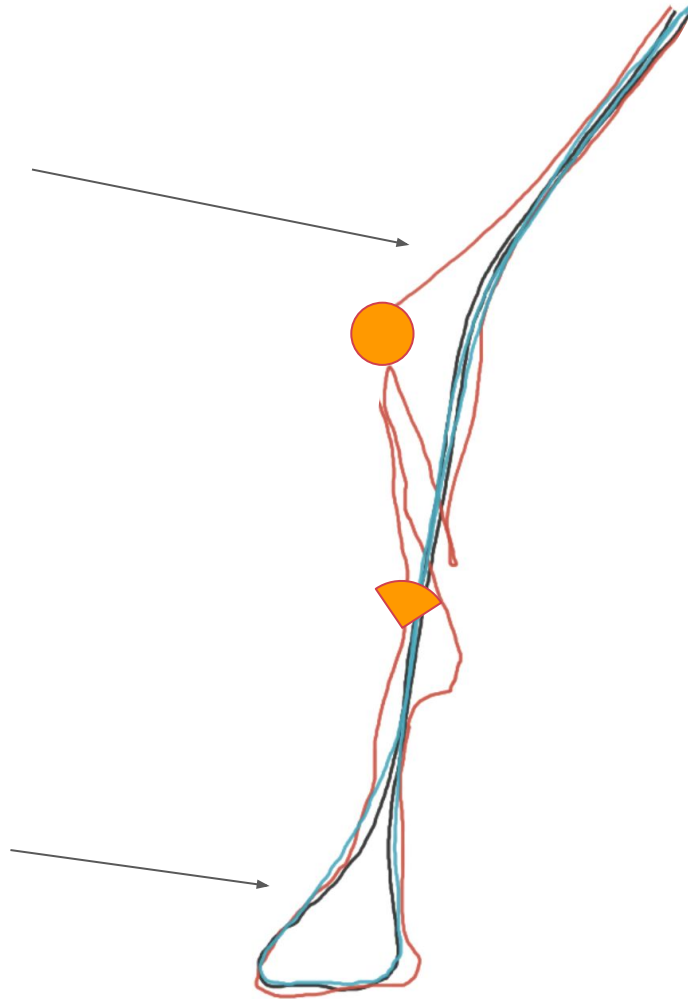
Spoofing location and beam direction

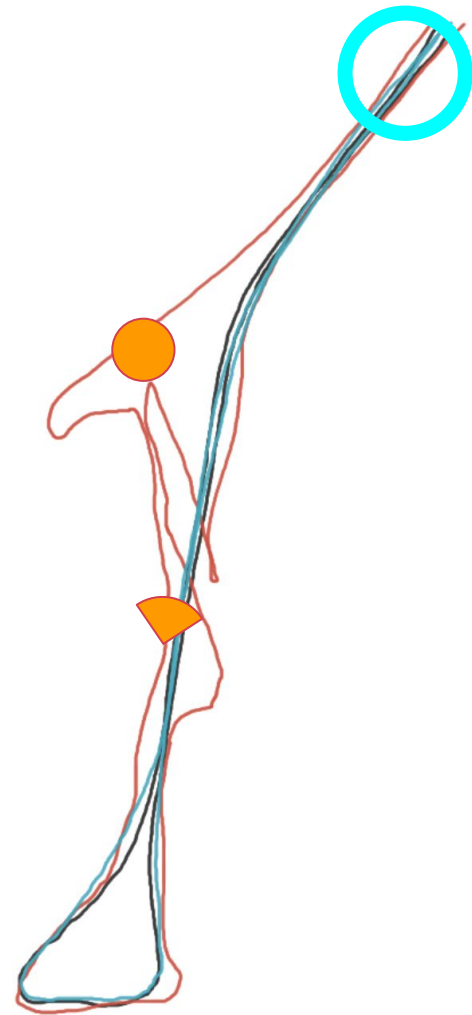
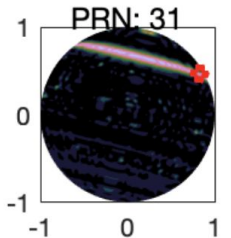
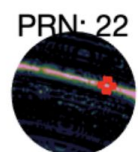
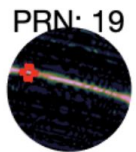
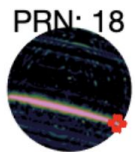
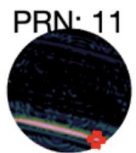
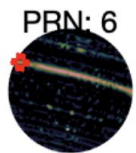
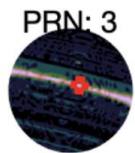
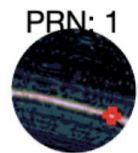


~200m

Red line = standard
GNSS positioning

Blue line = Supercorrelation
position fixes





PRN: 1



PRN: 3



PRN: 6



PRN: 9



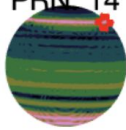
PRN: 11



PRN: 12



PRN: 14



PRN: 17



PRN: 18



PRN: 19



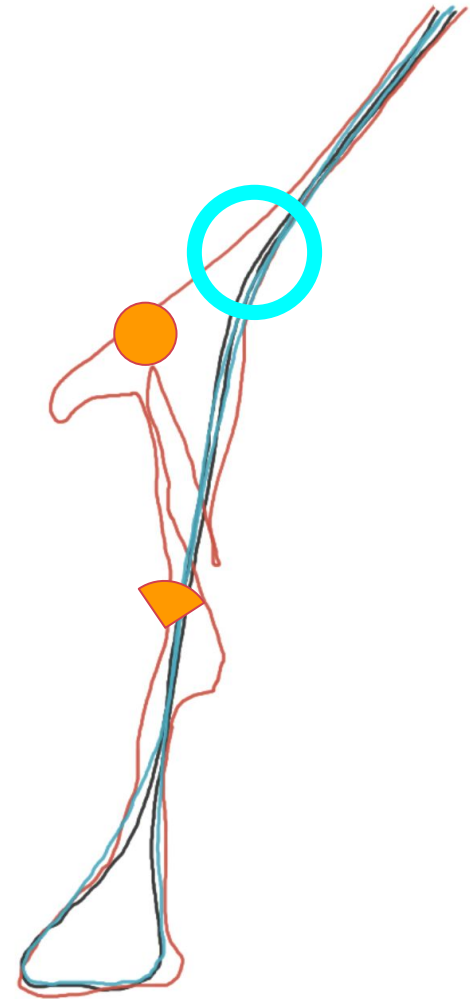
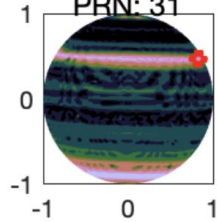
PRN: 22

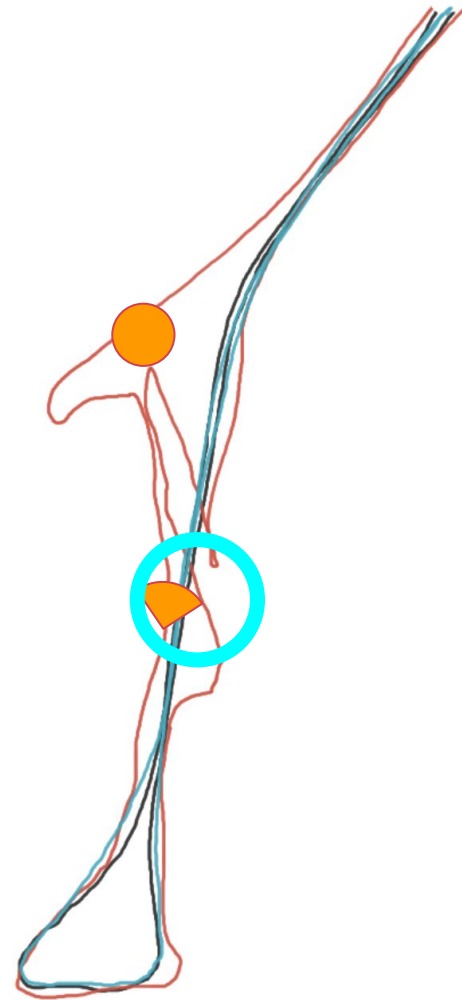
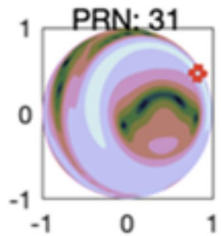
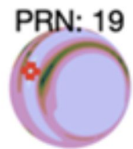
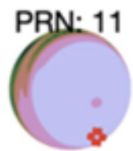
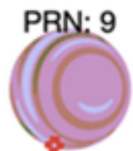
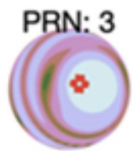


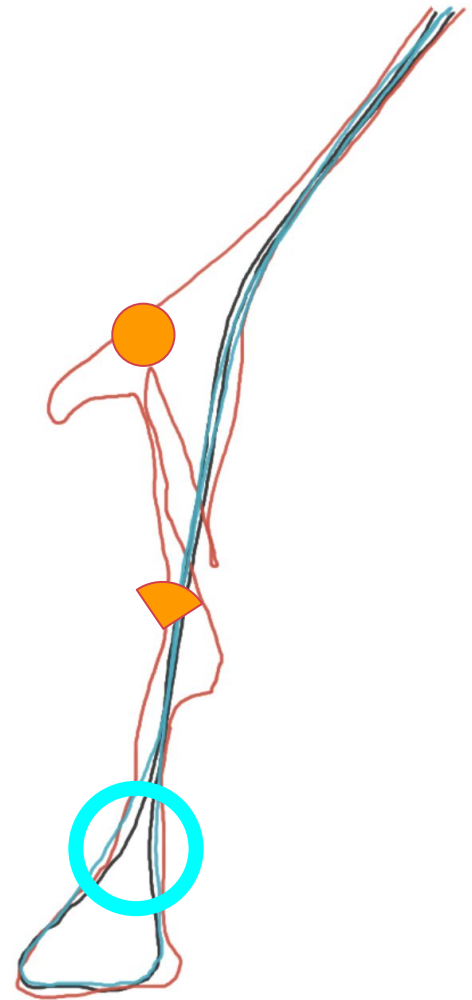
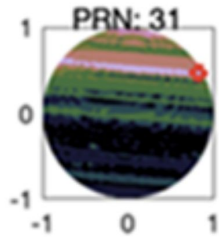
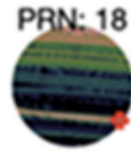
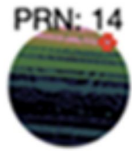
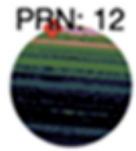
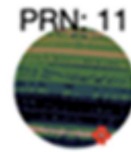
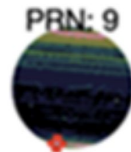
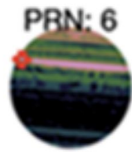
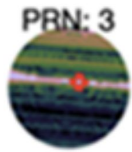
PRN: 23



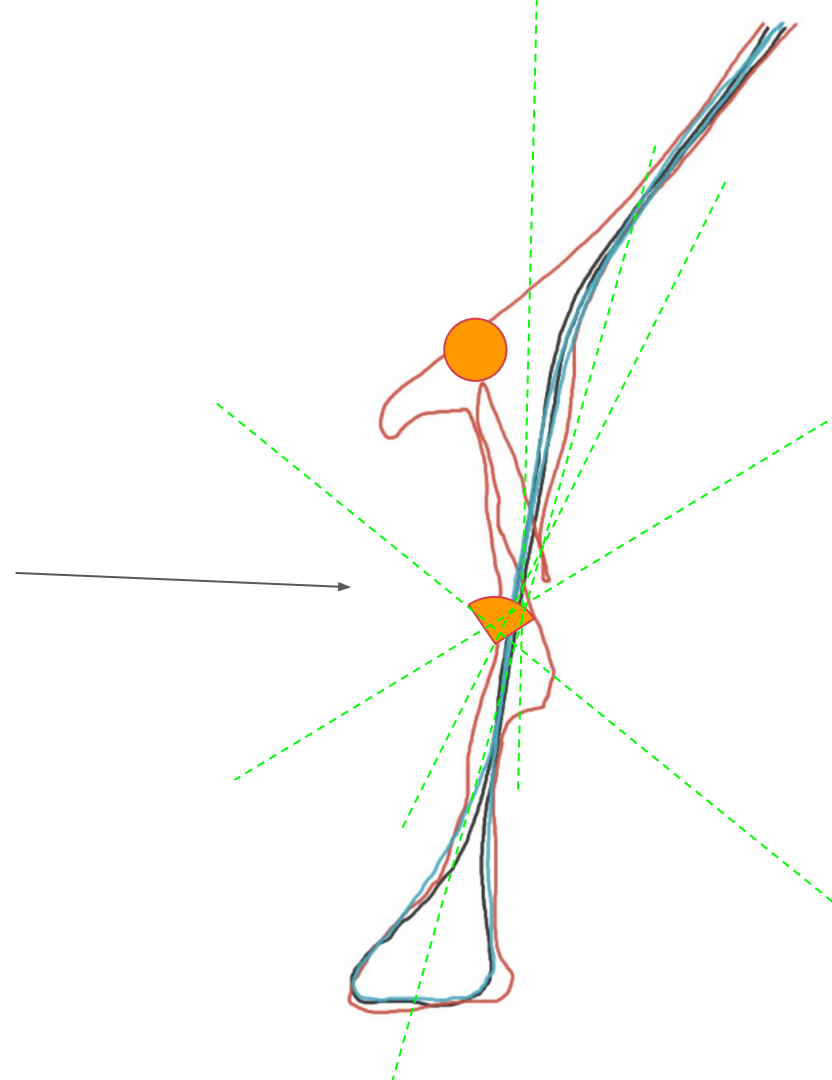
PRN: 31







Monitoring azimuths over time
as the receiver moves allows
the spoofer location to be
determined



Summary

Supercorrelation is motion-compensated, very long (>1 second) coherent integration

Supercorrelation provides angular dependant sensitivity boosts/nulls similar to a CRPA but entirely in software

We focus on smartphone and smartwatch grade devices

Supercorrelation can provide all GNSS receivers with greater resilience against jamming and spoofing attacks without any changes to the hardware

The angle of arrival sensing not only allows spoofers to be ignored, but it allows them to be located too



Founder, President and CTO
Dr Ramsey Faragher

Anti-spoofing capabilities - interference injected in playback (offline attack)

Driving
experiment
in car park

Simulated
meaconing
rebroadcaster
here

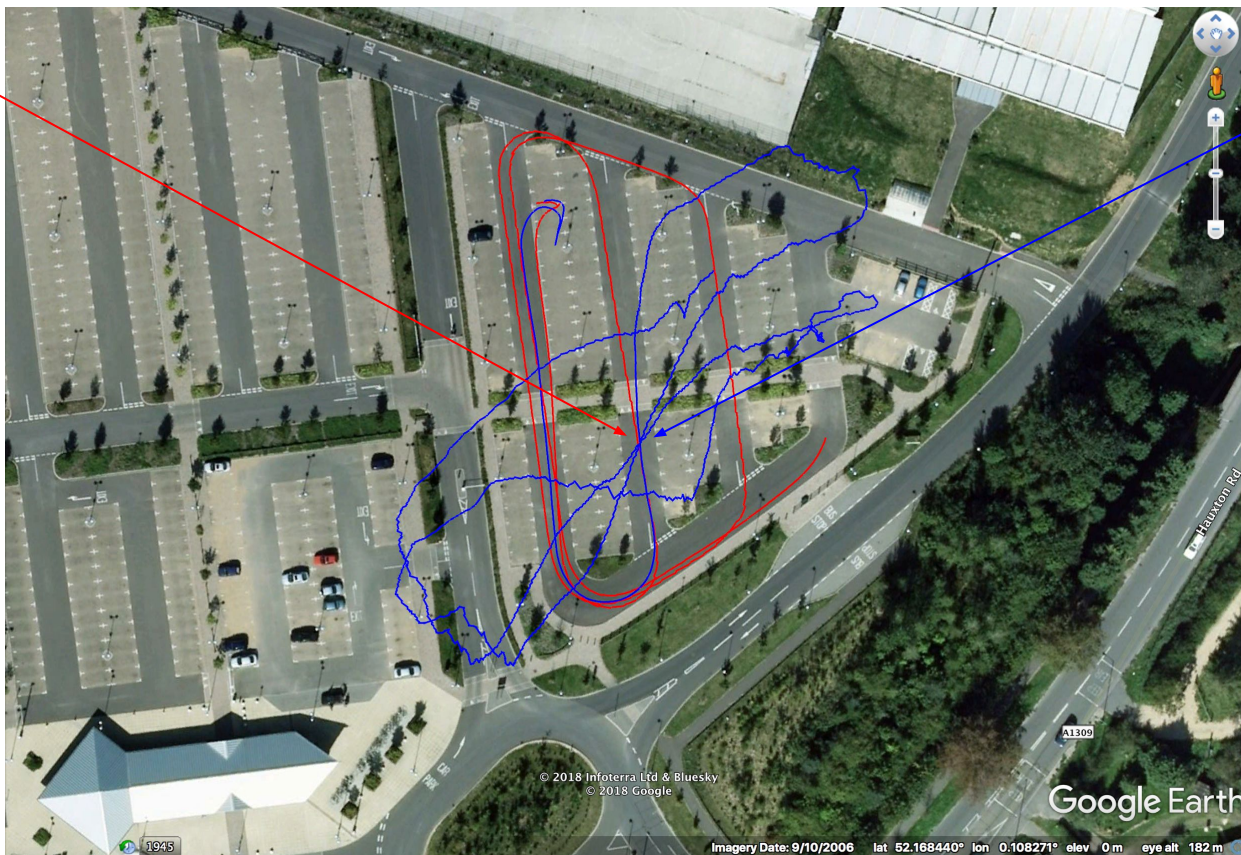


Anti-spoofing capabilities - interference injected in playback (offline attack)

Red line:

S-GPS

Resilient
against
the
meaconer



Blue line:

Standard
tracker

Disrupted
by the
meaconing
attack



Anti-spoofing capabilities - interference injected in playback (offline attack)

